

Electronics for Physicists

Analog Electronics

Chapter 4; Lecture 08

Frank Simon

Institute for Data Processing and Electronics

14.12.2023

KIT, Winter 2023/24

Chapter 4

Operational Amplifiers

- OpAmp Basics
- Simple Circuits: Feedback etc.
- OpAmp Circuits I
- Realistic OpAmps
- OpAmp Circuits II

Overview

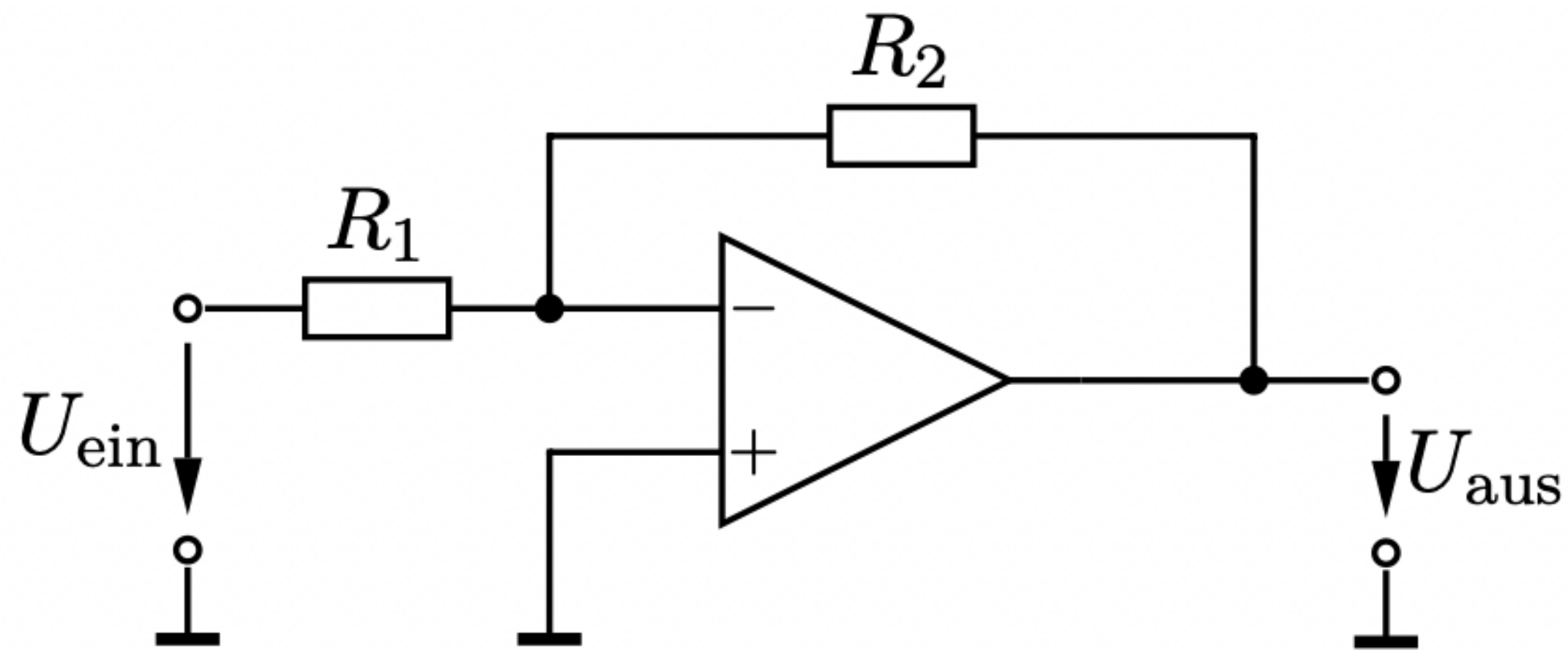
1. Basics
2. Circuits with R, C, L with Alternating Current
3. Diodes
- 4. Operational Amplifiers**
5. Transistors - Basics
6. 2-Transistor Circuits
7. Field Effect Transistors
8. Additional Topics
 - Filters
 - Voltage Regulators
 - Noise

A more general View of Feedback

In: Chapter 4: Operational Amplifiers

Equivalent Circuit

Inverting Amplifier



Input Impedance?

Output Impedance?

Definitions:

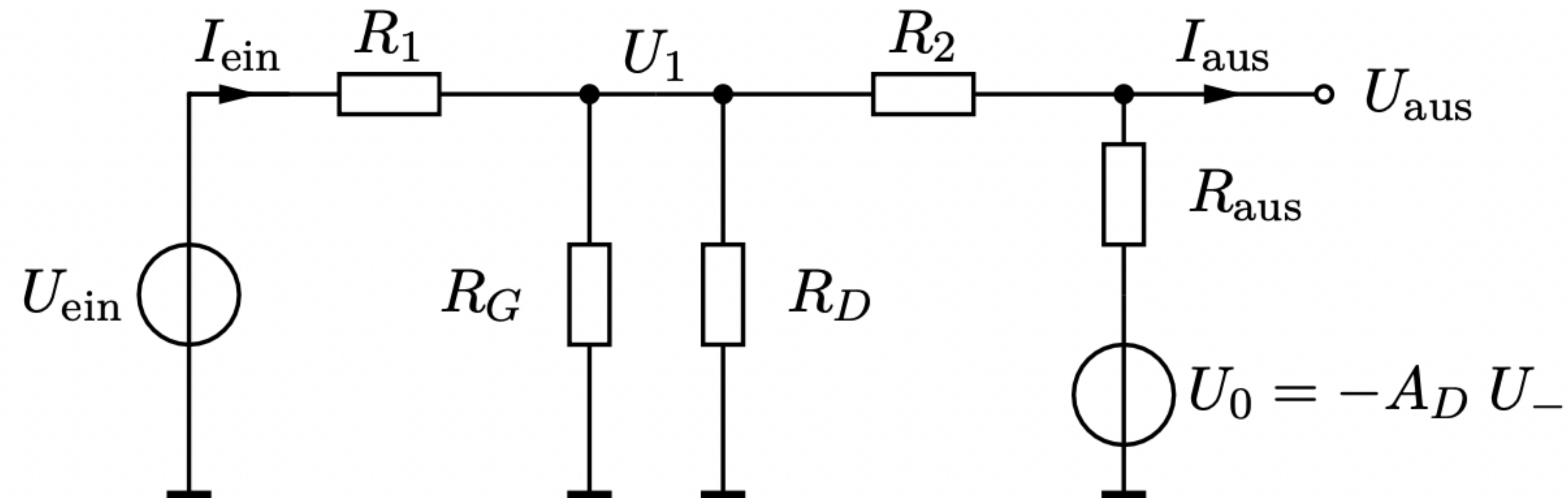
$$Z_{ein} = \frac{dU_{ein}}{dI_{ein}}$$

for open output $I_{aus} = 0$

$$Z_{aus} = \frac{dU_{aus}}{dI_{aus}}$$

short circuit on input

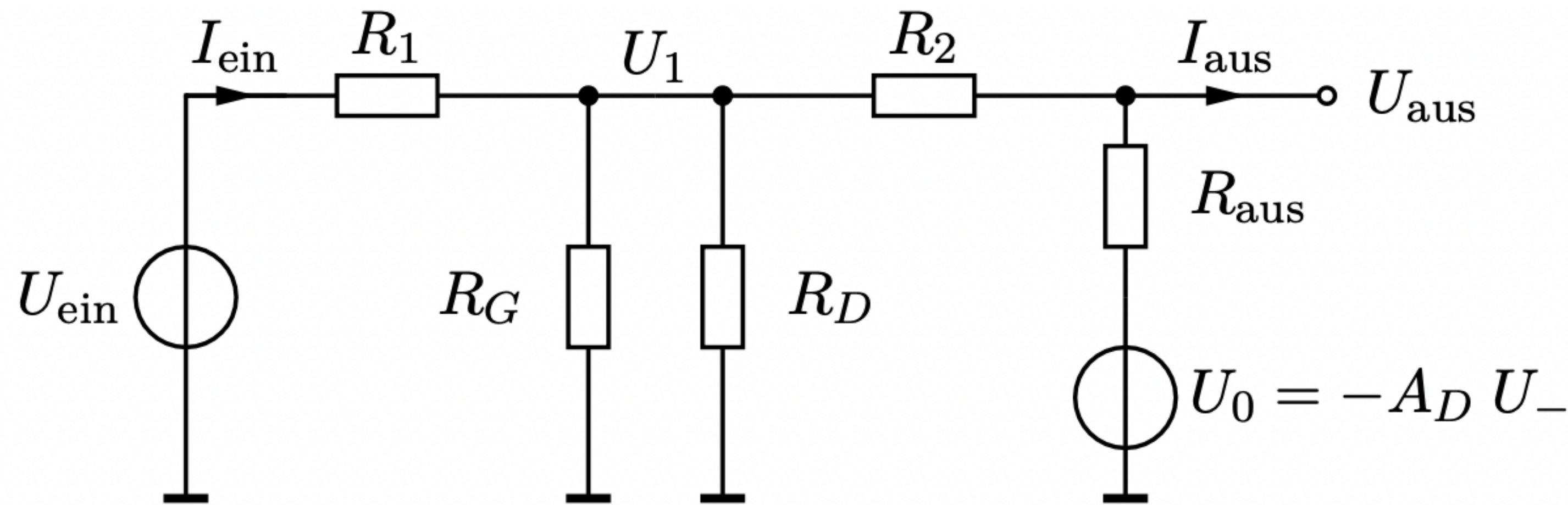
$$U_{ein} = 0$$



$U_- = U_1$ Voltage on inverting input

Equivalent Circuit

Inverting Amplifier



$$I_{ein} = \frac{U_{ein} - U_-}{R_1}$$

$$(R_2 + R_{aus}) = R$$

can be calculated with superposition principle, assuming $R_G \gg R_D \gg R_1, R_2$
- not done in detail here -

$$U_- = U_{ein} \frac{R}{R_1 + R} - A_D U_- \frac{R_1}{R + R_1} \quad \Rightarrow \quad U_- = U_{ein} \frac{R}{R + R_1 + R_1 A_D}$$

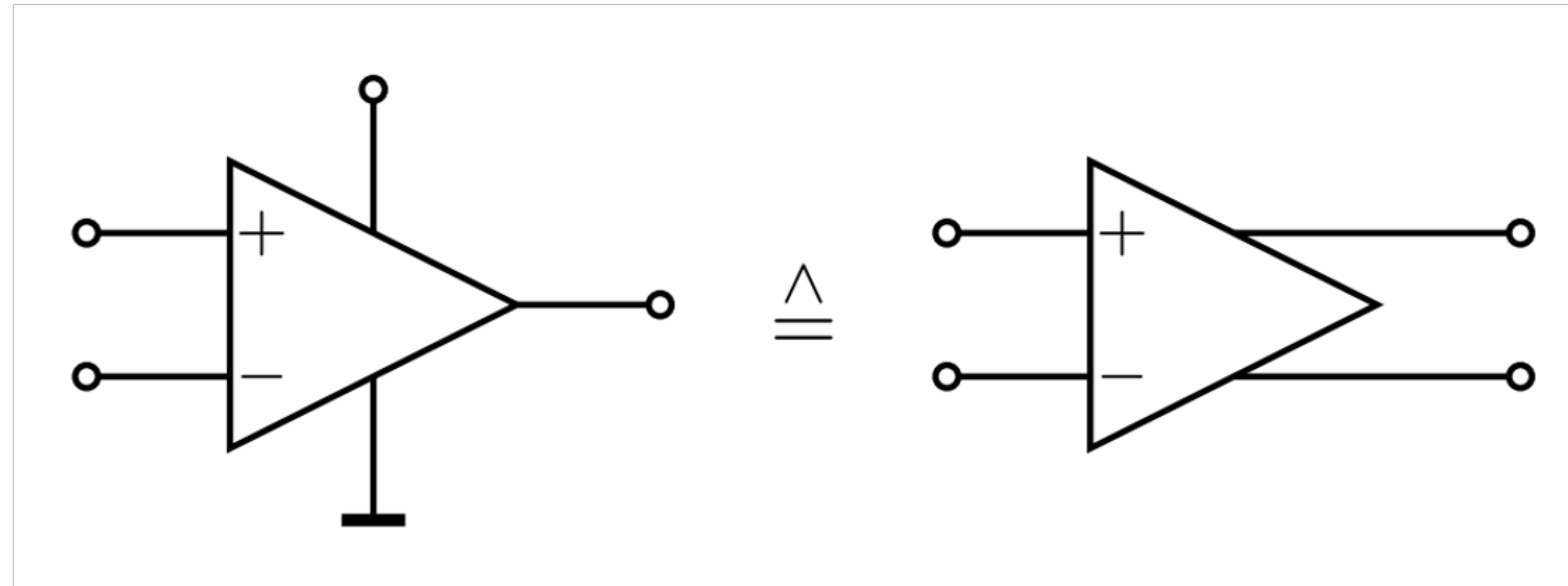
A_D is very large. Consequence: $U_- \ll U_{ein} \Rightarrow \sim 0$ V (“virtual mass”), see 1st Golden Rule. Results in: $Z_{ein} = R_1$

$$\text{Reminder: } Z_{ein} = \frac{dU_{ein}}{dI_{ein}}$$

More general Perspectives on Feedback

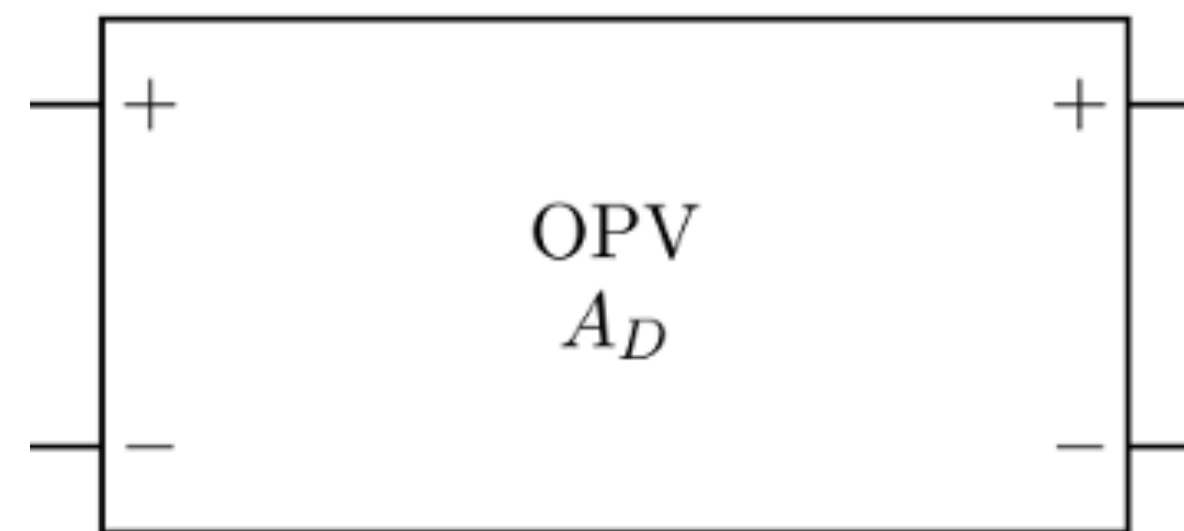
Control Loop

- Here: Assume an OpAmp with differential input and output

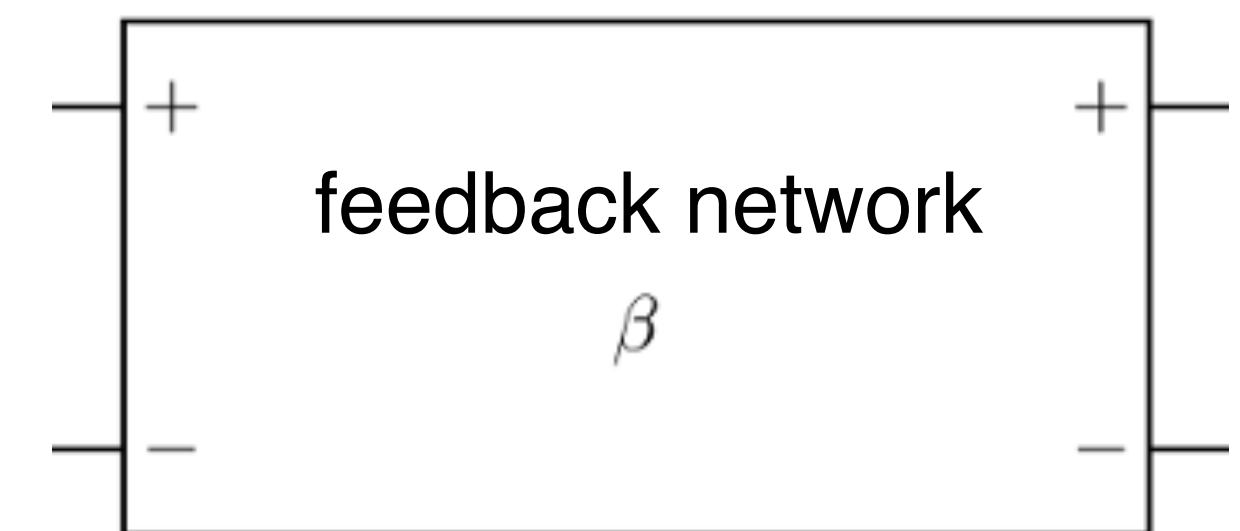


The components:

OpAmp with
differential gain A_D

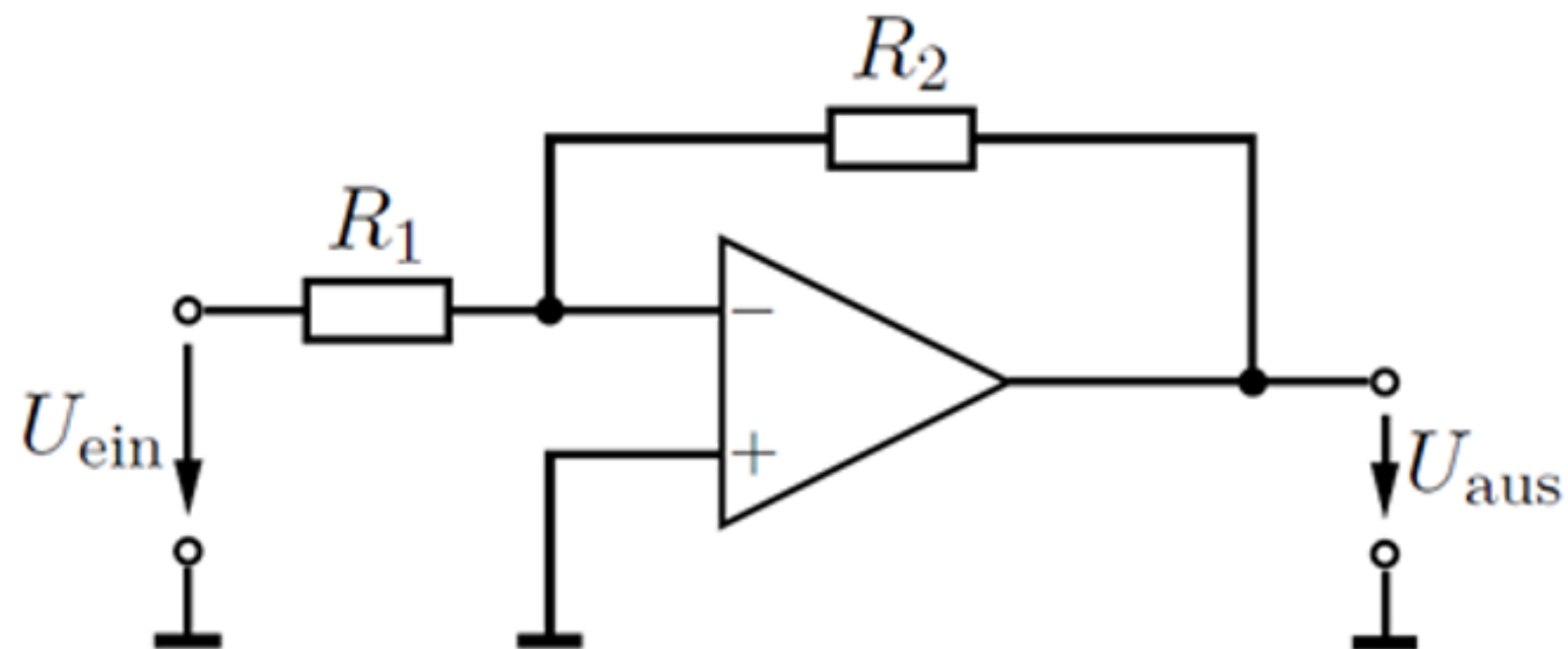


Feedback Network



More general Perspectives on Feedback

Inverting Amplifier

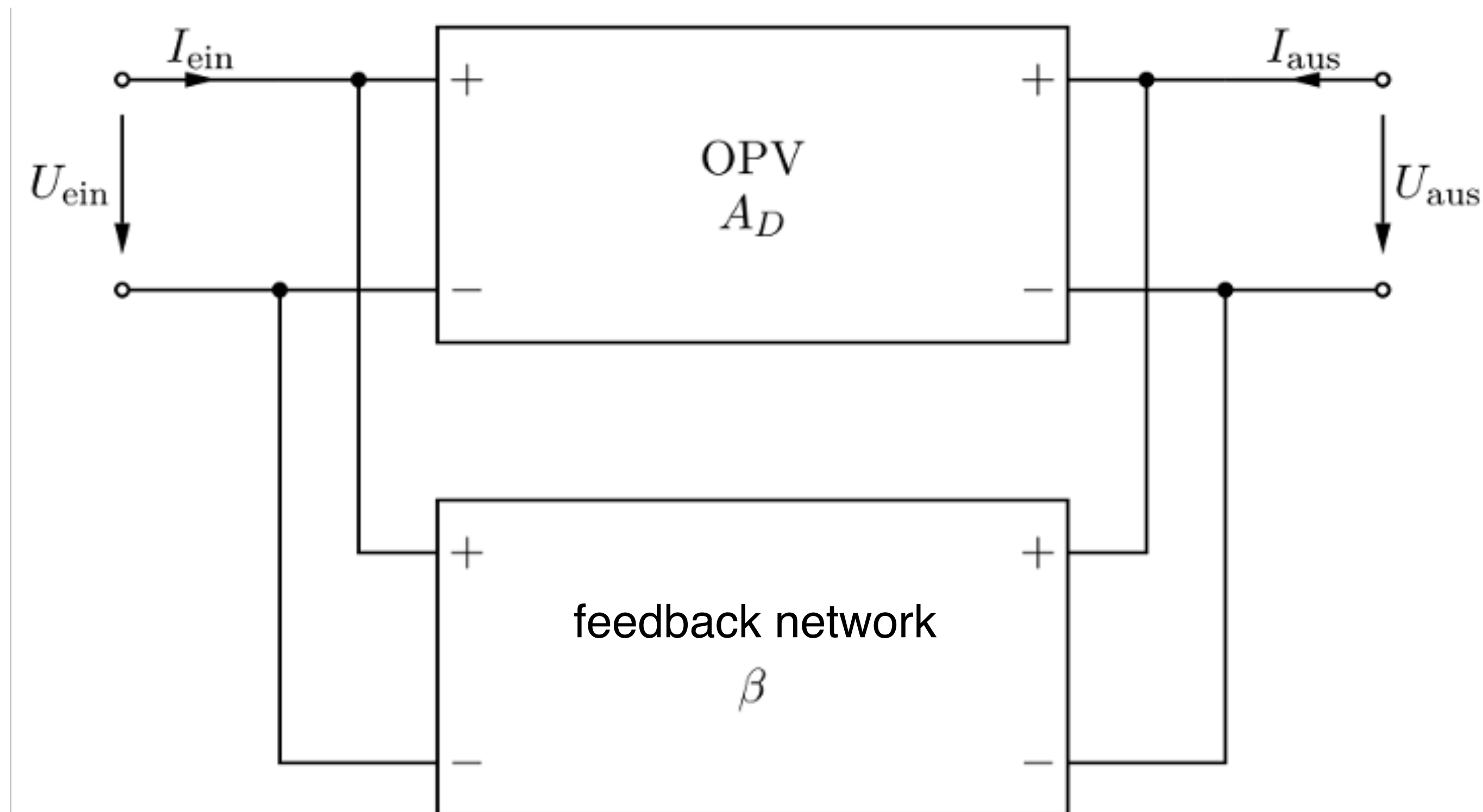


$$I_{\text{ein}} = U_{\text{ein}}/R_1 \text{ (since } U_- = 0\text{)}$$

Gain: $A = U_{\text{aus}}/U_{\text{ein}}$, or

$$A = \frac{dU_{\text{aus}}}{dI_{\text{ein}}}$$

“current-voltage feedback”

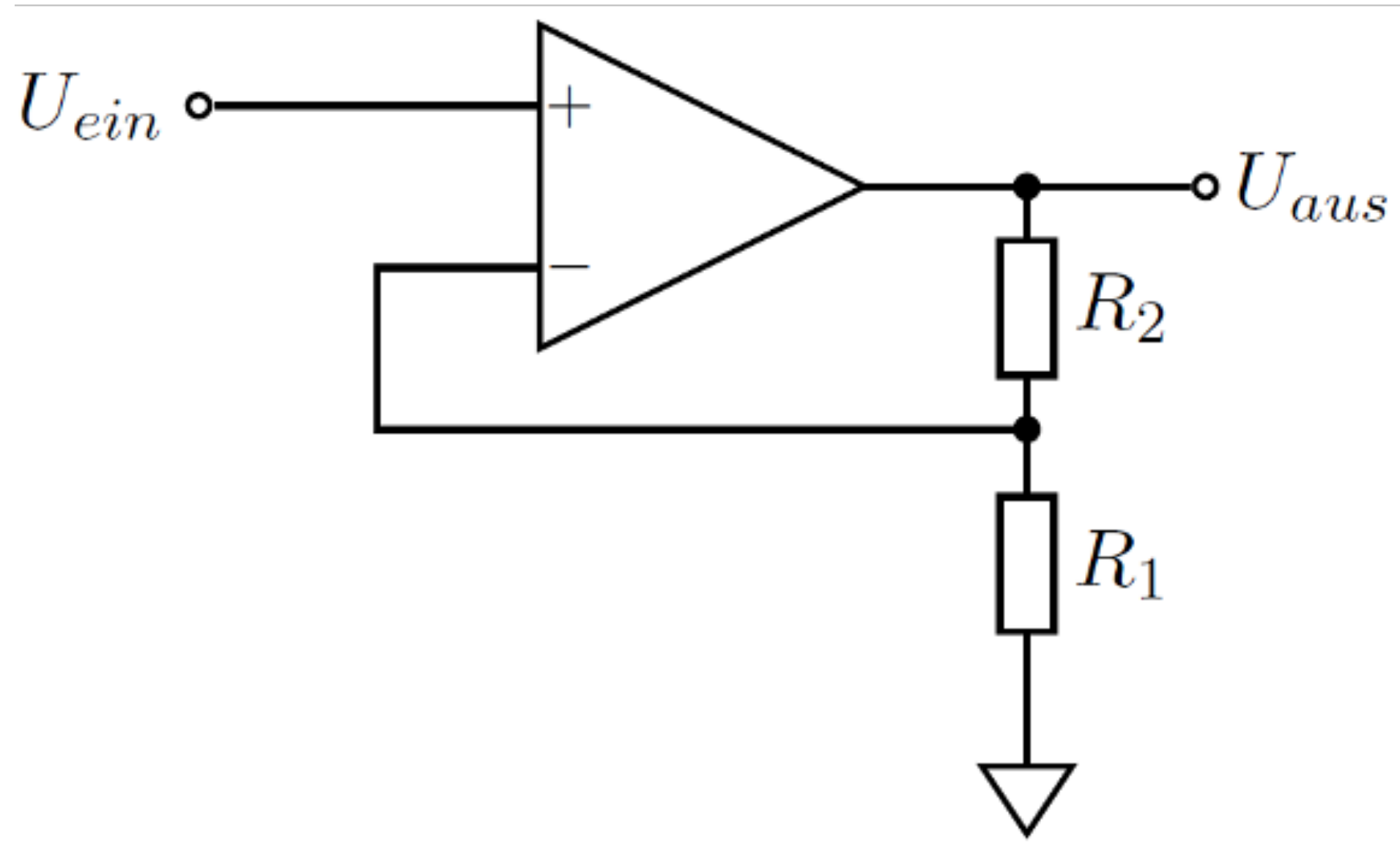


OpAmp parallel (“shunt”) on input and output of the feedback network: “shunt - shunt”

The feedback reduces input and output impedance.

More general Perspectives on Feedback

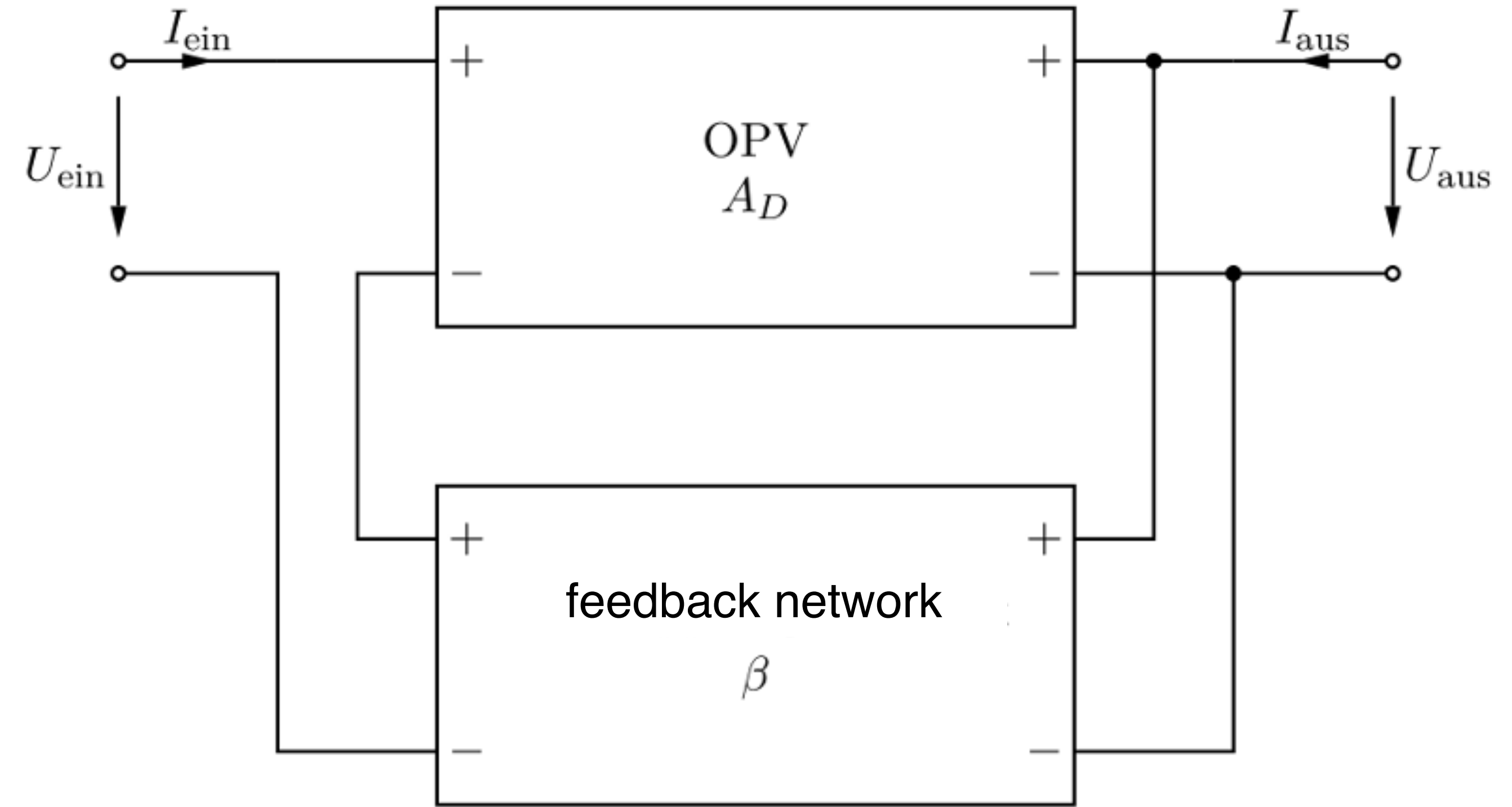
Non-inverting Amplifier



gain: $A = U_{aus}/U_{ein}$, or

$$A = \frac{dU_{aus}}{dU_{ein}}$$

“voltage amplifier”

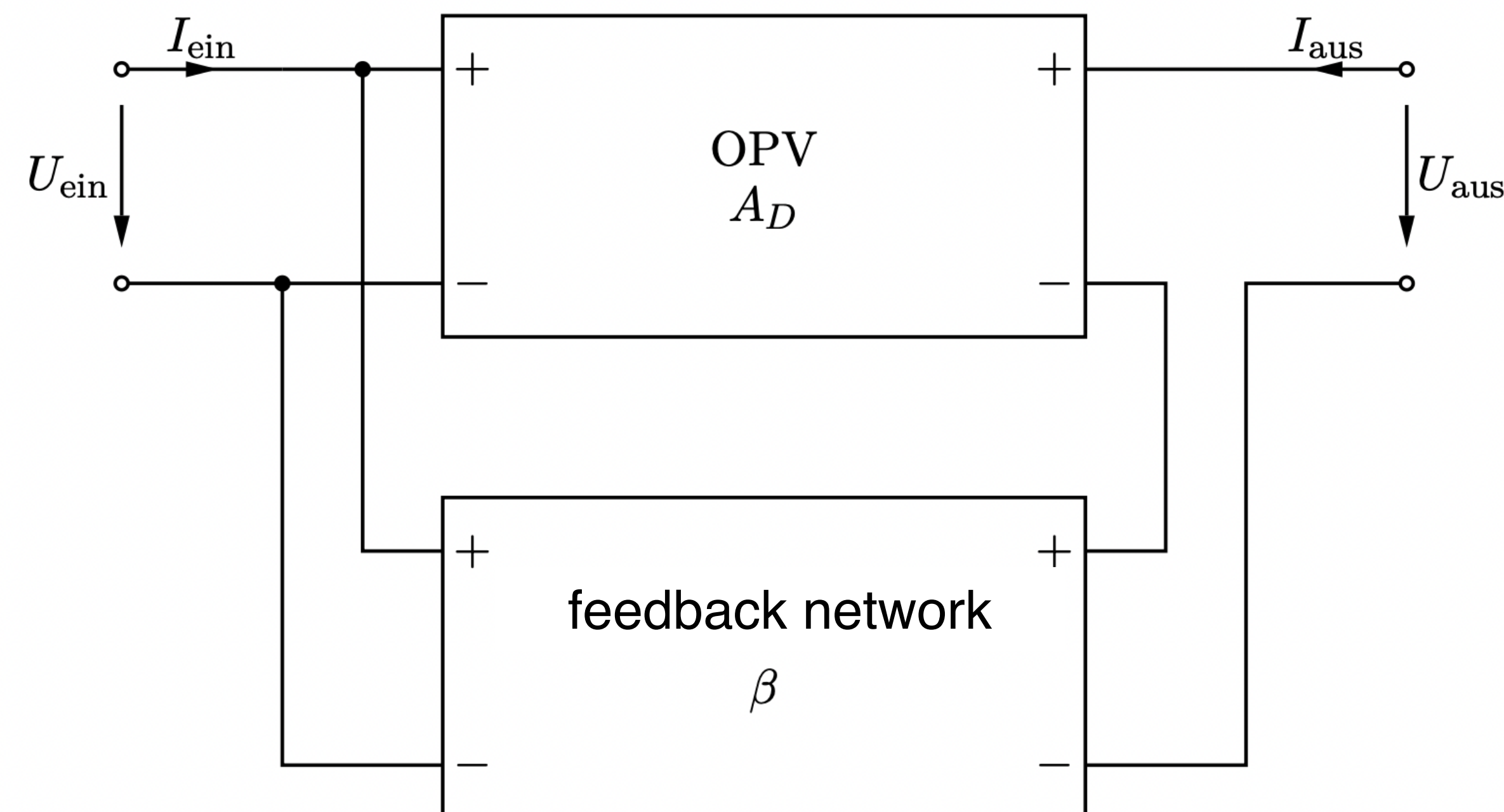


OpAmp in series (“series”) on input, parallel (“shunt”) on output of the feedback network : “series - shunt”

The feedback increases input impedance, reduces output impedance.

More general Perspectives on Feedback

Additional Options

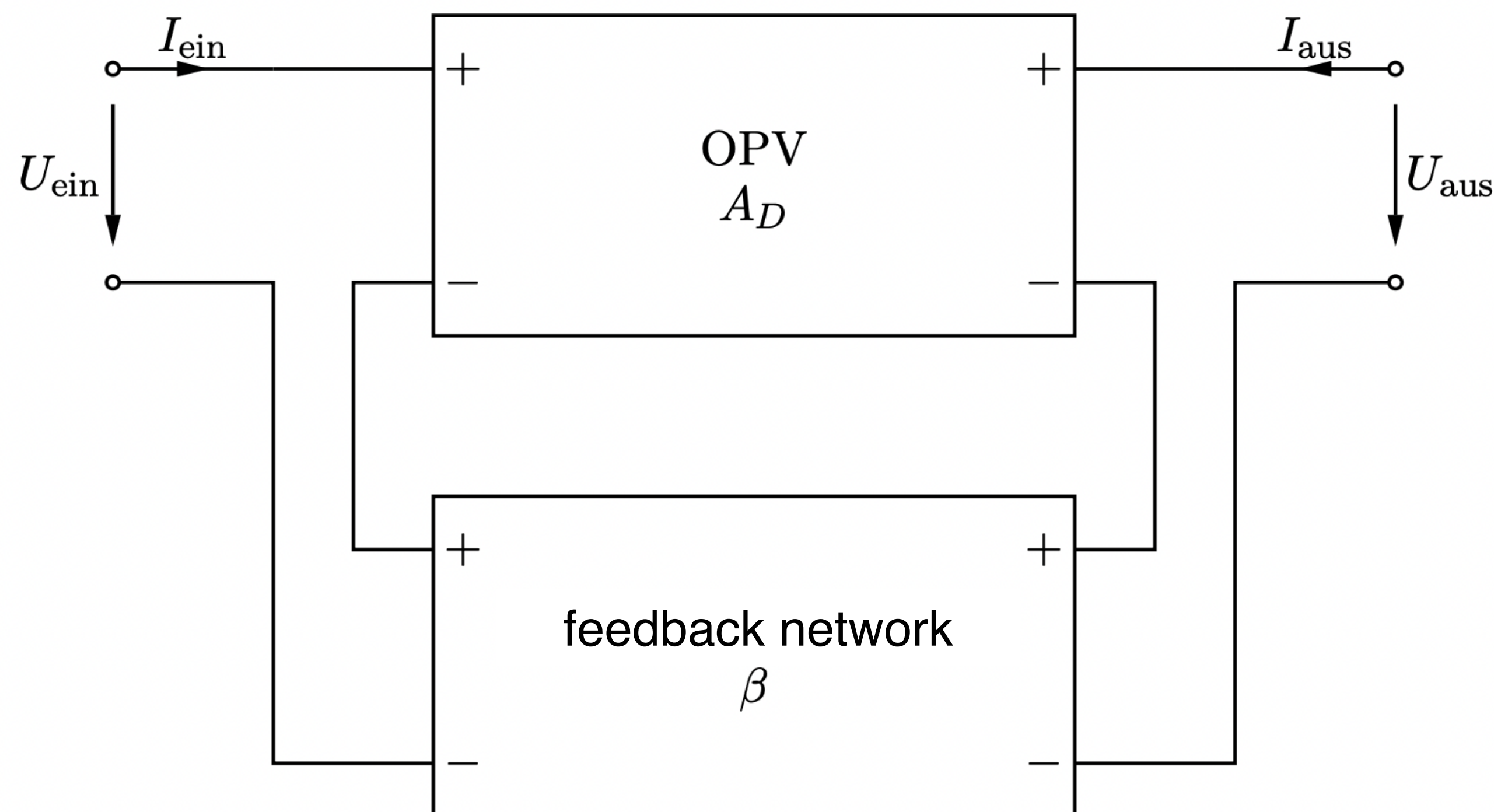


OpAmp in parallel (“shunt”) on input, in series (“series”) on output of feedback network: “shunt - series”

low input impedance, high output impedance:

Current-Current feedback

Current amplifier / current source



“series-series”

High input and output impedance:

Voltage-current feedback

“Transconductance amplifier”

Feedback: Summary

General View

Amplifier	Type	Gain	R_{ein}	R_{aus}
non-inverting amplifier (series-shunt)	voltage to voltage	$\frac{A_D}{1 + \beta A_D}$	$(1 + \beta A_D) R_{\text{ein}}$	$\frac{R_{\text{aus}}}{1 + \beta A_D}$
inverting amplifier (shunt-shunt)	current to voltage	$\frac{A_D}{1 + \beta A_D} \approx -R_2$	$\frac{R_{\text{ein}}}{1 + \beta A_D}$	$\frac{R_{\text{aus}}}{1 + \beta A_D}$
current amplifier (shunt-series)	current to current	$\frac{A_D}{1 + \beta A_D}$	$\frac{R_{\text{ein}}}{1 + \beta A_D}$	$(1 + \beta A_D) R_{\text{aus}}$
transconductance amplifier (series-series)	voltage to current	$\frac{A_D}{1 + \beta A_D}$	$(1 + \beta A_D) R_{\text{ein}}$	$(1 + \beta A_D) R_{\text{aus}}$

A_D : open loop gain

βA_D : loop gain

$R_{\text{ein}}, R_{\text{aus}}$:
input / output
impedance w/o
feedback

Feedback: Summary

General View - For Reference with German Terms

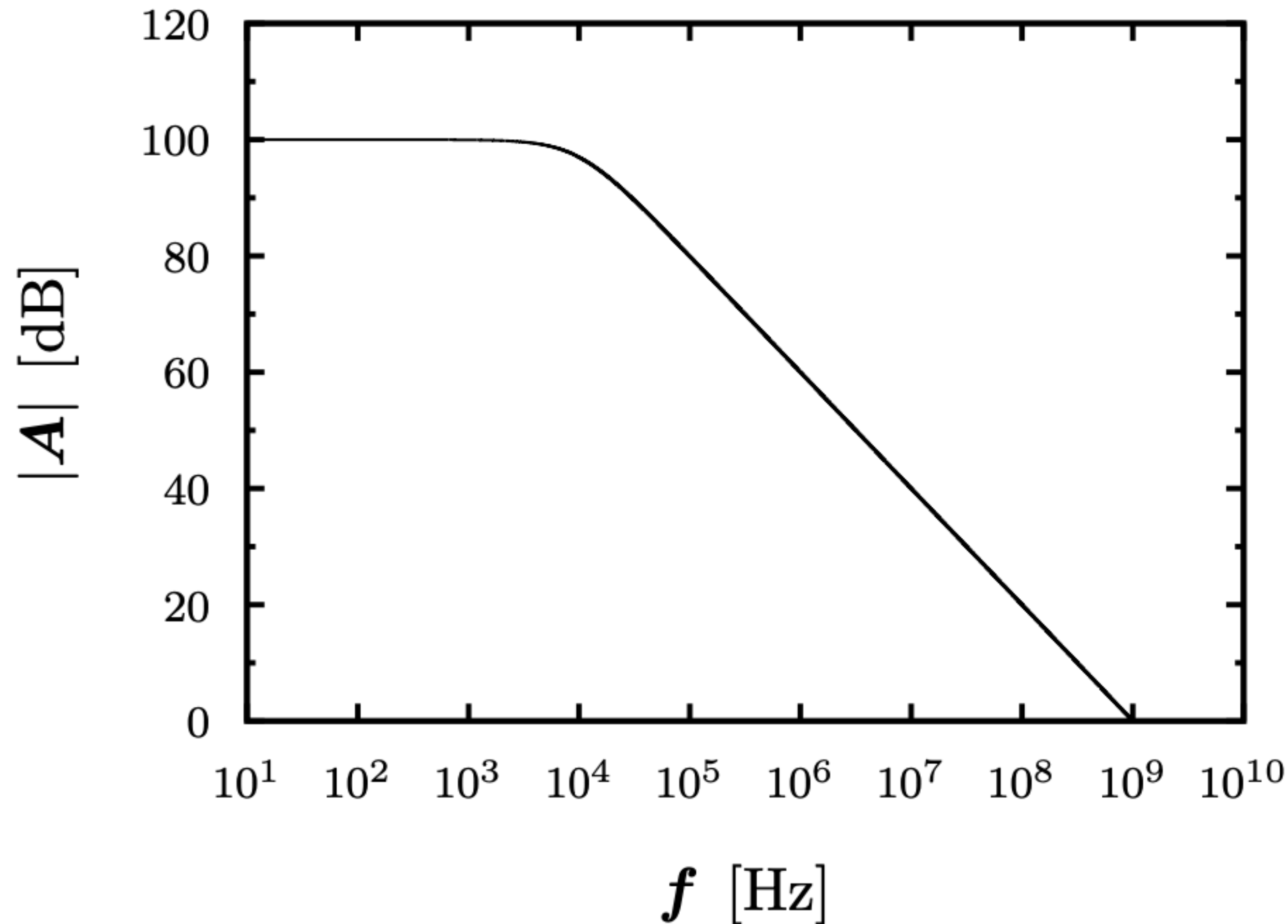
Verstärker	Typus	Verstärkung	R_{ein}	R_{aus}
Nicht-invertierender OPV (series-shunt)	Spannung zu Spannung	$\frac{A_D}{1 + \beta A_D}$	$(1 + \beta A_D) R_{\text{ein}}$	$\frac{R_{\text{aus}}}{1 + \beta A_D}$
Invertierender OPV (shunt-shunt)	Strom zu Spannung	$\frac{A_D}{1 + \beta A_D} \approx -R_2$	$\frac{R_{\text{ein}}}{1 + \beta A_D}$	$\frac{R_{\text{aus}}}{1 + \beta A_D}$
Stromverstärker (shunt-series)	Strom zu Strom	$\frac{A_D}{1 + \beta A_D}$	$\frac{R_{\text{ein}}}{1 + \beta A_D}$	$(1 + \beta A_D) R_{\text{aus}}$
Transkonduktanzverstärker (series-series)	Spannung zu Strom	$\frac{A_D}{1 + \beta A_D}$	$(1 + \beta A_D) R_{\text{ein}}$	$(1 + \beta A_D) R_{\text{aus}}$

A_D : Leerlauf-Verstärkung

βA_D : Schleifenverstärkung

$R_{\text{ein}}, R_{\text{aus}}$:
Eingangs- / Ausgangs-Impedanz ohne Rückkopplung

- Typically: Gain decreases with frequency, often as for a simple low pass



Gain drops significantly beyond cutoff frequency (“Grenzfrequenz) f_g

$$\underline{A}_D = \frac{A_{D_0}}{1 + j \frac{f}{f_g}}$$

Cutoff frequency = equal imaginary and real component of gain (see Chapter 02, Bode Plots)

What happens when feedback is introduced?

Reminder:

$$A = \frac{U_{aus}}{U_{ein}} = \frac{K_F A_D}{1 + K_R A_D} \approx \frac{K_F}{K_R}$$

Frequency Behavior with negative Feedback

Non-inverting Amplifier

- Gain with feedback ($K_F = 1$):

$$\underline{A} = \frac{\underline{U}_{aus}}{\underline{U}_{ein}} = \frac{\underline{A}_D}{1 + K_R \underline{A}_D}$$

adding frequency dependence:

$$\underline{A} = \frac{\frac{A_{D0}}{1 + j\frac{f}{f_0}}}{1 + K_R \frac{A_{D0}}{1 + j\frac{f}{f_0}}}$$

results in:
$$\underline{A} = \frac{A_{D0}}{1 + j\frac{f}{f_g} + K_R A_{D0}} \approx \frac{A_{D0}}{j\frac{f}{f_g} + K_R A_{D0}}$$

For low frequencies $f \ll f_g$
$$\underline{A} \approx \frac{1}{K_R} \quad (\text{frequency independent})$$

For high frequencies $f \gg f_g$
$$\underline{A} \approx \frac{A_{D0}}{j\frac{f}{f_g}} \quad \text{and} \quad \underline{A}_D \approx \frac{A_{D0}}{j\frac{f}{f_g}}$$

Frequency Behavior with negative Feedback

Non-inverting Amplifier

- More interesting: The region between the extremes

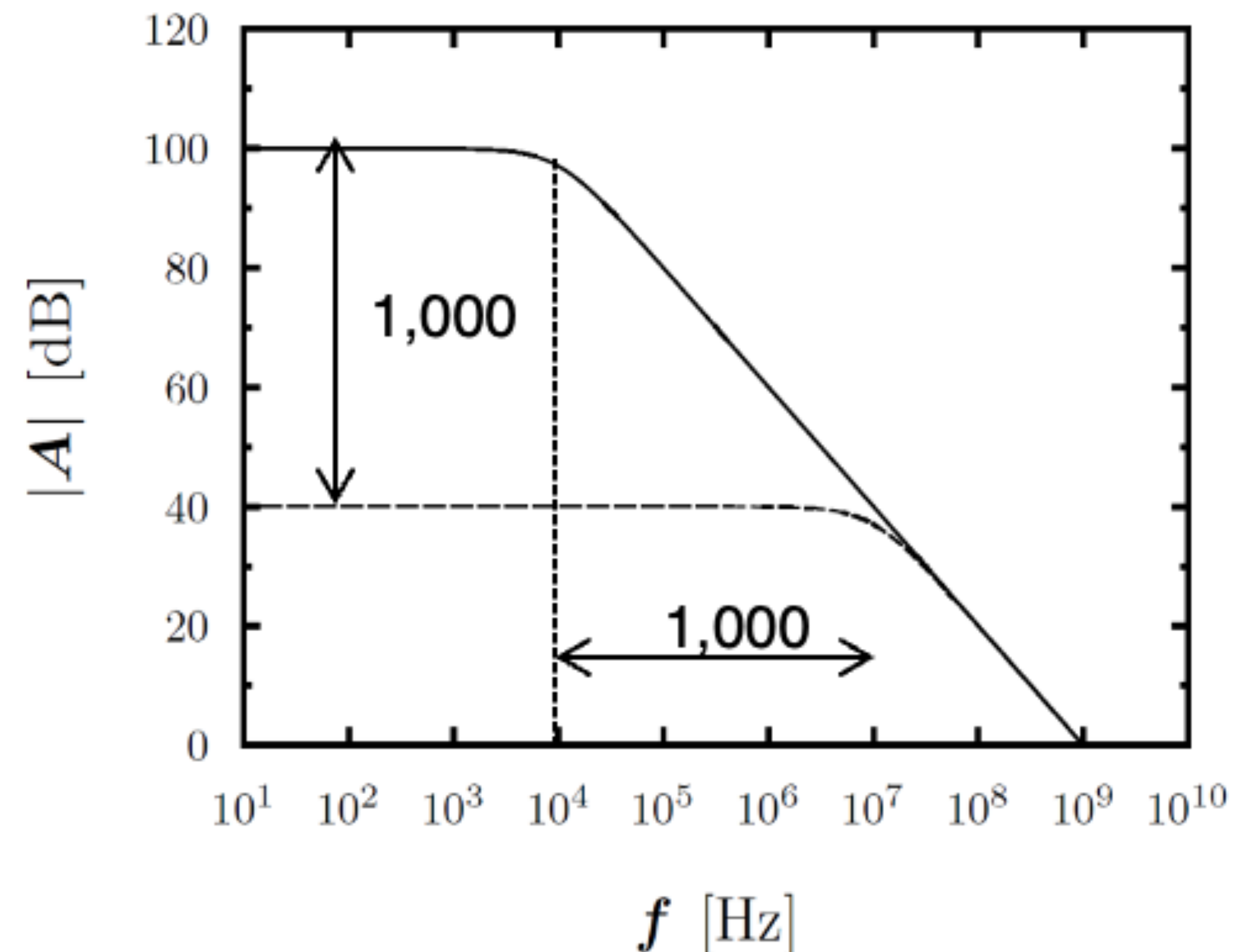
Cutoff frequency = equal imaginary and real component of gain

$$\underline{A} \approx \frac{A_{D_0}}{j\frac{f}{f_g} + K_R A_{D_0}} \quad \text{resulting in} \quad f_{g,FB} = f_g K_R A_{D_0}$$

feedback increases the cutoff frequency of the amplifier!

by
$$\frac{\text{open-loop gain } A_{D_0}}{\text{closed-loop gain } 1/K_R}$$

=> Lower gain => Higher cut-off frequency.



Frequency Behavior with negative Feedback

Gain Bandwidth Product

- Bandwidth of the amplifier: Region of (relatively) constant frequency-independent gain.

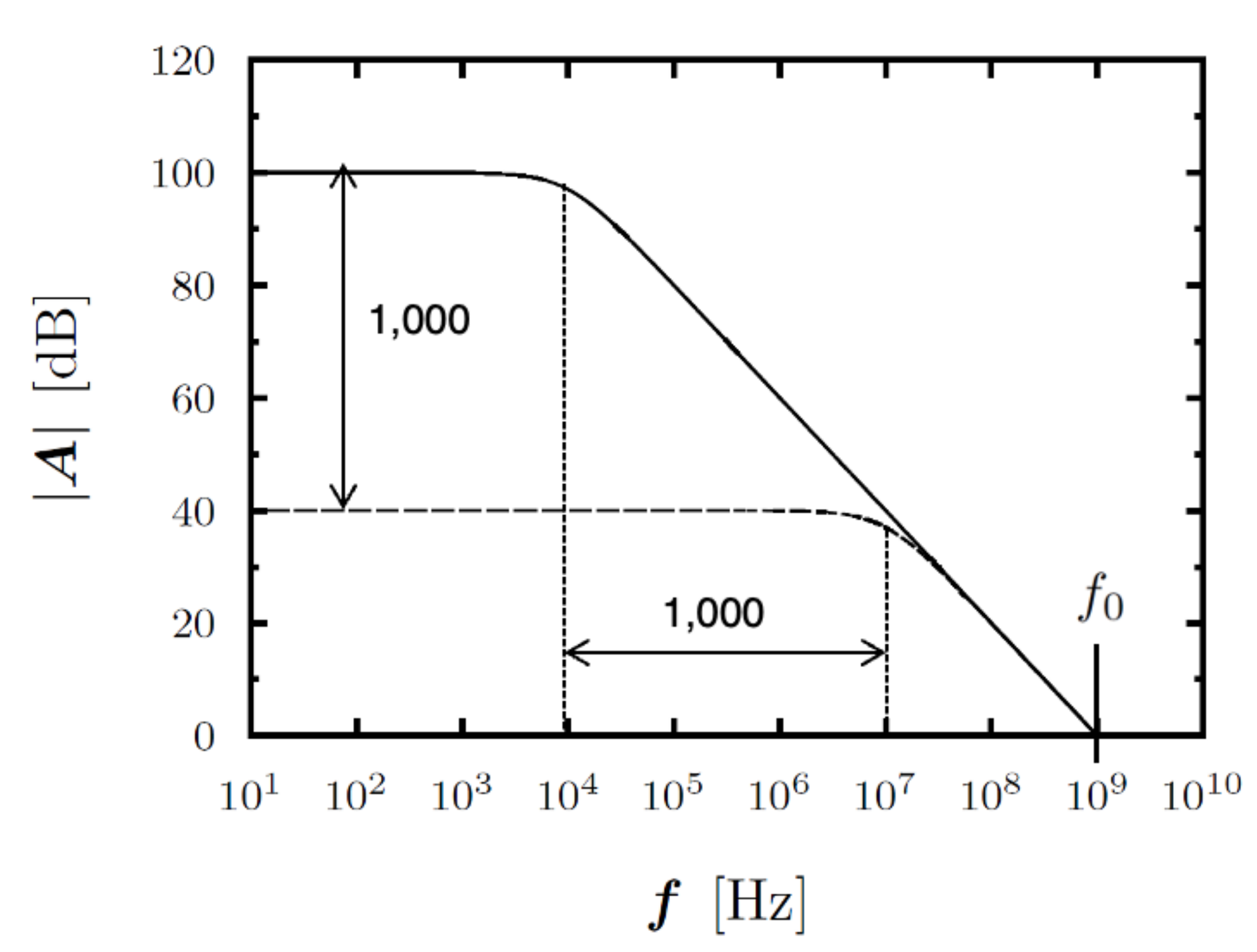
You can trade gain vs bandwidth:
Bandwidth increases by the same factor as gain is reduced.

“Gain-Bandwidth-Product GBP”:

$$A_{D_0} \cdot f_g = \frac{1}{K_R} \cdot f_{g,FB} = \frac{1}{K_R} \cdot f_g K_R A_{D_0} = f_0$$

w/o feedback

with feedback

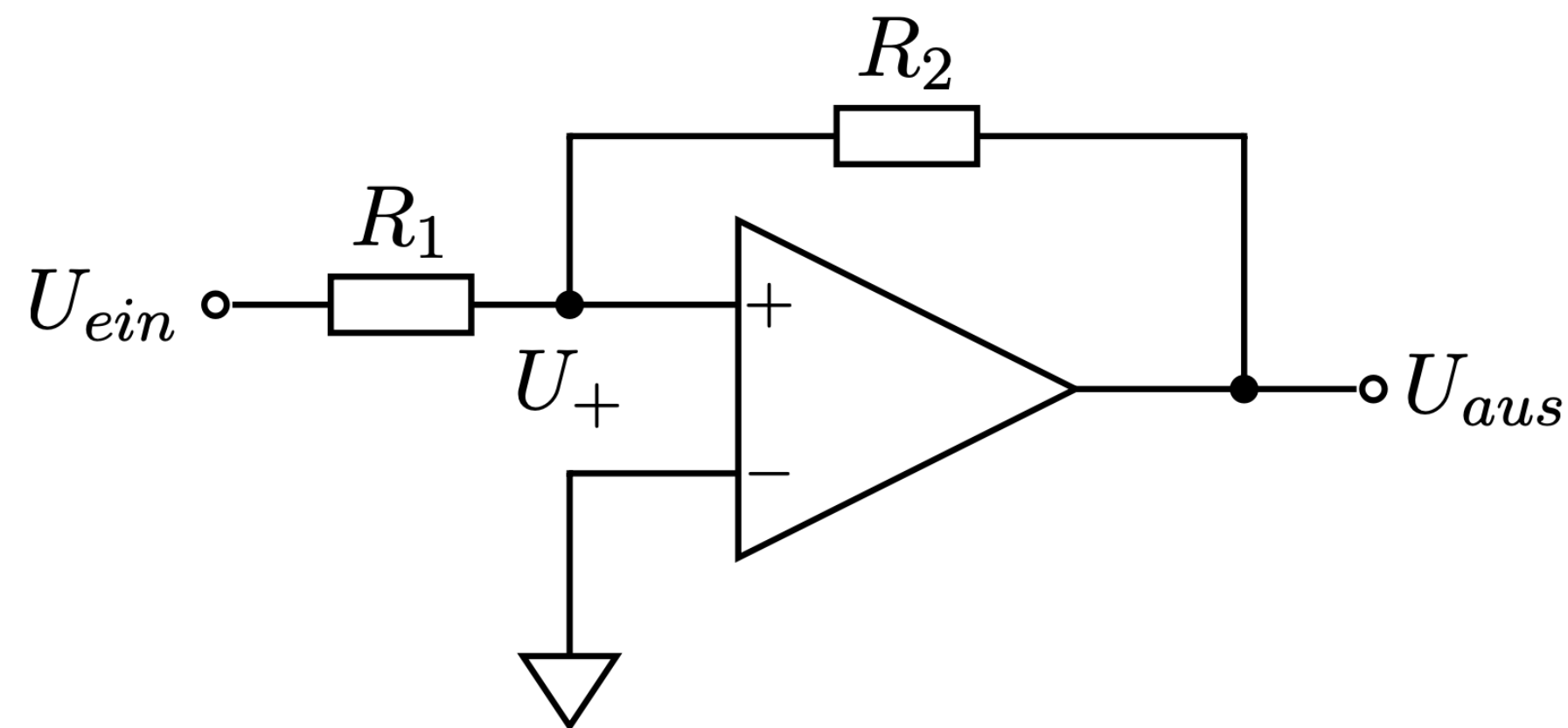


OpAmp Circuits - Part II

In: Chapter 4: Operational Amplifiers

- A wide range of applications, in particular in telecommunication, audio, ...
Desired: high frequency stability, low deviations from target waveform (distortions), ...

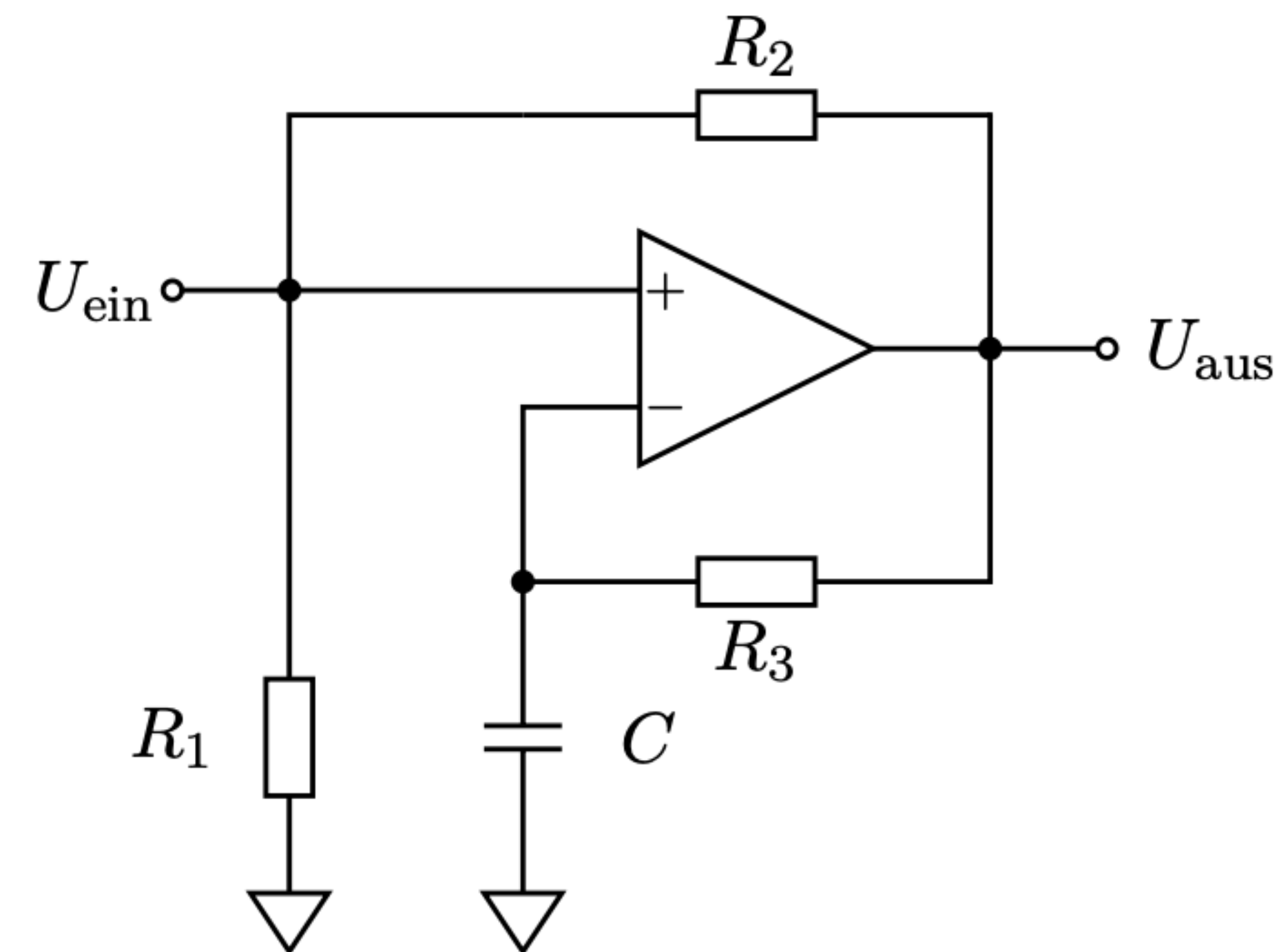
Reminder: Schmitt Trigger

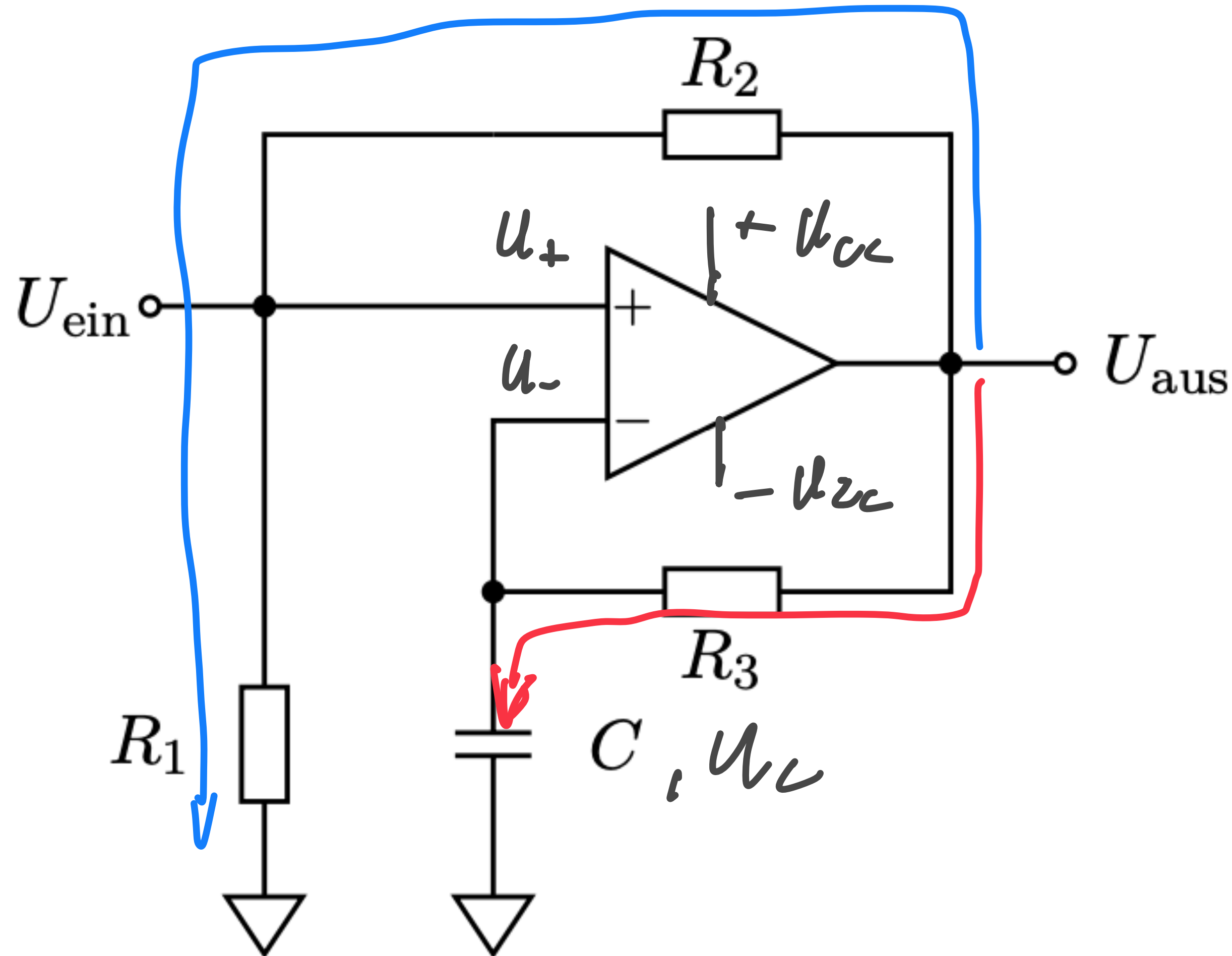


Two states:
 $+U_{CC}$, $-U_{CC}$

How do I get this
thing to oscillate?

Extension of feedback to both inputs





Starting point $t = 0$

$$U_{aus} = 0V \quad U_C = 0V$$

$\rightarrow U_{ein}$ positive

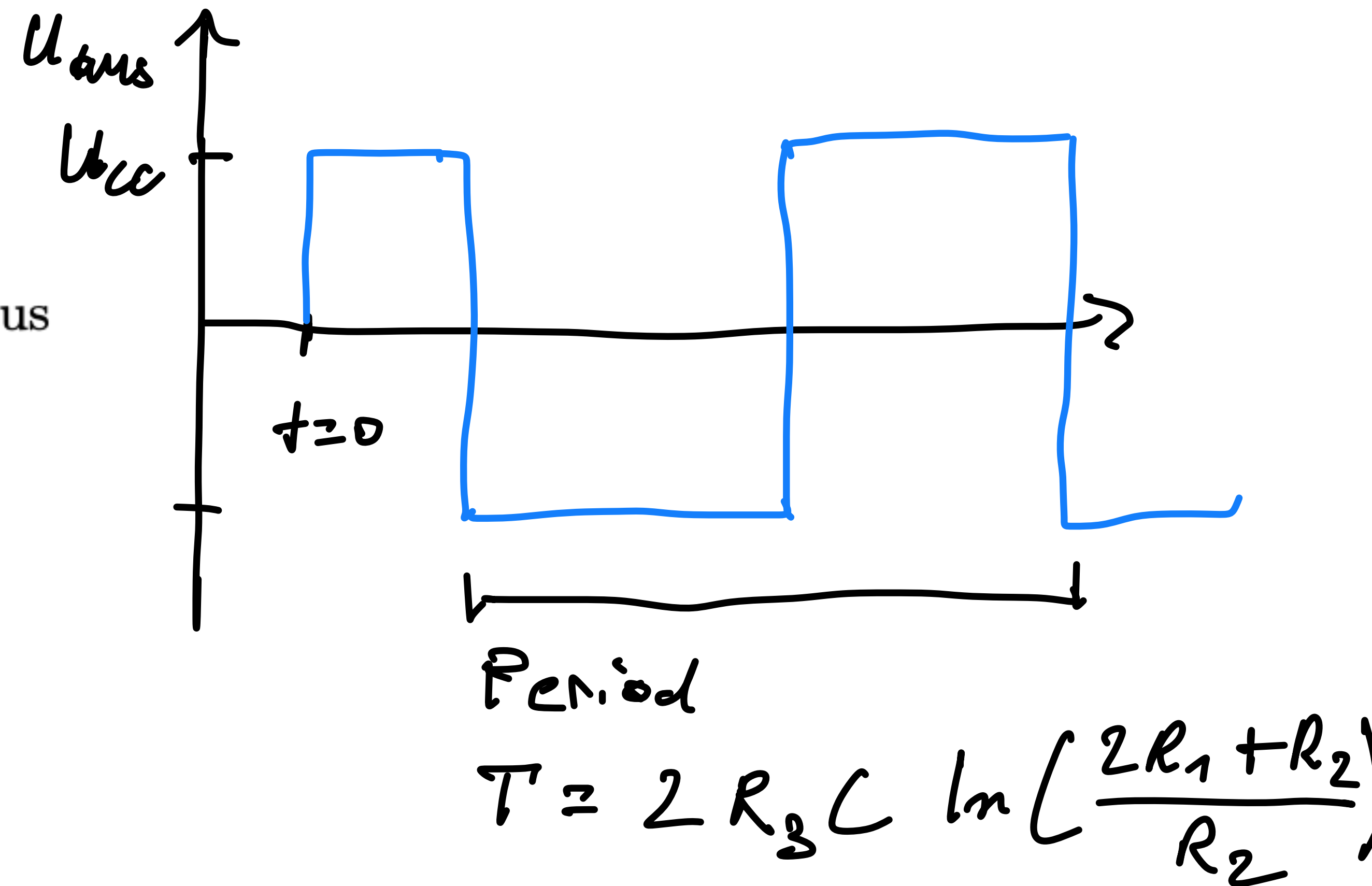
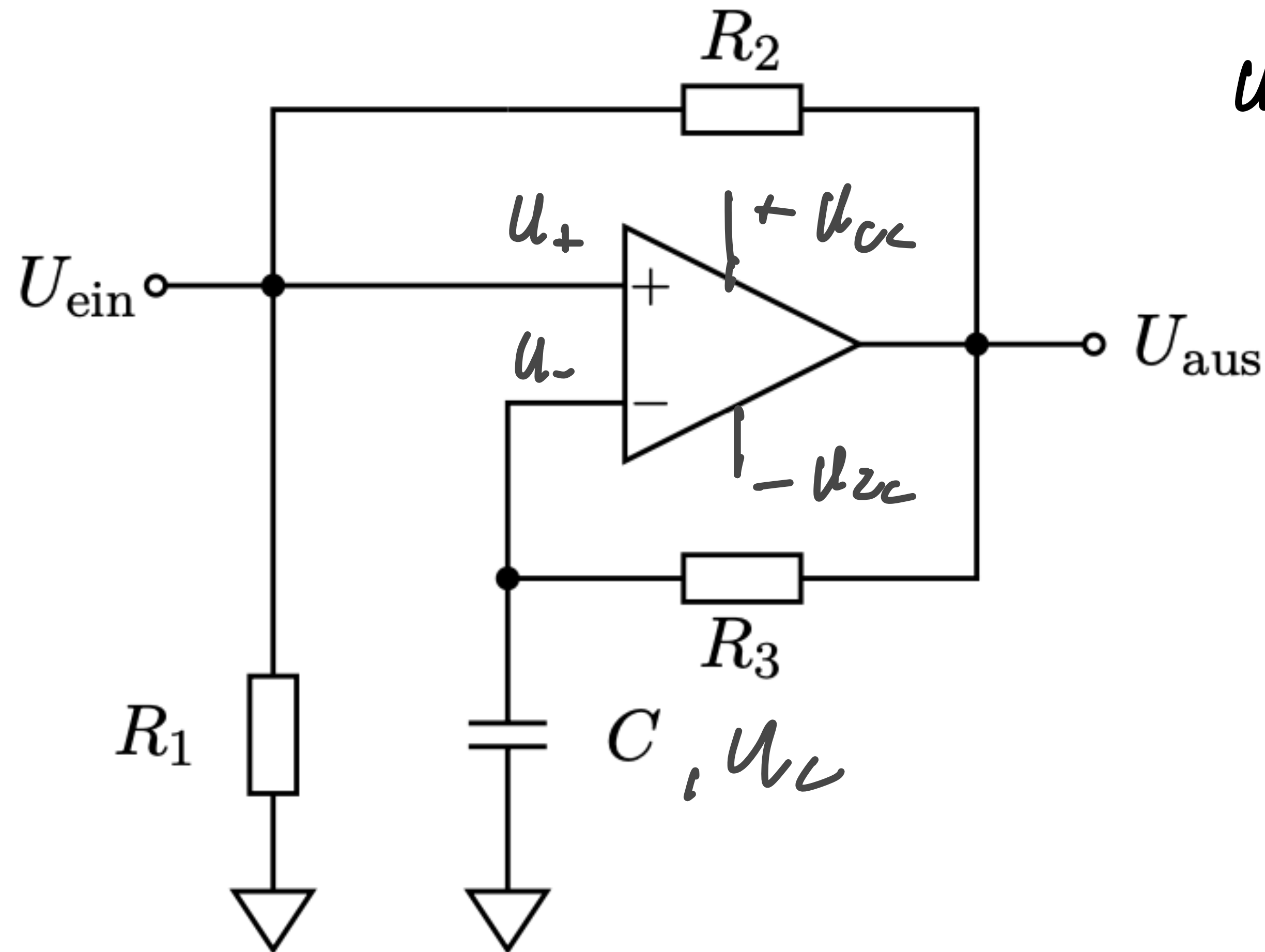
$$\rightarrow U_{aus} = +U_{CC}$$

$\rightarrow C$ is charged via R_3

Resulting in:

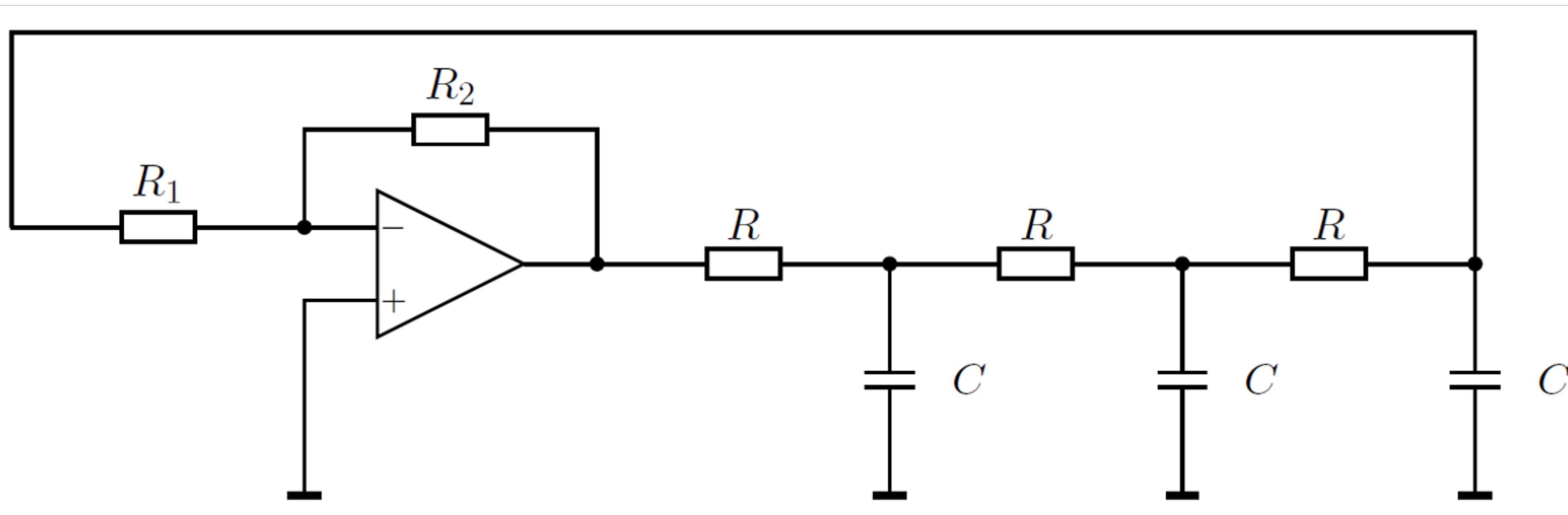
$$U_+ = U_{CC} \cdot \frac{R_1}{R_1 + R_2}$$

$$U_- = U_C = U_{CC} (1 - e^{-\frac{t}{R_3 C}})$$



- In general: How can stable, harmonic oscillations be achieved?

Oscillation condition: $U_{\text{aus}}(t) = U_{\text{aus}}(t+T)$

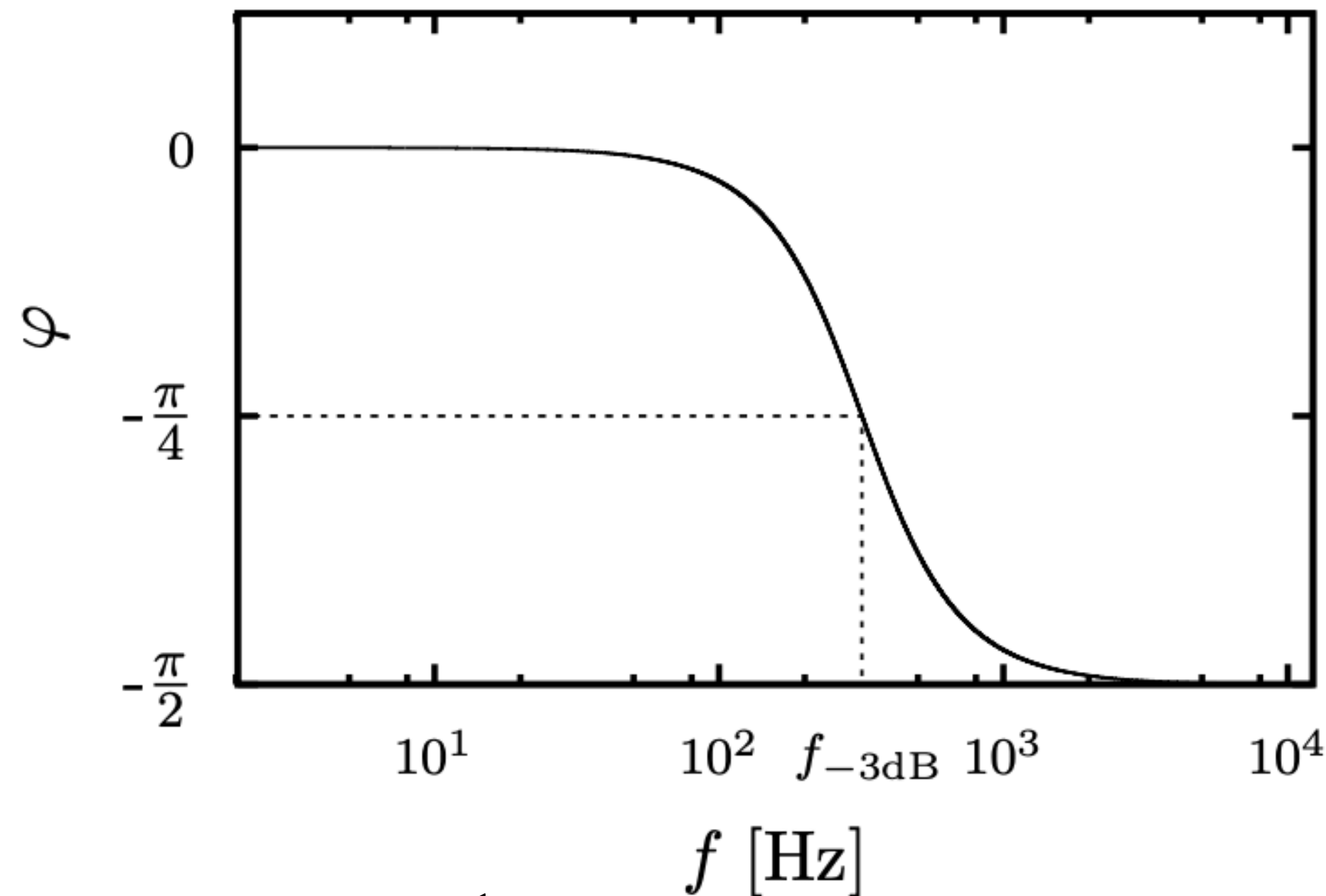


OpAmp with negative feedback, 3 low passes.

Frequency Dependence of Low Pass

Short Recall of Chapter 2

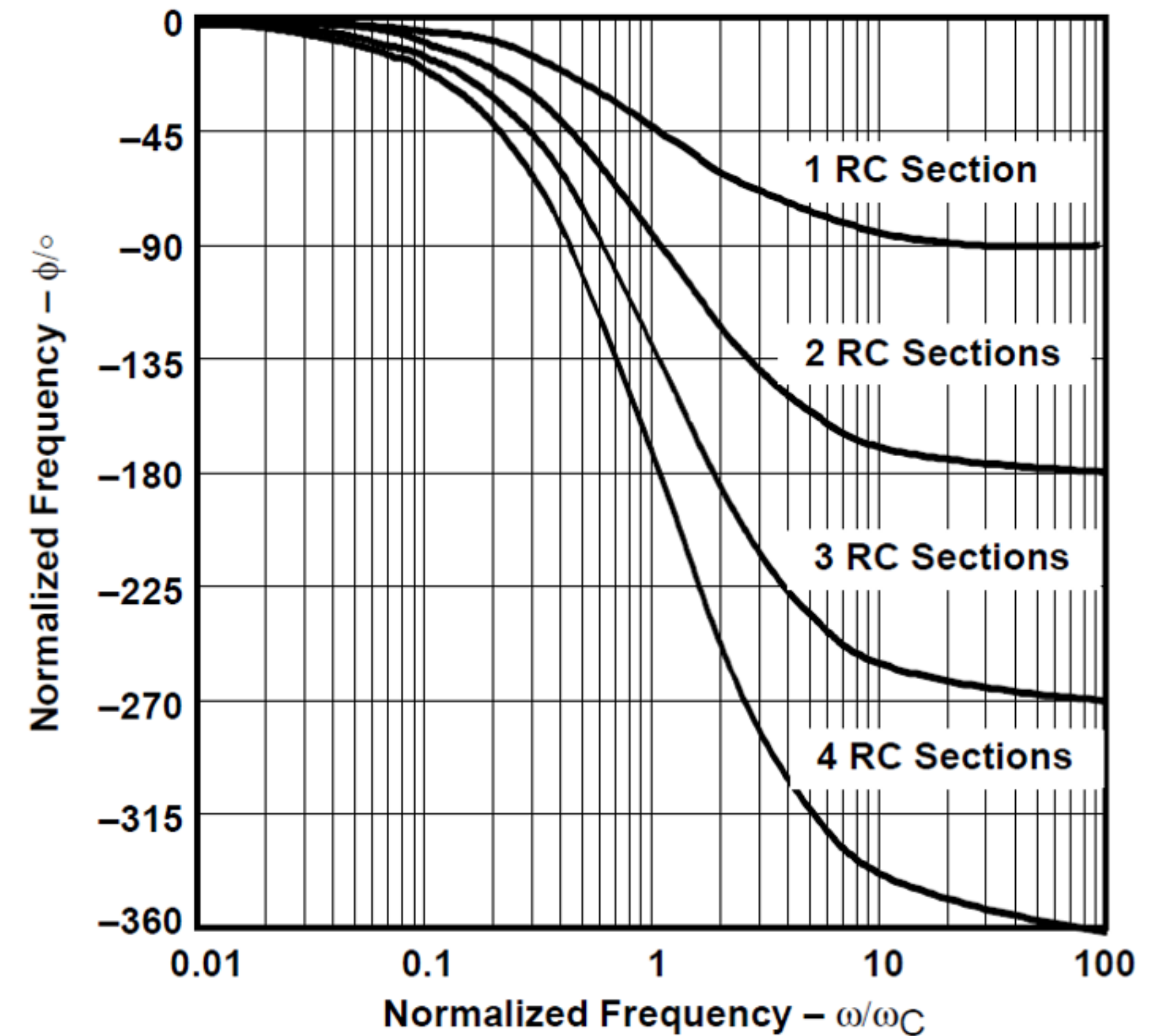
- Bode plot of low pass:

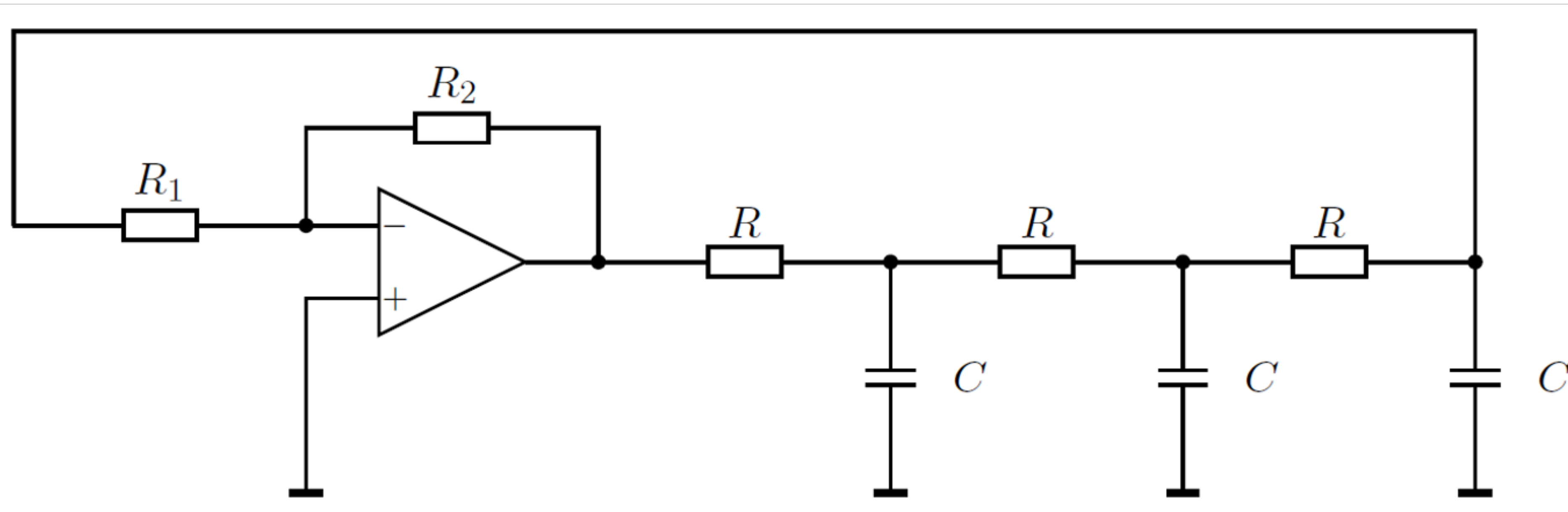


$$Z = \frac{1}{\sqrt{1 + (\omega RC)^2}} \quad \tan \varphi = -\omega RC$$

between 0 and 90 degrees phase shift

combination of multiple low passes

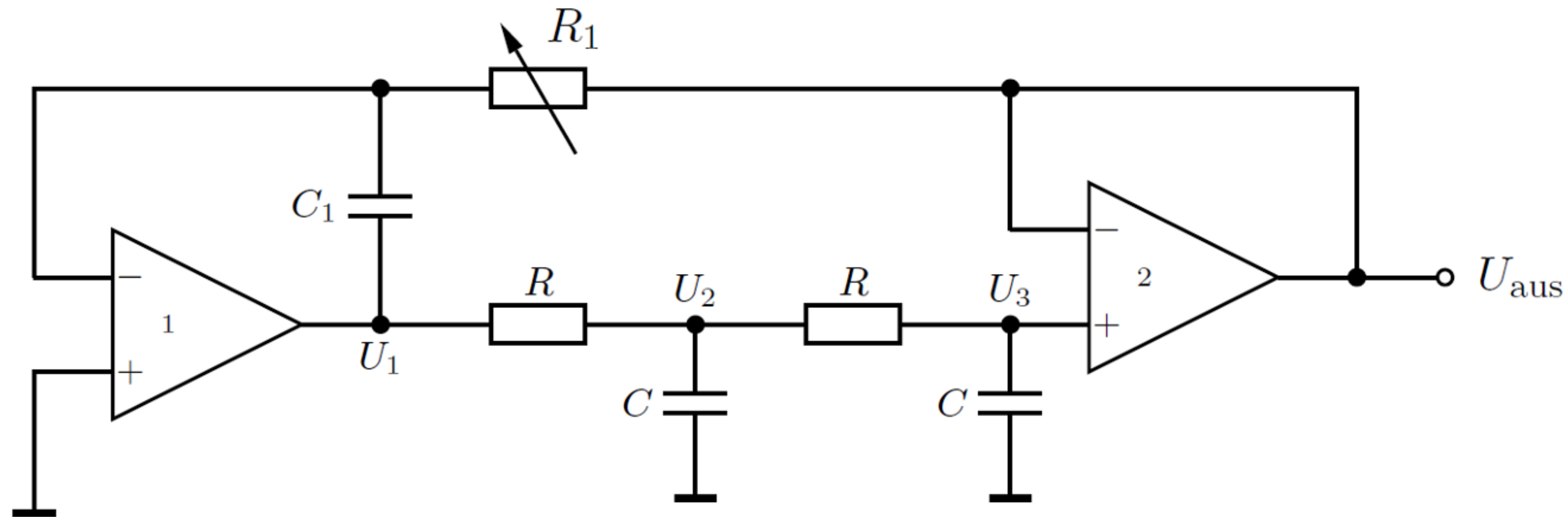




- Without external input: Oscillation for phase shifts of ± 360 degrees
- Resonance frequency depends on RC (here $\omega = 1.73/RC$ - 60 degrees per low pass)

$$U_{\text{aus}}(T) = -K_R A_D U_{\text{aus}}(t=0) = +U_{\text{aus}}(t=0)$$

Feedback network K_R contributes 180 degrees , inverting amplifier another 180 degrees.



- One integrator (OpAmp 1), two low passes, one voltage buffer
 - Adjustable via R_1

Here: No further details - see practical course!

- Gain of an OpAmp-based amplifier with negative feedback:

$$A = \frac{U_{aus}}{U_{ein}} = \frac{A_D}{1 + \beta A_D}$$

- 3 scenarios:

- Loop gain $|\beta A_D| \gg 1$:

Strong feedback, low gain:

-> stable behavior

$$A = \frac{A_D}{1 + \beta A_D} \approx \frac{1}{\beta}$$

- Loop gain $|\beta A_D| \ll 1$:

Weak feedback, very high gain $A \sim A_D$

-> stable behavior (not ideal for “normal” amplifiers, but ok as trigger, comparator, ...)

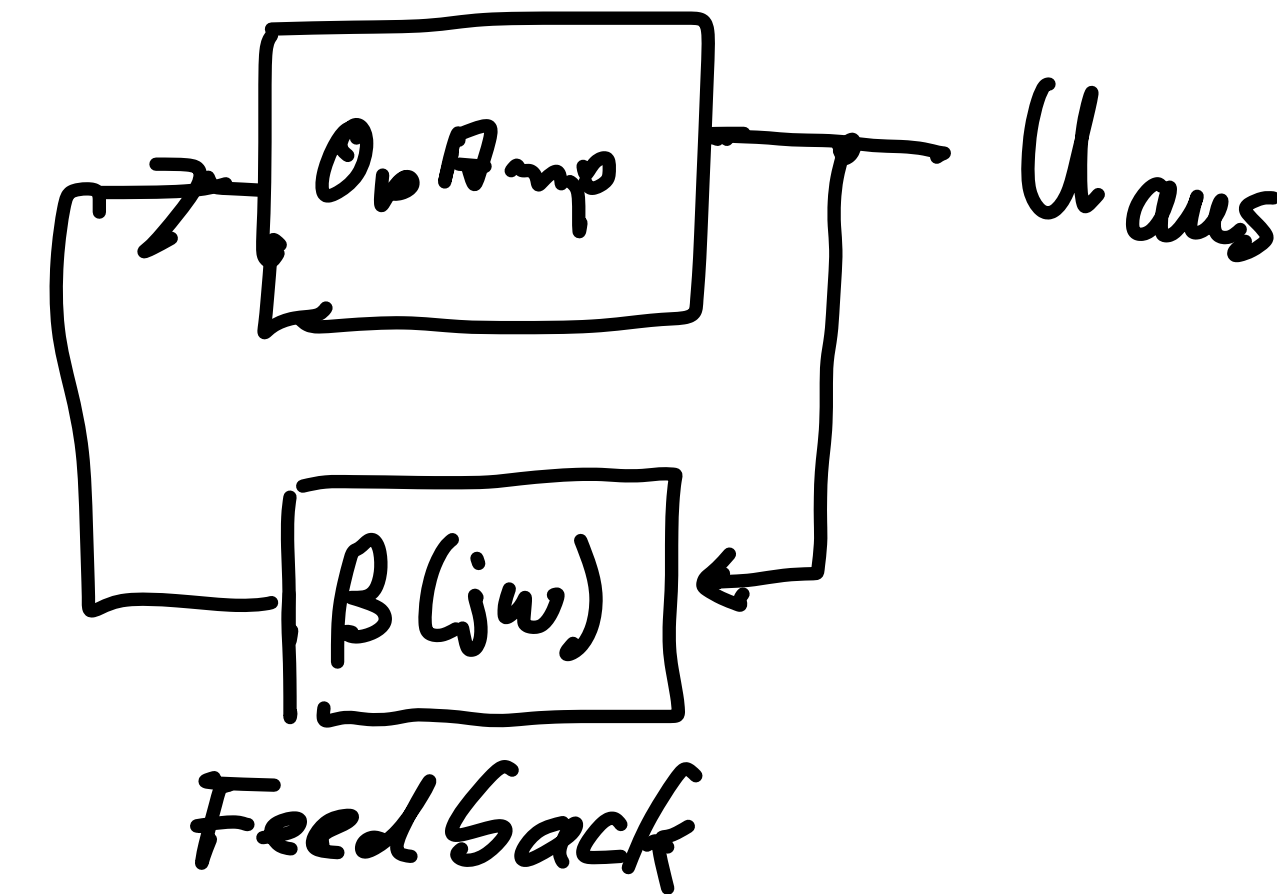
- Loop gain $|\beta A_D| \sim 1$: Here it depends on the phase!

For $\beta A_D \sim 1$: similar to weak feedback,

$\beta A_D \sim -1$: Oscillation (**Barkhausen Criterion**)

Here extreme gain (A diverges), also without further input.

Not good for amplifiers!



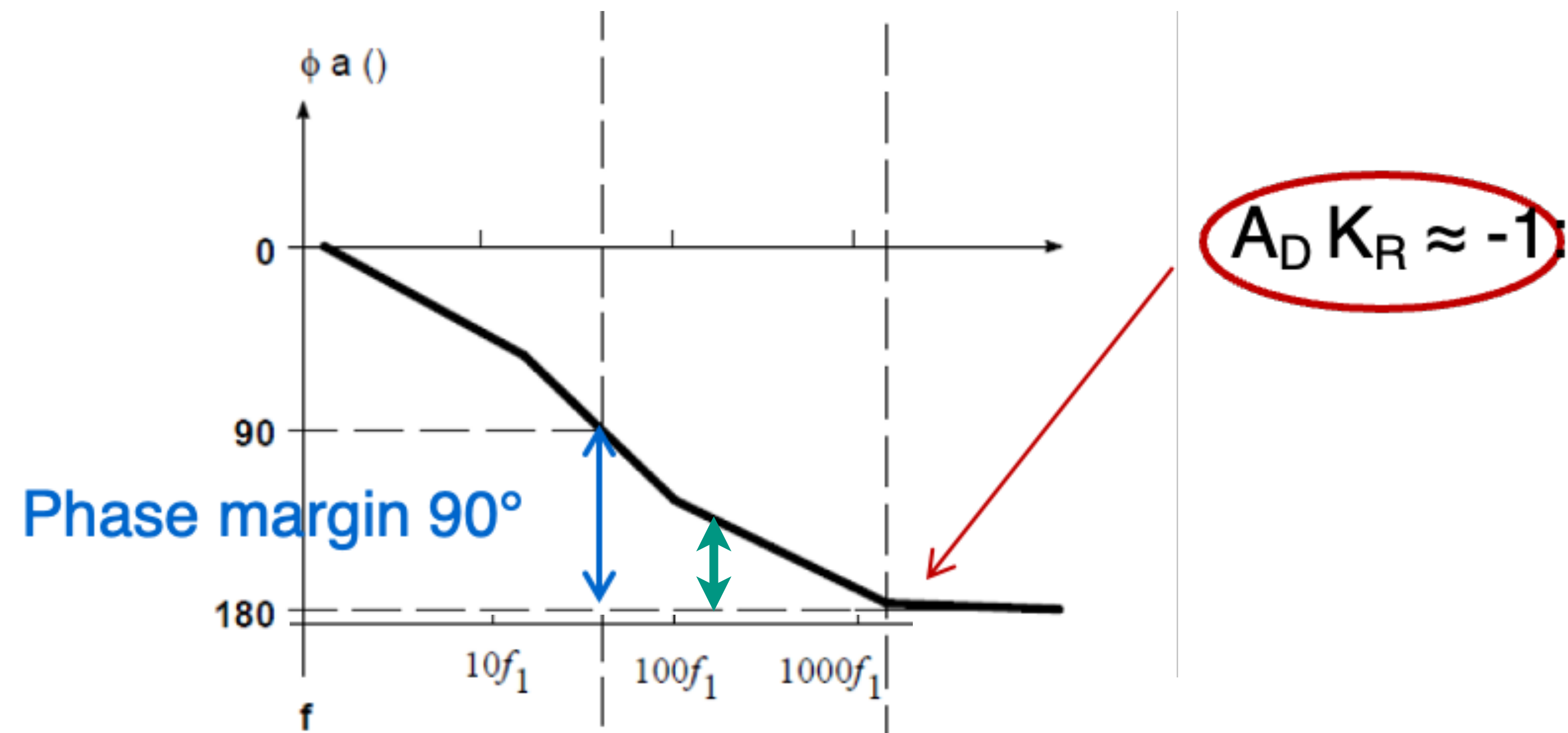
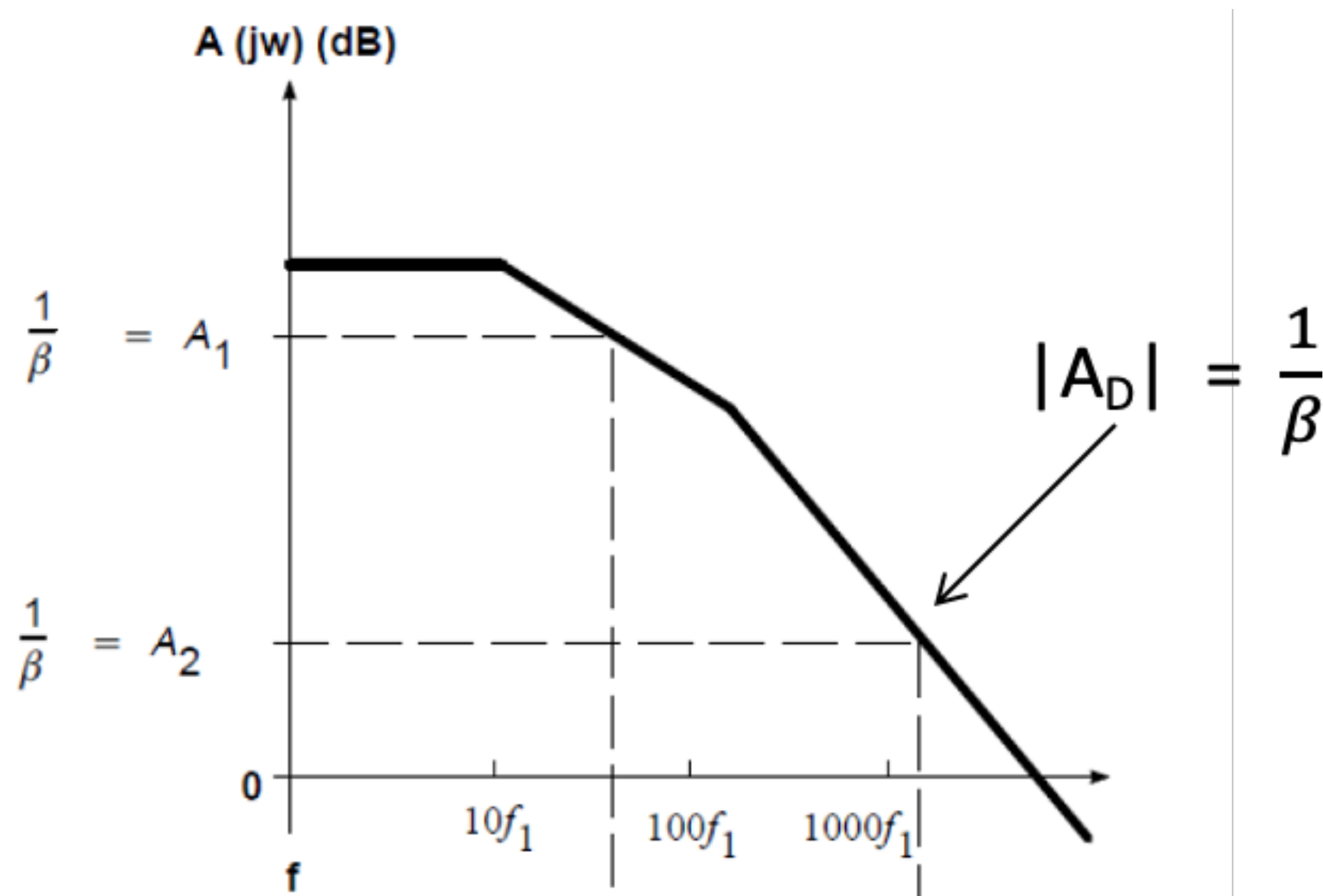
$$U_{aus}(T) = -\beta A_D U_-(t=0) = -\beta A_D U_{aus}(t=0) = +U_{aus}(t=0)$$

Phase Margin of Amplifiers

Phasenreserve

- Since gain and phase shift change with frequency amplifiers can always enter the “danger zone” under certain conditions.

Simplified representation via Bode Plots:



In general: A phase margin of 45 degrees is considered “safe”.
Defines the maximum usable range in frequency.

- OpAmps have many other applications - some examples still later in the lecture, such as DC-DC converters

Electronics for Physicists

Analog Electronics

Chapter 5; Lecture 08 Part II

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Chapter 5

Transistors - Basics

- Bipolar Transistors Introduction
- Basic Transistor Circuits

Overview

1. Basics
2. Circuits with R, C, L with Alternating Current
3. Diodes
4. Operational Amplifiers
- 5. Transistors - Basics**
6. 2-Transistor Circuits
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Bipolar Transistors Introduction

In: Chapter 5: Transistor Basics

- The basis of all modern microelectronics:

An active component - switching and amplification of voltages and currents, can also act as adjustable resistor.

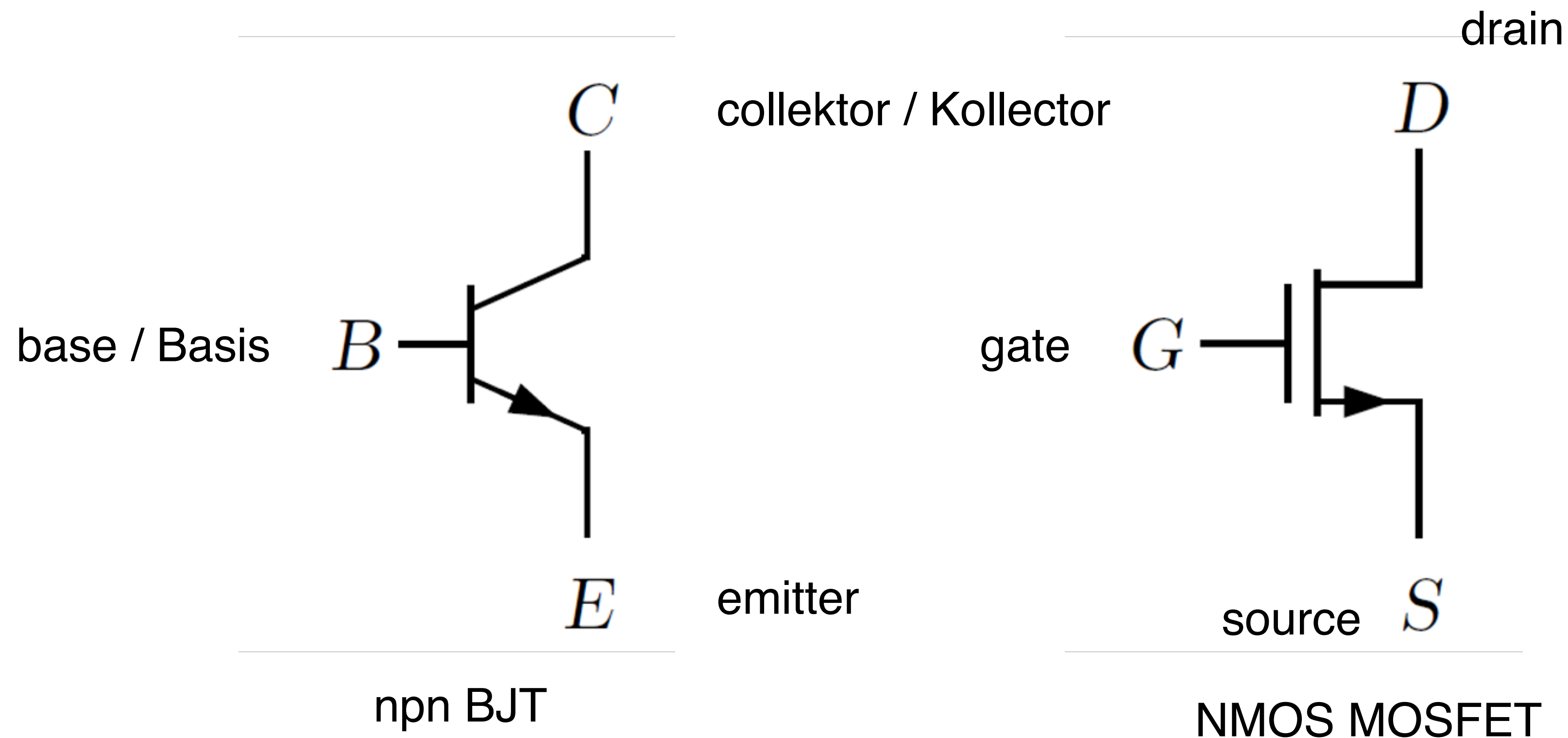
The basic building block of digital logic.

Concept of the field effect transistor (FET) already introduced in 1925 (Patent Lilienfeld, 1925) - technical capabilities back then not sufficient for implementation.

First functional transistor: 1947 by Bardeen, Brattain, Shockley (Bell Labs): Bipolar transistor

Nobel Prize 1956

- Bipolar transistor (BJT)
- Field effect transistors:
 - Junction Field Effect Transistor (JFET)
 - Metal Oxide Semiconductor Field Effect Transistor (MOSFET)



(in principle the body
("Substrat") as 4th connection)

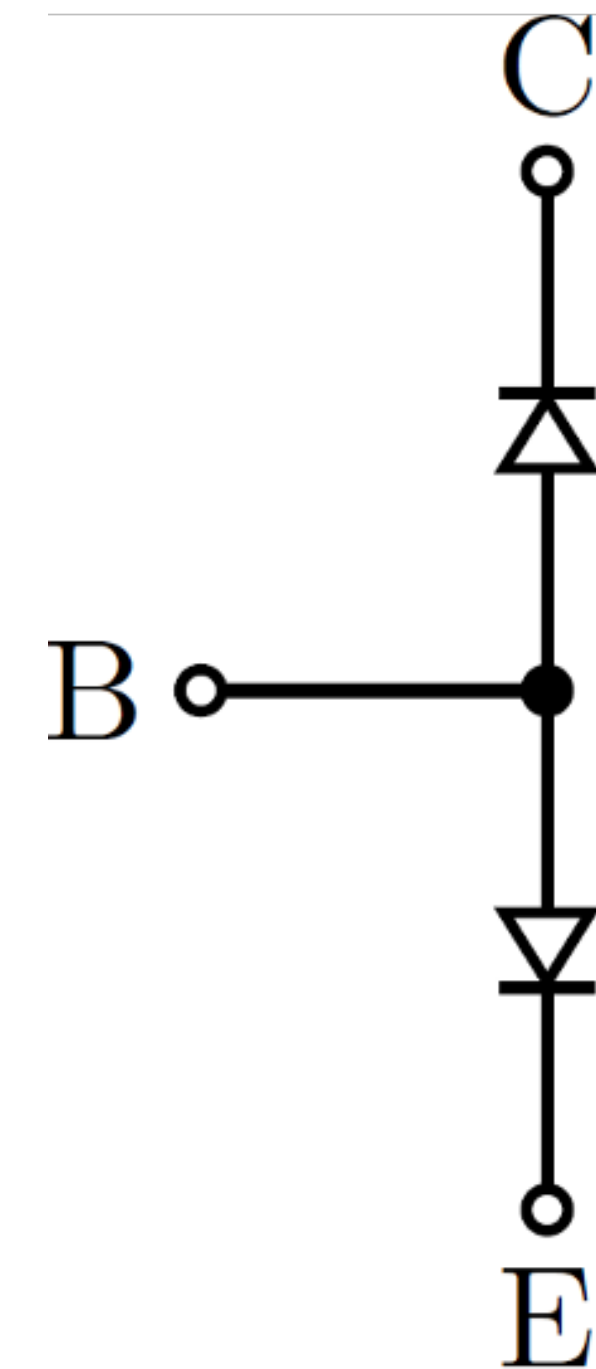
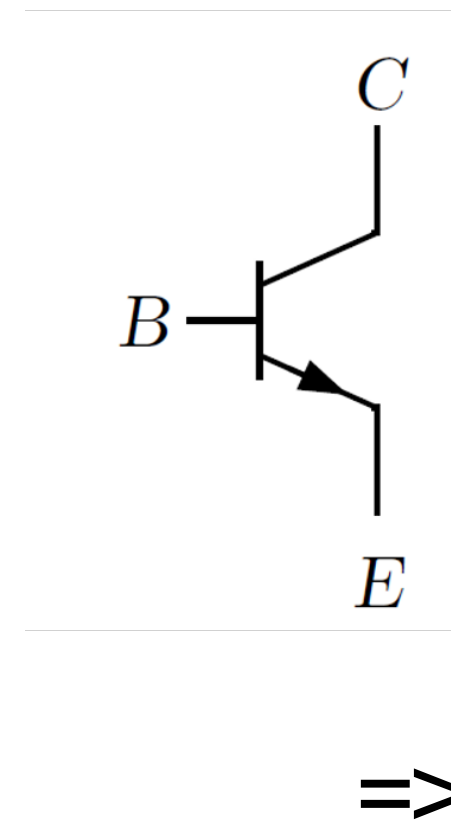
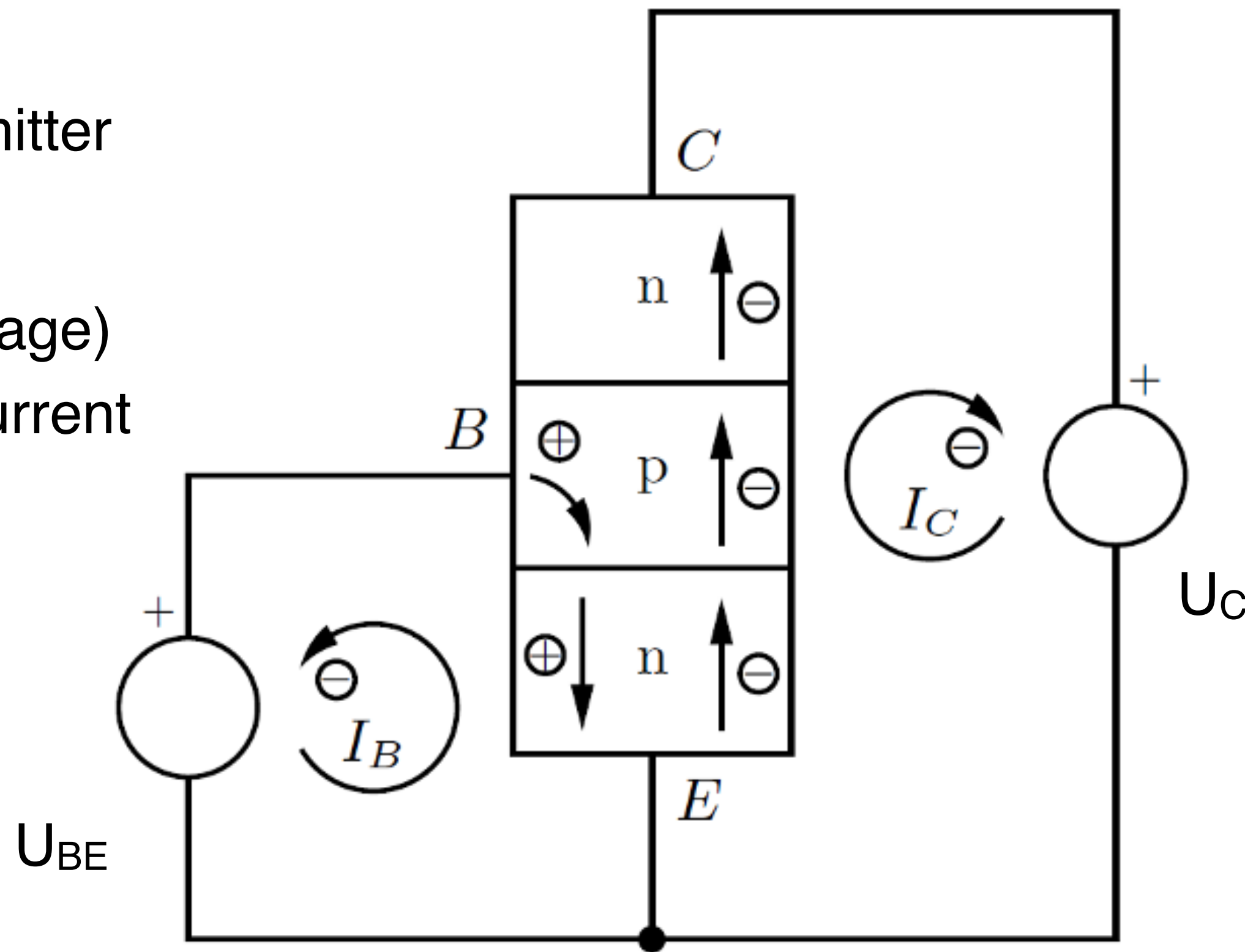
The bipolar Transistor

Basic Principle

npn transistor

Collector-base-emitter

base current (voltage)
drives collector current



Normally: $U_B > U_E$

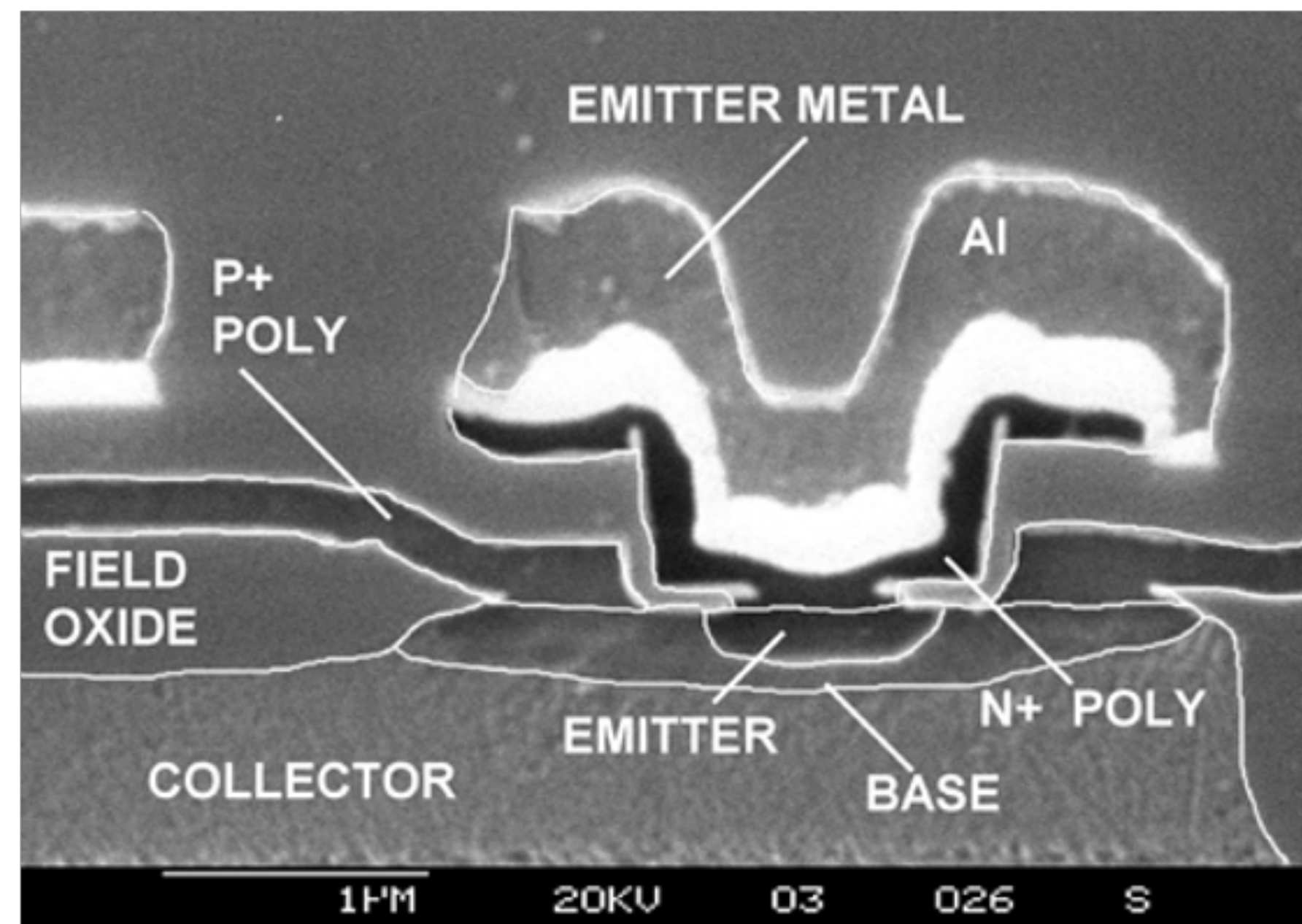
For $U_C > U_B$: collector current:
Electrons from E to B
enable current from E to C

Thin base layer:
< diffusion length of charge carriers

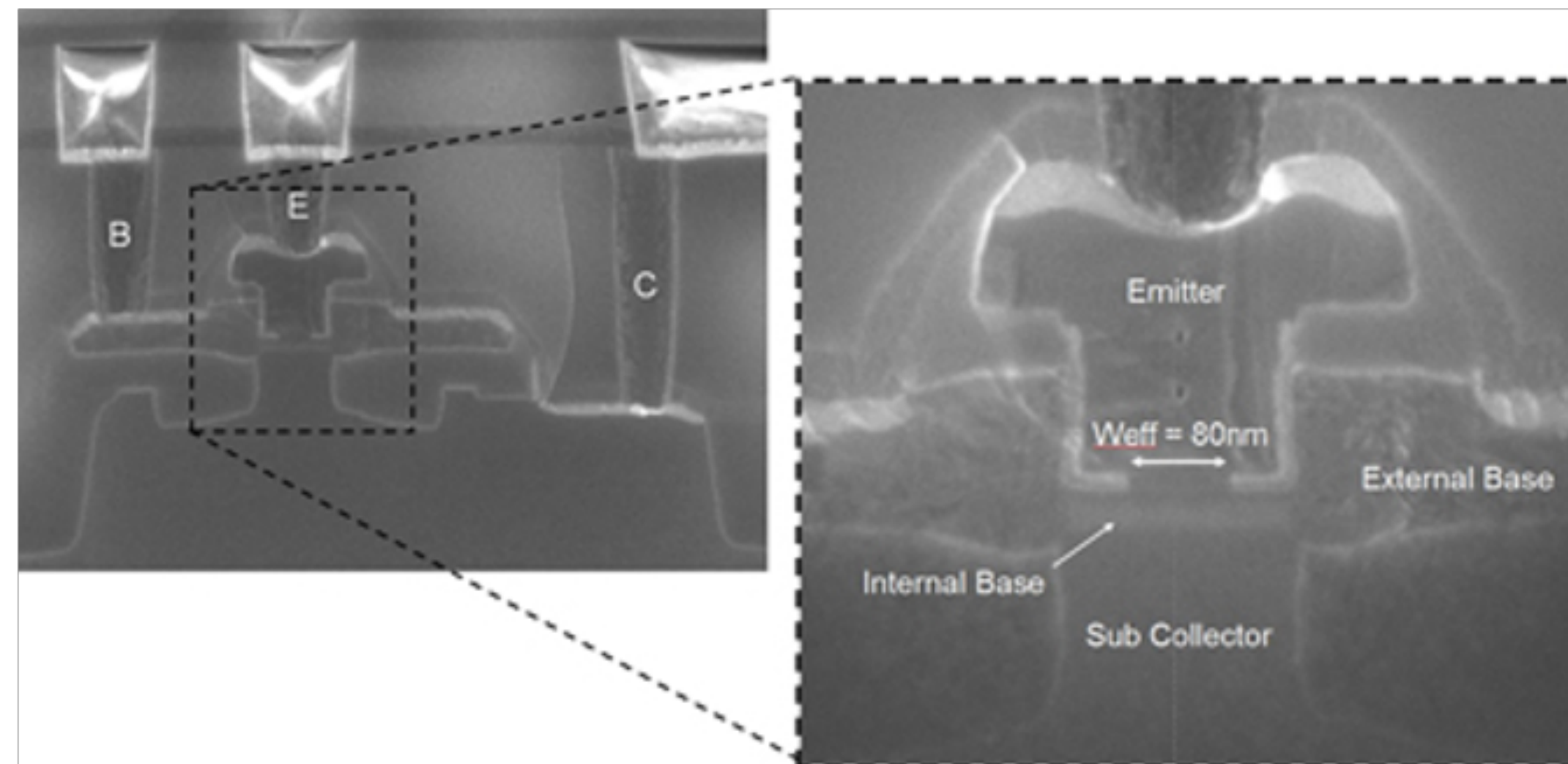
$$\frac{I_C}{I_B} \sim \frac{N_{D_{Emitter}}}{N_{A_{Basis}}} \gg 1$$

The bipolar Transistor

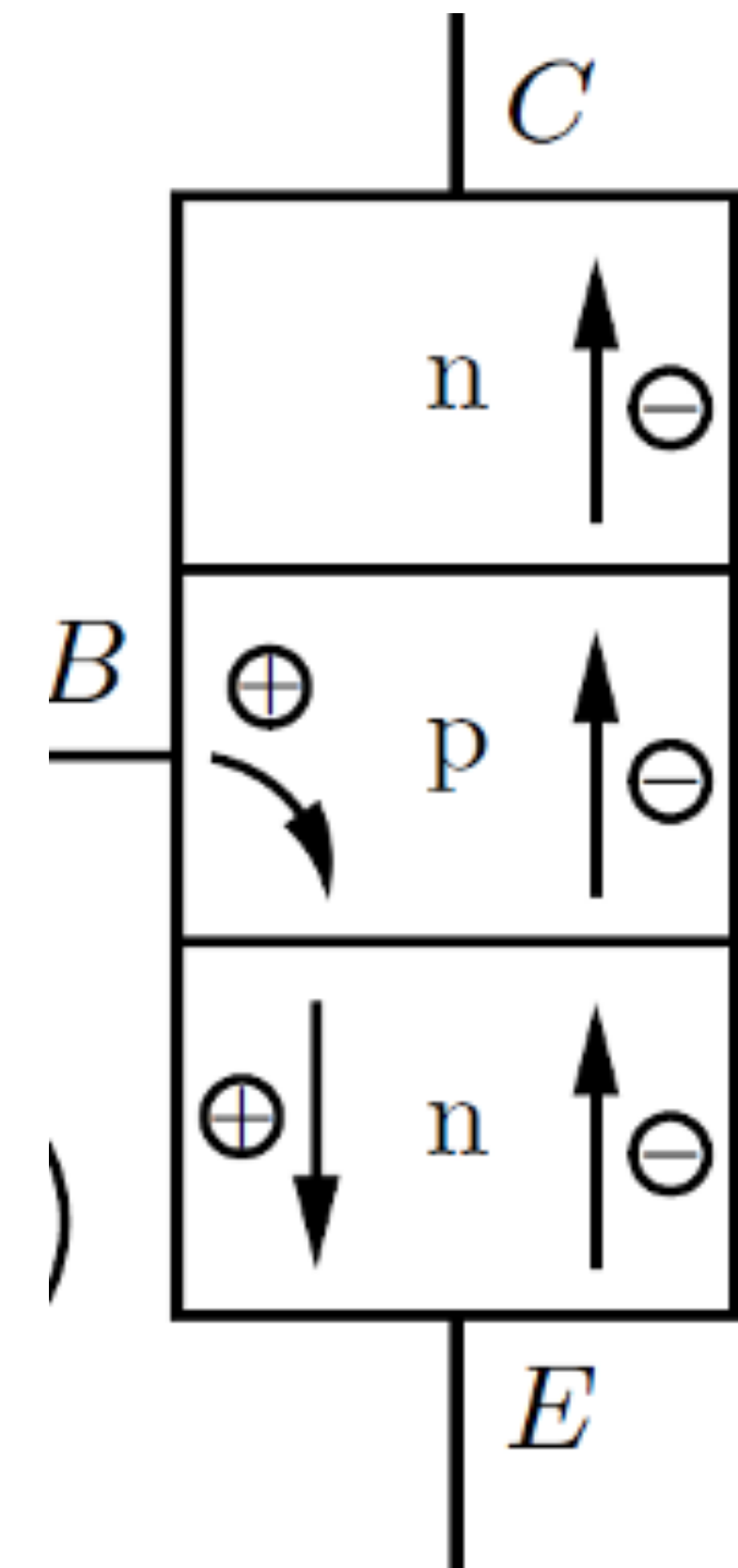
Under the Microscope



Source: Raytheon

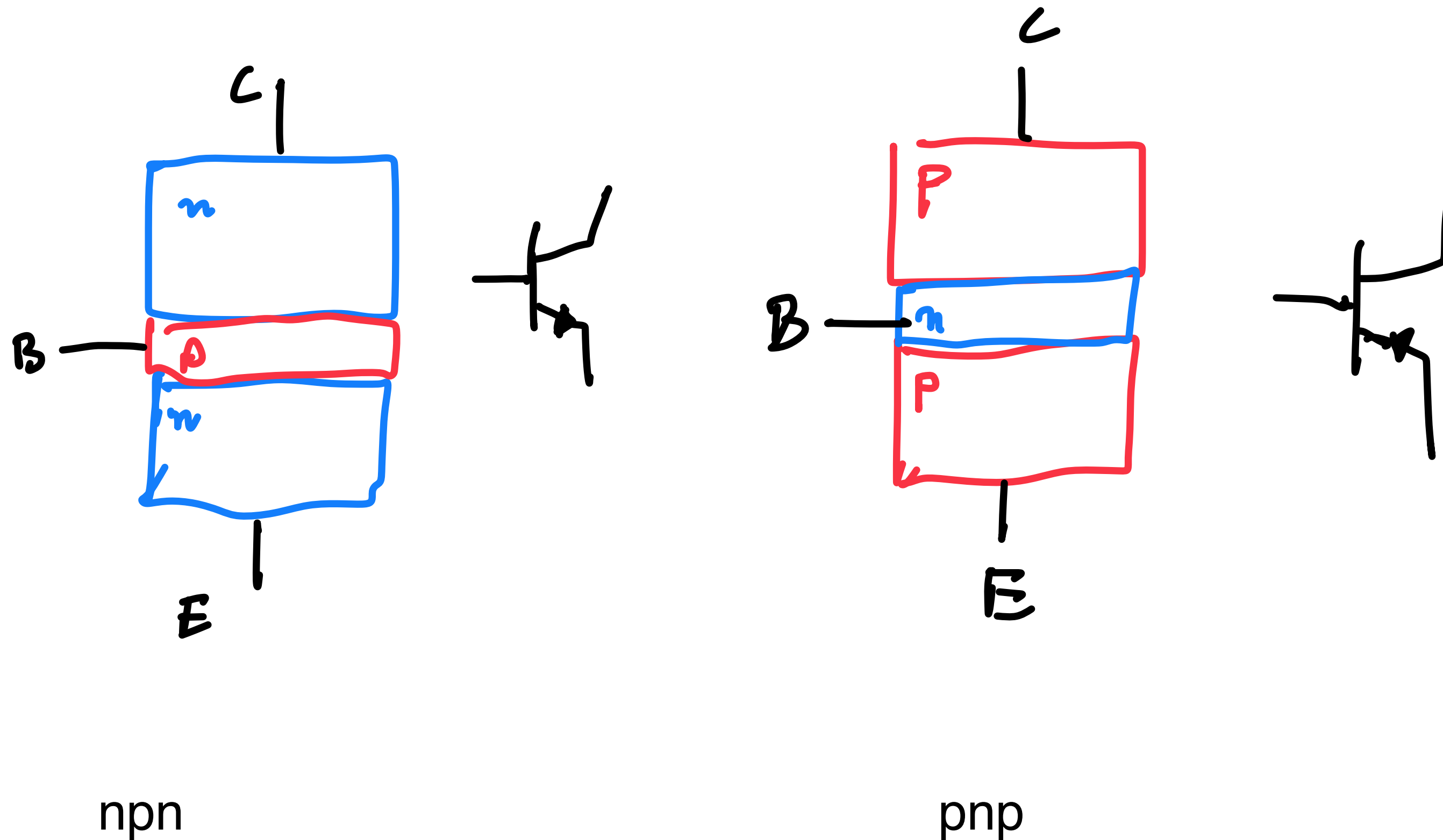


Source: IMEC



The bipolar Transistor

npn and pnp



- Same principle, swapped voltage sign:

- npn: Positive base voltage U_{BE} results in a collector current I_C (via electrons)
- pnp: Negative base voltage U_{BE} results in a collector current I_C (via holes)

=> Due to hole-driven currents a pnp-transistor has long switching times.

nnp are the by far more common transistors.

Moore's Law

The Microelectronics Revolution

Moore's Law: The number of transistors on microchips has doubled every two years

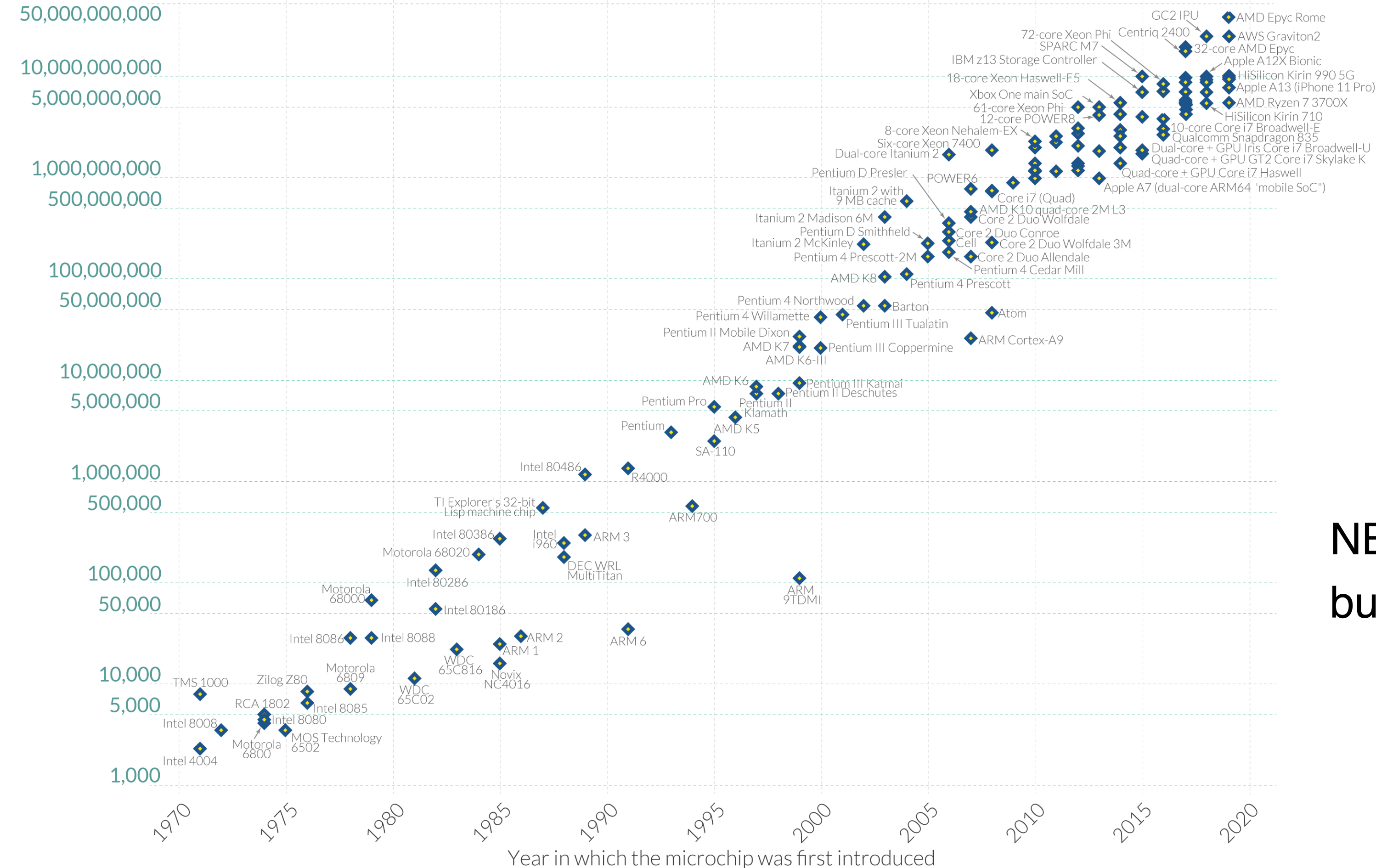
Moore's law describes the empirical regularity that the number of transistors on integrated circuits doubles approximately every two years. This advancement is important for other aspects of technological progress in computing – such as processing speed or the price of computers.

Our World
in Data



Apple M3 Max (2023)
92 G transistors

Transistor count



NB: These are not BJTs,
but FETs

Data source: Wikipedia (wikipedia.org/wiki/Transistor_count)

OurWorldinData.org – Research and data to make progress against the world's largest problems.

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Next Lectures:

Analog 09 - Chapter 05 - Tuesday, December 19

Digital - Thursday, December 21

Time Plan for Next Lectures

A few Changes coming up!

Calender Week	Tuesday	Thursday
45	07.11. Analog	09.11. Digital
46	14.11. Analog	16.11. Digital
47	21.11. Digital	23.11. Analog
48	28.11. Digital	30.11. Digital
49	05.12. Digital	07.12. Analog
50	12.12. Digital	14.12. Analog
51	19.12. Analog	21.12. Digital
2	09.01. Analog	11.01. Analog
3	16.01. Digital	18.01. Digital
4	23.01. Analog	25.01. Digital
5	30.01. Analog	01.02. Digital
6	06.02. Analog	08.02. Digital
7	13.02. Analog	15.02. Digital

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