



**Examination 2010**

# **„Electromagnetics and Numerical Calculation of Fields“**

**March 9, 2010**

**Name:** \_\_\_\_\_

**Student number:** \_\_\_\_\_

### Exercise 1:

a.) Given is the potential  $\phi = \frac{1}{4\pi\epsilon_0} \frac{q}{\sqrt{x^2 + y^2 + z^2}}$

Calculate the electric Field  $\vec{E}$ . ( 3 pt )

b.) Given is the electric flux density  $\vec{D} = \begin{pmatrix} 4(x-y) \\ 3(x+2y) \\ 2z \end{pmatrix}$ .

Calculate the charge density  $\rho$ . ( 3 pt )

### Exercise 2:

(a) What type of equation has to be solved for finding the electric potential  $\phi$  of an arbitrary charge distribution  $\rho(x, y, z)$  ? ( 2 pt )

(b) What are Dirichlet boundary conditions and Neumann boundary conditions? ( 4 pt )

### Exercise 3:

a.) Write down Gauss' law and Stokes' law and show how to translate the Maxwell's equations from differential form to integral form. ( 6 pt )

b.) Use the Gauss' law to prove the

first: 
$$\int_S \phi(\nabla\psi) d\vec{a} = \int_V (\phi\Delta\psi) + (\nabla\phi)(\nabla\psi) dv$$

and second Green's identity: 
$$\int_S \psi\nabla\phi - \phi\nabla\psi d\vec{a} = \int_V \psi\Delta\phi - \phi\Delta\psi dv . ( 6 pt )$$

Hint:  $\nabla(\phi\nabla\psi) = \phi\Delta\psi + (\nabla\phi)(\nabla\psi)$

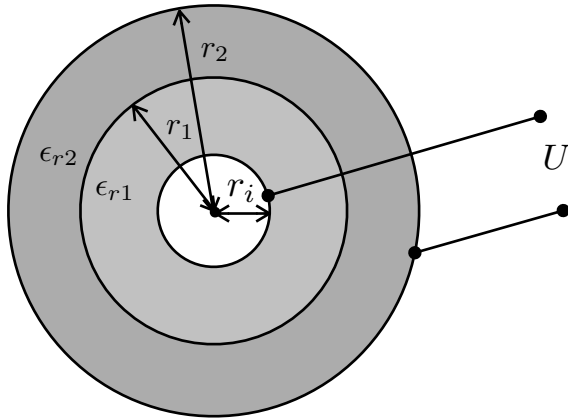
### Exercise 4:

Derive the wave equation for  $\vec{E}$  and  $\vec{H}$  directly from the Maxwell's equations for vacuum ( $\rho = 0$ ,  $\vec{j} = 0$ ). ( 6 pt )

Hint:  $\text{rot rot } \vec{F} = \text{grad div } \vec{F} - \Delta\vec{F}$

### Exercise 5:

Find the capacitance of a spherical capacitor (inner radius  $r_i$ , the outer radii  $r_1$ ,  $r_2$  and the relative dielectric constants  $\epsilon_{r1}$ ,  $\epsilon_{r2}$ ). ( 8 pt )



### Exercise 6:

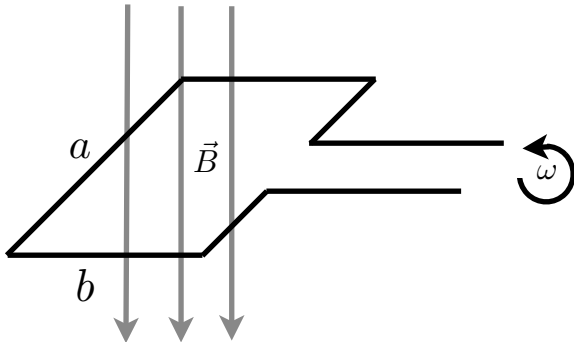
- a.) Write down the sinusoidal plane-wave solutions of the electromagnetic wave equation for  $\vec{E}$  and  $\vec{H}$  (two types of solutions). ( 4 pt )
- b.) How can you find  $E_0$  if  $H_0$  is given ? (2 pt)

### Exercise 7:

- a.) What is the definition of the magnetic flux  $\phi_{mag}$  and how can it be found directly from the magnetic vector potential (use Stokes' law !) ( 4 pt )
- b.) Assume a thin wire of arbitrary shape is given together with the current  $I$  in the wire. How can you find the magnetic vector potential ? ( 4 pt )

### Exercise 8:

A rectangular coil of length  $a$  and width  $b$  is turning with constant angular velocity  $\omega$  inside a homogenous field of magnetic induction  $\vec{B}$  (see figure) . How large is the induced voltage?  
What is the time course of the voltage? ( 4 pt )



### Exercise 9:

a.) Write down the central difference approximation used in the Finite Difference Method (FDM) for:

$$\frac{\partial \Phi}{\partial x} \quad \text{and} \quad \frac{\partial^2 \Phi}{\partial x^2}. \quad (4 \text{ pt})$$

b.) Give a sketch of the computing molecule for the Laplace/Poisson equation (FDM).

Caption the axes.

Mark the values that are used to calculate the next value.

What does the computing molecule deliver ?

What do you do at the boundaries ? (8 pt)

## Exercise 10:

a.) Describe the basic idea and equations of the Finite Element Method using Weighted Residuals with Poisson's Equation as an example.

What is the Residuum? What was Galerkin's idea? ( 8 pt )

b). Describe how a scalar function  $\phi$  can be approximated using linear node shape functions.

Give a sketch of the linear shape functions in 1D case. ( 6 pt )

## Examination Result:

Ex 1	Ex 2	Ex 3	Ex 4	Ex 5	Ex 6	Ex 7	Ex 8	Ex 9	Ex 10	SUM
6	6	12	6	8	6	8	4	12	14	82

**GRADE:** \_\_\_\_\_

# Solutions for Examination 2010

## *Electromagnetics and Numerical Calculations of Field*

1a) 
$$\phi = \frac{1}{4\pi\epsilon_0} \frac{q}{\sqrt{x^2 + y^2 + z^2}}$$

$$\vec{E} = -\nabla\phi$$

$$\frac{\partial\phi}{\partial x} = -\frac{1}{4\pi\epsilon_0} \frac{2xq}{2(\sqrt{x^2 + y^2 + z^2})^3}$$

$$\frac{\partial\phi}{\partial y} = -\frac{1}{4\pi\epsilon_0} \frac{2yq}{2(\sqrt{x^2 + y^2 + z^2})^3}$$

$$\frac{\partial\phi}{\partial z} = -\frac{1}{4\pi\epsilon_0} \frac{2zq}{2(\sqrt{x^2 + y^2 + z^2})^3}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{(\sqrt{x^2 + y^2 + z^2})^3} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

1b)

$$\nabla \vec{D} = \partial_x D_x + \partial_y D_y + \partial_z D_z = 4 + 6 + 2 = 12$$

2a) Poisson equation: 
$$\Delta\phi = -\frac{\rho}{\epsilon_0}$$

or Coulomb Integral 
$$\Phi(\vec{r}) = \frac{1}{4\pi\epsilon} \iiint \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} d\mathbf{v}'$$

2b) Neumann: 
$$\frac{\partial\phi}{\partial n}|_{\text{boundary}} = \hat{\phi}_n$$

On the boundaries the normal derivative of the potential is given.

Dirichlet: 
$$\phi|_{\text{boundary}} = \hat{\phi}$$

On the boundaries the potential is given.

3a)

$$\text{Gauss: } \int_V \text{div} \vec{A} dv = \int_S \vec{A} d\vec{a}$$

$$\text{Stokes: } \int_S \text{rot} \vec{A} d\vec{a} = \int_s \vec{A} d\vec{s}$$

Maxwell:

$$\text{div} \vec{D} = \rho \rightarrow \int \text{div} \vec{D} dv = \int \vec{D} d\vec{a} = \int \rho dv$$

$$\text{div} \vec{B} = 0 \rightarrow \int \text{div} \vec{B} dv = \int \vec{B} d\vec{a} = 0$$

$$\text{rot} \vec{E} = -\frac{\partial}{\partial t} \vec{B} \rightarrow \int \text{rot} \vec{E} d\vec{a} = \int \vec{E} d\vec{s} = -\frac{\partial}{\partial t} \int \vec{B} d\vec{a}$$

$$\text{rot} \vec{H} = \vec{J} + \frac{\partial}{\partial t} \vec{D} \rightarrow \int \text{rot} \vec{H} d\vec{a} = \int \vec{H} d\vec{s} = \int (\vec{J} + \frac{\partial}{\partial t} \vec{D}) d\vec{a}$$

3b)

First Green's Identity

$$\int_V (\phi \Delta \psi + (\nabla \phi)(\nabla \psi)) dv = \int_V \nabla(\phi \nabla \psi) dv = \int_S \phi \nabla \psi d\vec{a}$$

Second Green's Identity

$$\begin{aligned} \int_S \psi \nabla \phi - \phi \nabla \psi d\vec{a} &= \int_V \nabla(\psi \nabla \phi - \phi \nabla \psi) dv \\ &= \int_V \psi \Delta \phi + (\nabla \psi)(\nabla \phi) - \phi \Delta \psi - (\nabla \phi)(\nabla \psi) dv \\ &= \int_V \psi \Delta \phi - \phi \Delta \psi dv \end{aligned}$$

4)

$$\begin{aligned}
 \text{rot} \vec{E} &= -\mu \frac{\partial}{\partial t} \vec{H} & \text{rot} \vec{H} &= \epsilon \frac{\partial}{\partial t} \vec{E} \\
 \text{rot rot} \vec{E} &= -\mu \text{rot} \frac{\partial}{\partial t} \vec{H} & \text{rot rot} \vec{H} &= \epsilon \text{rot} \frac{\partial}{\partial t} \vec{E} \\
 \text{grad div} \vec{E} - \Delta \vec{E} &= -\mu \frac{\partial}{\partial t} \text{rot} \vec{H} & \text{grad div} \vec{H} - \Delta \vec{H} &= \epsilon \frac{\partial}{\partial t} \text{rot} \vec{E} \\
 \text{since } \text{div} \vec{E} &= 0 & \text{since } \text{div} \vec{H} &= 0 \\
 \rightarrow \Delta \vec{E} - \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} &= 0 & \rightarrow \Delta \vec{H} - \epsilon \mu \frac{\partial^2 \vec{H}}{\partial t^2} &= 0
 \end{aligned}$$

5)

The spherical capacitor can be treated as two partial spherical capacitors in series.

$$\frac{1}{C_{total}} = \frac{1}{C_1} + \frac{1}{C_2}$$

$$U_1 = \int_{r_i}^{r_1} E dr = \int_{r_i}^{r_1} \frac{Q}{4\pi \epsilon_{r1} \epsilon_0} \frac{1}{r^2} dr = \frac{Q}{4\pi \epsilon_{r1} \epsilon_0} \left( \frac{1}{r_i} - \frac{1}{r_1} \right)$$

$$C_1 = \frac{4\pi \epsilon_{r1} \epsilon_0}{\frac{1}{r_i} - \frac{1}{r_1}}$$

$$U_2 = \int_{r_1}^{r_2} E dr = \int_{r_1}^{r_2} \frac{Q}{4\pi \epsilon_{r2} \epsilon_0} \frac{1}{r^2} dr = \frac{Q}{4\pi \epsilon_{r2} \epsilon_0} \left( \frac{1}{r_1} - \frac{1}{r_2} \right)$$

$$C_2 = \frac{4\pi \epsilon_{r2} \epsilon_0}{\frac{1}{r_1} - \frac{1}{r_2}}$$

$$C_{total} = \frac{4\pi \epsilon_0 \epsilon_{r1} \epsilon_{r2}}{\epsilon_{r2} \left( \frac{1}{r_i} - \frac{1}{r_1} \right) + \epsilon_{r1} \left( \frac{1}{r_1} - \frac{1}{r_2} \right)}$$

6)

$$\begin{aligned} E_y &= E_0 e^{j(\omega t - kx)} \\ H_z &= H_0 e^{j(\omega t - kx)} \end{aligned}$$

or

$$\begin{aligned} E_y &= E_0 e^{j(\omega t + kx)} \\ H_z &= -H_0 e^{j(\omega t + kx)} \end{aligned}$$

6b) 
$$E_0 = \Gamma H_0 = \sqrt{\frac{\mu}{\epsilon}} H_0$$

7a)

Magnetic Flux:

$$\begin{aligned} \phi_m &= \int_S \vec{B} d\vec{a} \\ \vec{B} &= \text{rot} \vec{A} \\ \Rightarrow \phi_m &= \int_S \text{rot} \vec{A} d\vec{a} = \int_S \vec{A} d\vec{s} \end{aligned}$$

7b)

Bio-Savart-Law:

$$\vec{A}(r) = \frac{\mu I}{4\pi} \int_S \frac{1}{r - r'} dv'$$

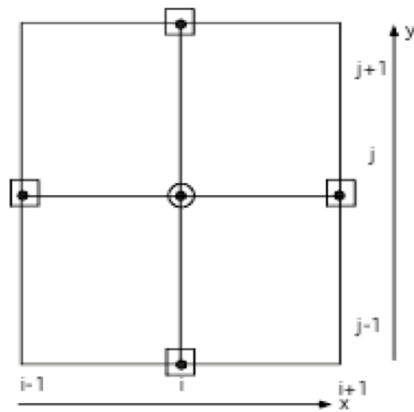
8)

$$U_{ind} = -\frac{d}{dt} \int_S \vec{B} d\vec{a} = -\frac{d}{dt} (Bab \cos(\omega t)) = Bab \omega \sin(\omega t)$$

9a)

$$\left. \frac{\partial \Phi}{\partial x} \right|_{ij} \cong \frac{\Phi(i+1, j) - \Phi(i-1, j)}{2 \Delta x}$$

$$\left. \frac{\partial^2 \Phi}{\partial x^2} \right|_{ij} \cong \frac{\Phi(i+1, j) - 2\Phi(i, j) + \Phi(i-1, j)}{(\Delta x)^2}$$



The computing molecule delivers one linear equation for each node  
 $\Rightarrow$  A linear equation system  $Ax = g$  has to be solved for the whole system. Matrix  $A$  has size  $n \times n$  for  $n$  nodes;

At the boundary, Dirichlet, Neumann or Mixed boundary conditions have to be taken into account

10a)

Poisson's equation:  $\Delta\Phi = -\frac{\rho}{\varepsilon}$

Ideal solution:  $\Delta\Phi + \frac{\rho}{\varepsilon} = 0$

Approximated solution:  $\Delta\tilde{\Phi} + \frac{\rho}{\varepsilon} = R$   $R$  is the Residuum.

Best approximation:  $\int w \cdot R dv = \int \left( \Delta\tilde{\Phi} + \frac{\rho}{\varepsilon} \right) \cdot w dv = 0$

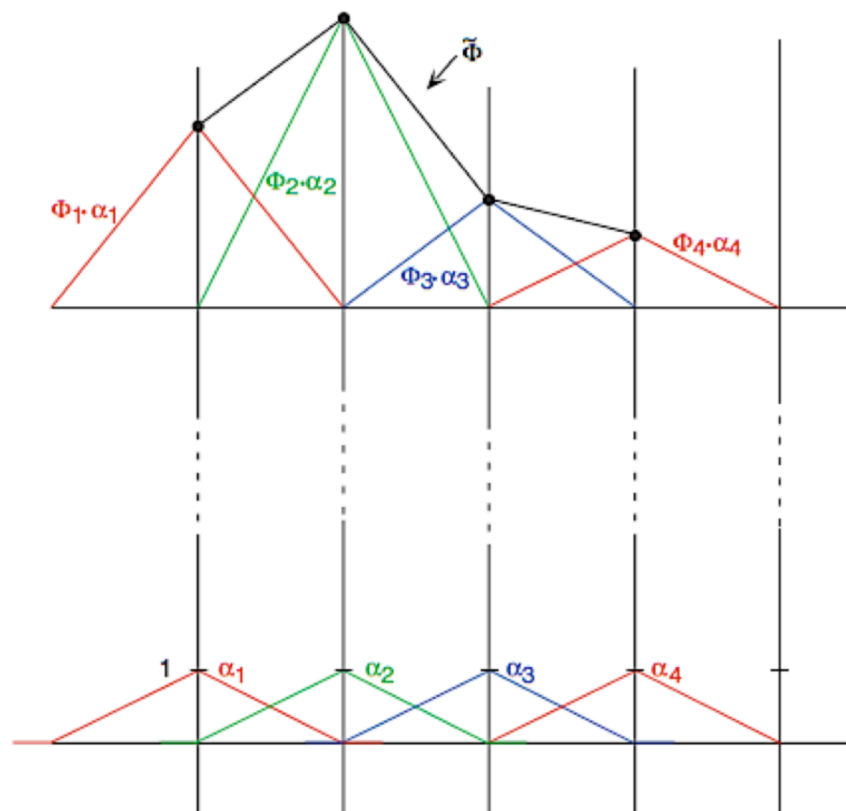
where  $w$  is weighting function.

Using Green's 2<sup>nd</sup> law:

$$\int (\text{grad}\tilde{\Phi}) \cdot (\text{grad}w) dv - \oint w \frac{\partial\tilde{\Phi}}{\partial n} da - \int \frac{\rho}{\varepsilon} w dv = 0$$

In the Galerkin's method, the weighting functions are chosen to be the basis functions ( node shape functions):  $w_i(x,y,z) = \alpha_i(x,y,z)$ .

10b)



$$\tilde{\Phi} = \sum_{k=1}^{nodes} \alpha_k(x,y,z) \cdot \Phi_k, \text{ where } \Phi_k \text{ is a node potential.}$$