

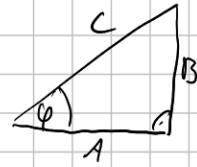
A1) a)

$$\begin{aligned}
 & 4[\cos(x)\cos(y) + \sin(y)\sin(x)] \\
 &= (e^{ix} + e^{-ix})(e^{iy} + e^{-iy}) - (e^{ix} - e^{-ix})(e^{iy} - e^{-iy}) \\
 &= e^{i(x+y)} + e^{i(x-y)} + e^{-i(x+y)} + e^{-i(x-y)} - e^{i(x+y)} + e^{i(x-y)} - e^{-i(x+y)} - e^{-i(x-y)} \\
 &= 2 e^{i(x-y)} + 2 e^{-i(x-y)} = 4 \cos(x-y)
 \end{aligned}$$

b)  $\mathbb{H}_i$  (ts beweis)

$$\begin{aligned}
 & 4i(\sin(x)\cos(y) + \sin(y)\cos(x)) \\
 &= ((e^{ix} - e^{-ix})(e^{iy} + e^{-iy}) + (e^{iy} - e^{-iy})(e^{ix} + e^{-ix})) \\
 &= (e^{i(x+y)} + e^{i(x-y)} - e^{-i(x+y)} - e^{-i(x-y)} + e^{i(x+y)} + e^{-i(x+y)} - e^{-i(x+y)} - e^{-i(x-y)}) \\
 &= 2(e^{i(x+y)} - e^{-i(x+y)}) = 4i \sin(x+y)
 \end{aligned}$$

Viel leichter kurz  
was dazu  
sagen als  
Begründung



$$\begin{aligned}
 C \cdot \sin(x+\varphi) &= C \cdot (\sin(x)\cos(\varphi) + \cos(x)\sin(\varphi)) \\
 &= C \cdot \left( \sin(x) \frac{B}{C} + \cos(x) \frac{A}{C} \right) \\
 &= B \sin(x) + A \cos(x)
 \end{aligned}$$

c)  $\sin(x-y) + \sin(x+y)$  | Beweis siehe A1 b)

$$\begin{aligned}
 &= \sin(x)\cos(-y) + \sin(-y)\cos(x) + \sin(x)\cos(y) + \sin(y)\cos(x) \\
 &= \sin(x)\cos(y) - \sin(y)\cos(x) + \sin(x)\cos(y) + \sin(y)\cos(x) \\
 &= 2 \sin(x)\cos(y)
 \end{aligned}$$

A2)  $\frac{F_g}{m} = -g \frac{x}{R} = \ddot{x}$

$x_0 = 0 \frac{m}{s}$

$x_0 = R$

$$\Rightarrow x(t) = A \cos\left(-\sqrt{\frac{g}{R}} t\right)$$

$$\Rightarrow x_0 = A \cos(0) = R \Rightarrow A = R$$

$$x(t) = R \cos\left(-\sqrt{\frac{g}{R}} t\right) \stackrel{!}{=} -R$$

$$\Rightarrow -1 = \cos\left(-\sqrt{\frac{g}{R}} t_{\text{end}}\right)$$

$$\cos(-1) = \pi = -\sqrt{\frac{g}{R}} t_{\text{end}} \mid : -\sqrt{\frac{g}{R}}$$

$$\Rightarrow \pi \sqrt{\frac{R}{g}} = t_{\text{end}} \approx 2537,5 \text{ s}$$

$$v(t) = \sqrt{gR} \sin\left(-\sqrt{\frac{g}{R}} t\right) \quad v\left(\frac{t_{\text{end}}}{2}\right) = -\sqrt{gR} \sin\left(\frac{\pi}{2}\right) = -\sqrt{\frac{g}{R}} \approx -7923,6 \frac{\text{m}}{\text{s}}$$

AB) Es gibt zwei Anfangsbedingungen  $x_0$  und  $v_0$ .

Ein Ansatz mit nur einem freien Parameter wäre überbestimmt.

$$\ddot{x} - 2\alpha \dot{x} + \omega_0^2 x = 0 \quad \text{mit } x = A e^{\alpha t}$$

$$A e^{\alpha t} + 2\dot{A} e^{\alpha t} + A \alpha^2 e^{\alpha t} - 2\alpha \dot{A} e^{\alpha t} - 2\alpha^2 A e^{\alpha t} + \omega_0^2 t e^{\alpha t} = 0 \quad | : e^{\alpha t}$$

$$A + 2\dot{A}\alpha + A\alpha^2 - 2\alpha \dot{A} - 2\alpha^2 A + \omega_0^2 A = 0$$

$$\dot{A} + \underbrace{A(2\alpha - 2\alpha)}_{=0} + \underbrace{A(\alpha^2 - 2\alpha^2 + \omega_0^2)}_{=0} = 0 \quad | \text{ da } \omega_0^2 = \alpha^2$$

$$\dot{A} = 0$$

$$x = (\beta + ct) e^{\alpha t}$$

$$\dot{x} = \alpha(\beta + ct)e^{\alpha t} + ce^{\alpha t}$$

$$x(0) = \beta = x_0$$

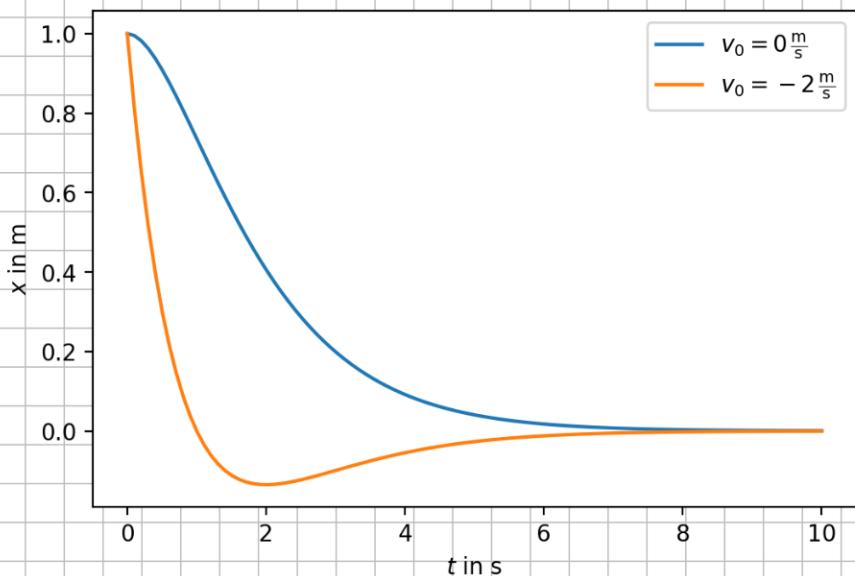
$$\dot{x}(0) = \alpha x_0 + C = v_0$$

$$\Rightarrow C = v_0 - \alpha x_0$$

$$\Rightarrow x(t) = (x_0 + (v_0 - \alpha x_0)t) e^{\alpha t}$$

mit  $\alpha = -\omega_0$  ergibt sich

$$\Rightarrow x(t) = (x_0 + (v_0 + \omega_0 x_0)t) e^{-\omega_0 t}$$



A4)

$$D = 5 \cdot 10^4 \frac{N}{m} \quad N = 800 \text{ kg}$$

$\Rightarrow$  Vereinfachung mit 1. Feder und  $m = 200 \text{ kg}$  ✓

$$\frac{D}{m} = \omega_0^2 \doteq \mu^2 = \frac{\mu^2}{4m^2}$$

$$2\sqrt{Dm} = \mu_s = 2\sqrt{5 \cdot 10^4 \frac{N}{m} \cdot 200 \text{ kg}} \approx 6324,55 \frac{\text{kg}}{\text{s}}$$

## Ex\_7

December 10, 2022

```
[11]: import numpy as np
import matplotlib.pyplot as plt
from numpy import e
import matplotlib as mpl
mpl.rcParams['figure.dpi'] = 200

w = 1
v0s = [0, -2]
x0 = 1
t = np.linspace(0,10,100)

for v0 in v0s:
    x = (x0 + (v0+w*x0)*t )*e**(-w*t)
    plt.plot(t,x, label=f"$v_0 = {v0}$")
plt.legend()
plt.ylabel("$x$ in m")
plt.xlabel("$t$ in s")
```

