

Aufgabe 1) $\left(\frac{4}{5}\right)$
 $\frac{r}{\pi r^2} = \rho \rightarrow \Theta = \int r^2 dV \rho$

$$a) \left(\frac{m}{\pi r^2}\right) = \frac{m}{\pi r^2} \int_0^r \int_0^{2\pi} r^2 d\varphi dr = \frac{m}{\pi r^2} \int_0^r 2\pi r^3 dr = \frac{m}{\pi r^2} \frac{2}{4} \pi r^4 = \frac{1}{2} m r^2 = \Theta$$

Drehimpuls(erhaltung):

$$\frac{1}{2} \omega_1 m r^2 = \omega_g \cdot \left(\frac{1}{2} m r^2 + \frac{1}{2} m \left(\frac{r}{2} \right)^2 \right) = \frac{1}{2} \omega_g m \frac{5}{4} r^2$$

$$\Leftrightarrow \omega_g = \frac{4}{5} \omega_1 = 4 \text{ Hz}$$

$$b) E_1 = \frac{1}{2} \Theta_1 \omega_1^2 \quad E_2 = \frac{1}{2} \Theta_g \omega_g^2$$

$$\frac{E_2}{E_1} = \frac{\Theta_g \omega_g^2}{\Theta_1 \omega_1^2} = \frac{\frac{1}{2} m \frac{5}{4} r^2 \frac{16}{25} \omega_1^2}{\frac{1}{2} m r^2 \omega_1^2} = \frac{\frac{5}{4} \cdot \frac{16}{25}}{1} = \frac{4}{5}$$

$\Rightarrow$ Es bleiben 80% der kin. Energie erhalten.

Aufgabe 2 $\left(\frac{5}{5}\right)$

$$a) \Theta = \frac{M}{V} \int_b^R \int_0^{2\pi} r^2 d\varphi dr = \frac{M}{\pi(R^2 - b^2)} \int_b^R 2\pi r^3 dr = \frac{M}{\pi(R^2 - b^2)} \frac{1}{2} \pi (R^4 - b^4)$$

$$= \frac{M}{2} \left(\frac{R^4 - b^4}{R^2 - b^2} \right) = \frac{M}{2} \left(\frac{(R^2 + b^2)(R^2 - b^2)}{(R^2 - b^2)} \right) = \frac{M}{2} (R^2 + b^2)$$

$$b) m \cdot g = \frac{\Theta a}{R} + m \cdot a = \frac{\Theta a}{R^2} + m a = a \left[\frac{M}{2R^2} (R^2 + b^2) + m \right]$$

$$\Rightarrow a = m \cdot g \cdot \left[\frac{M}{2R^2} (R^2 + b^2) + m \right]^{-1} = \frac{1}{2} g = 4,905 \frac{\text{m}}{\text{s}^2}$$

$$F_s = \frac{1}{2} m g = 12,2625$$

Aufgabe 3

4,5/5

$$a) \omega = \frac{v_p - v_s}{r}$$

$$b) \Theta = \frac{2}{3} m r^2$$

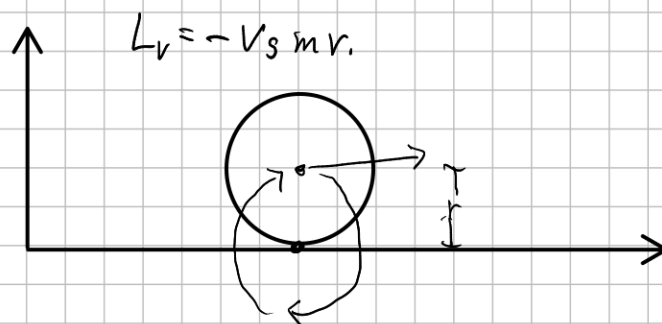
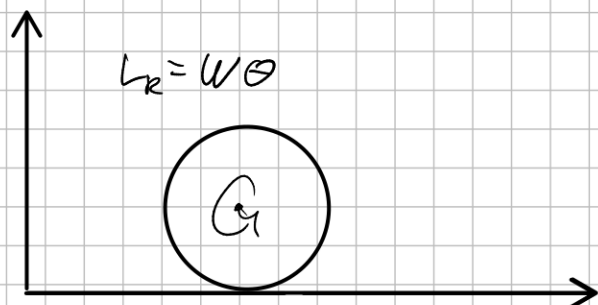
Der Drehimpuls um die Kontaktlinie bei $t=0_s$ ist konstant, da die Kraft, die die Bewegung erzeugt radial zu ihr liegt: senkrecht ✓

$$L = \omega \Theta + (-v_s) m r \stackrel{!}{=} 0 \quad (\text{da vor Beginn } \omega=0 \text{ und } v_s=0)$$

$$= \frac{v_p - v_s}{r} \Theta - 2 v_s \frac{\Theta}{r}$$

$$\Leftrightarrow v_p - v_s = +2 v_s$$

$$\Leftrightarrow v_s = \frac{1}{3} v_p \quad \checkmark$$



```
In[ ]:= m = 2.5;  
      M = 3.2;  
      R = 0.2;  
      b = 0.15;
```

```
In[ ]:= a := m g  $\left( \frac{M}{2 R^2} (R^2 + b^2) + m \right)^{-1}$ 
```

```
In[ ]:= a
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Out[ ]:= 0.5 g
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In[ ]:= a /. g → 9.81
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Out[ ]:= 4.905
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