

# Electronics for Physicists

## *Analog Electronics*

*Chapter 5; Lecture 10*

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**Institute for Data Processing and Electronics**

09.01.2024

*KIT, Winter 2023/24*

## ***Chapter 5***

# **Transistors - Basics**

- Bipolar Transistors Introduction
- Basic Transistor Circuits

### ***Overview***

1. Basics
2. Circuits with R, C, L with Alternating Current
3. Diodes
4. Operational Amplifiers
- 5. Transistors - Basics**
6. 2-Transistor Circuits
7. Field Effect Transistors
8. Additional Topics
  - Filters
  - Voltage Regulators
  - Noise

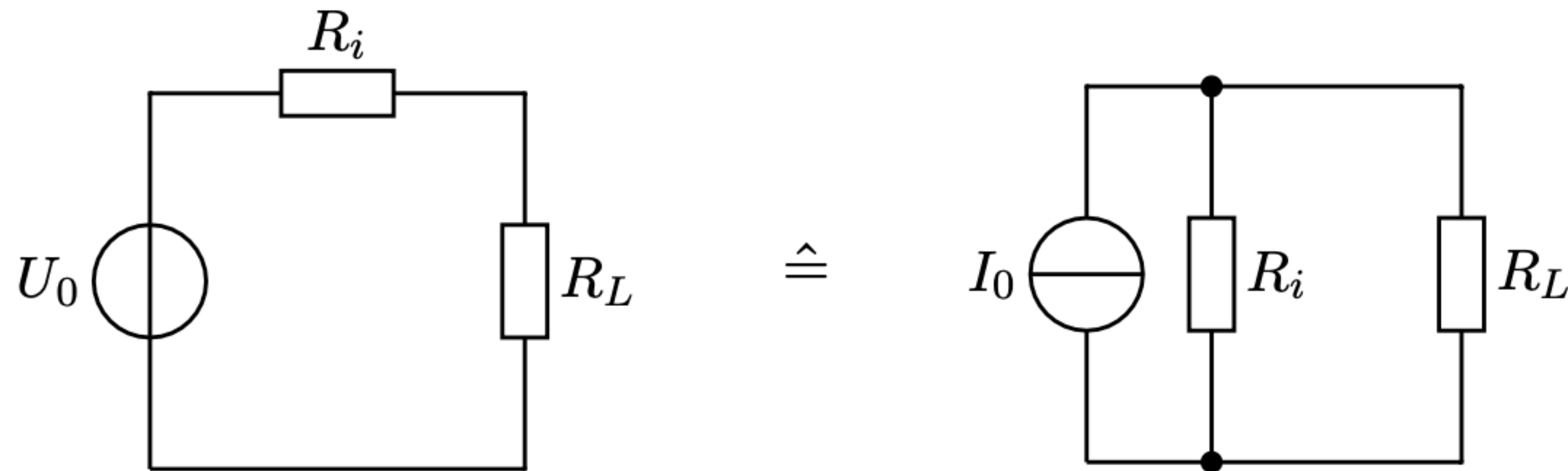
# Basic Transistor Circuits - Cont'd

*In: Chapter 5: Transistor Basics*

# Current Source

*With a single Transistor*

- Reminder:



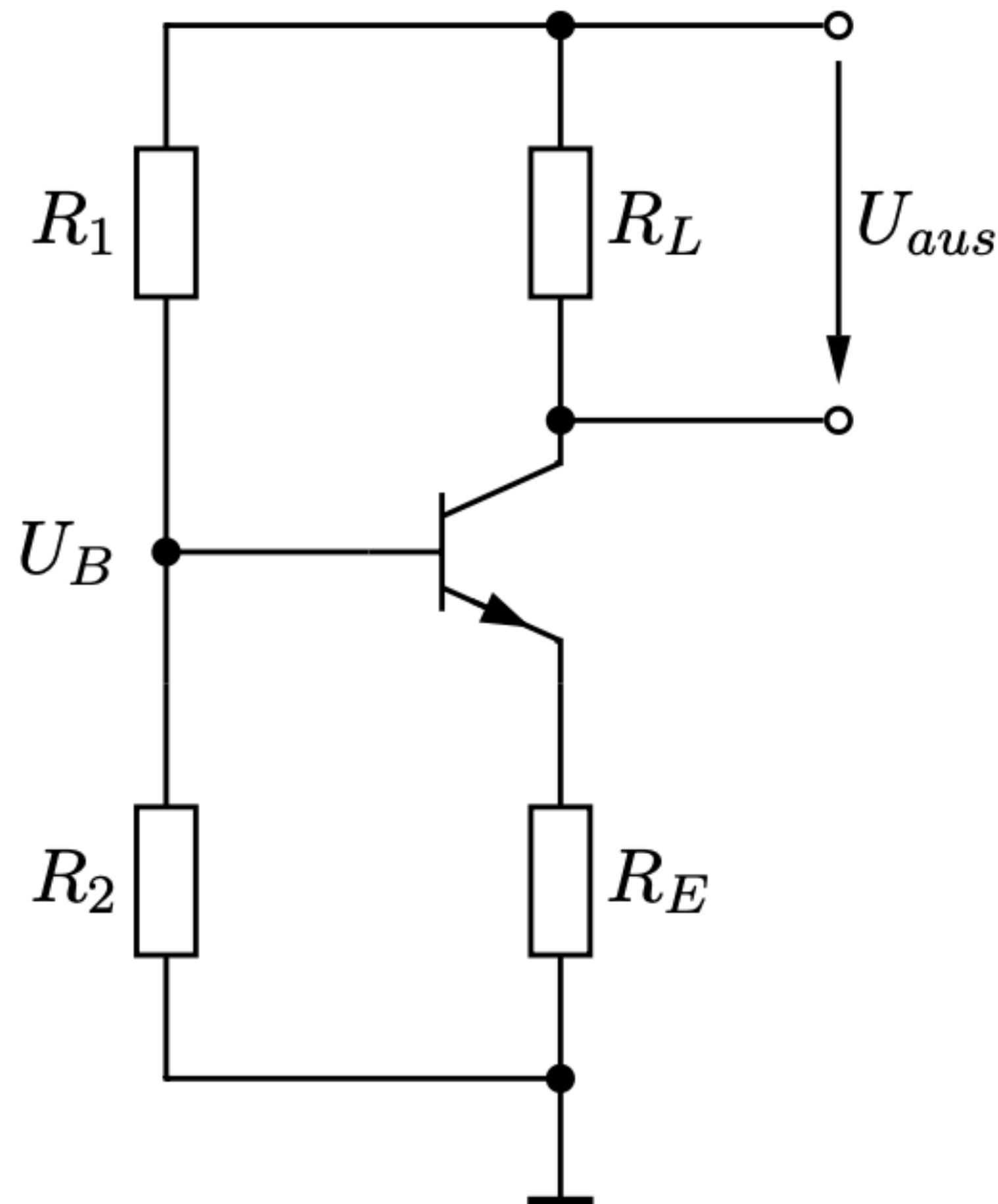
Norton Theorem (Chapter 1):

A circuit (and, with that, also a voltage source) can also be represented by a current source with corresponding internal resistor  $R_i$ .

# Current Source

## With a single Transistor

- The more practical solution: Resistor  $R_i$  of voltage source replaced by transistor!
- Working point adjusted such that differential internal impedance  $dU_{aus}/dI_{aus}$  is large (as desired for current sources)



$$I_L = I_C \approx I_E = \frac{U_E}{R_E} \approx \frac{U_B - 0,7 \text{ V}}{R_E}$$

With that:  $R_1$  and  $R_2$  define  $U_B$ , and in turn  $I_L$

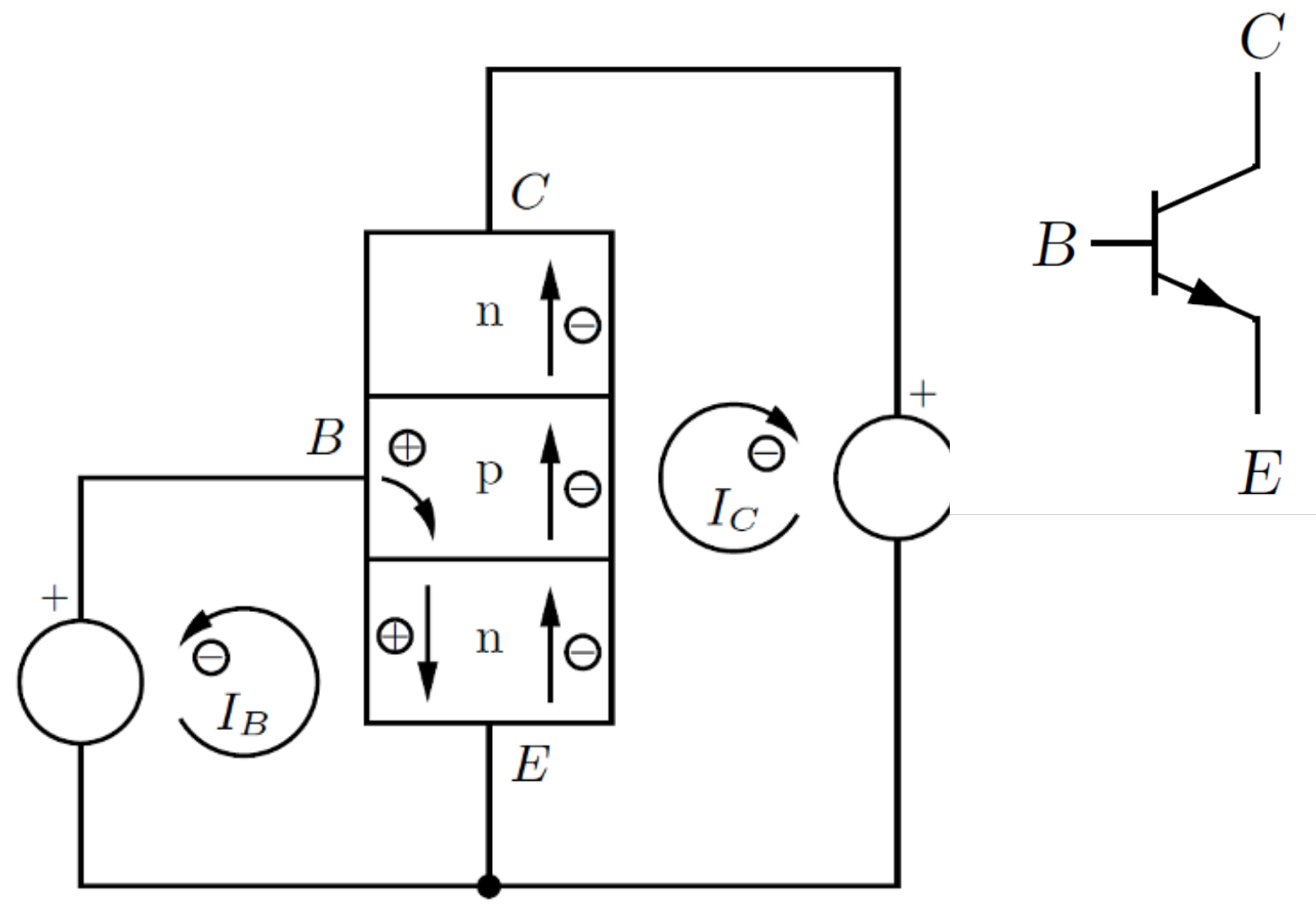
Transistor behavior makes  $I_L$  independent on  $R_L$ :

$$I_L = \frac{U_{CC} - U_C}{R_L} \quad \text{und} \quad I_L = I_C = \beta I_B$$

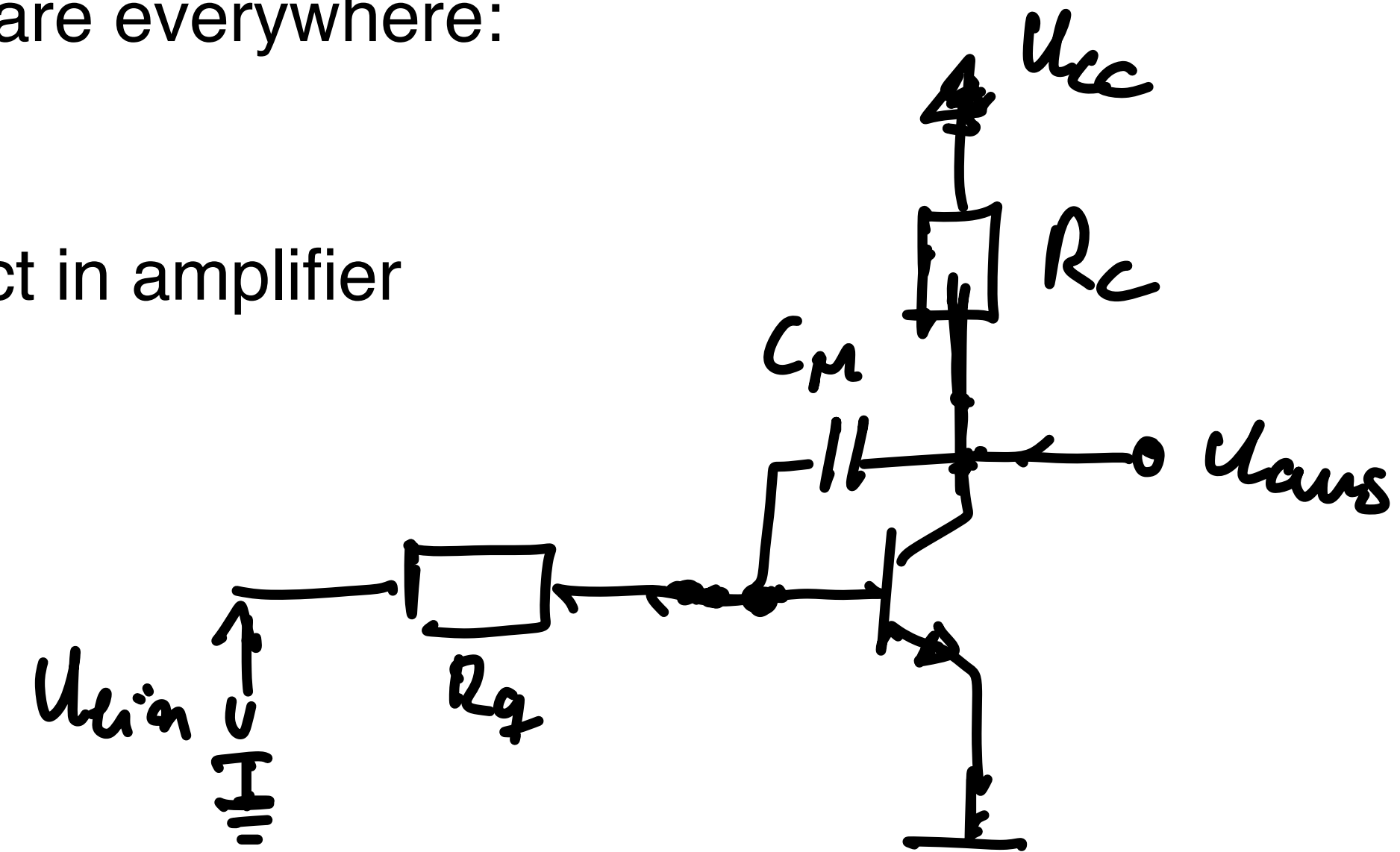
Also relevant: temperature dependence

$$\frac{dI_{aus}}{dT} = - \frac{1}{R_E} \frac{dU_{BE}}{dT} \approx \frac{2}{R_E} \frac{\text{mV}}{\text{K}}$$

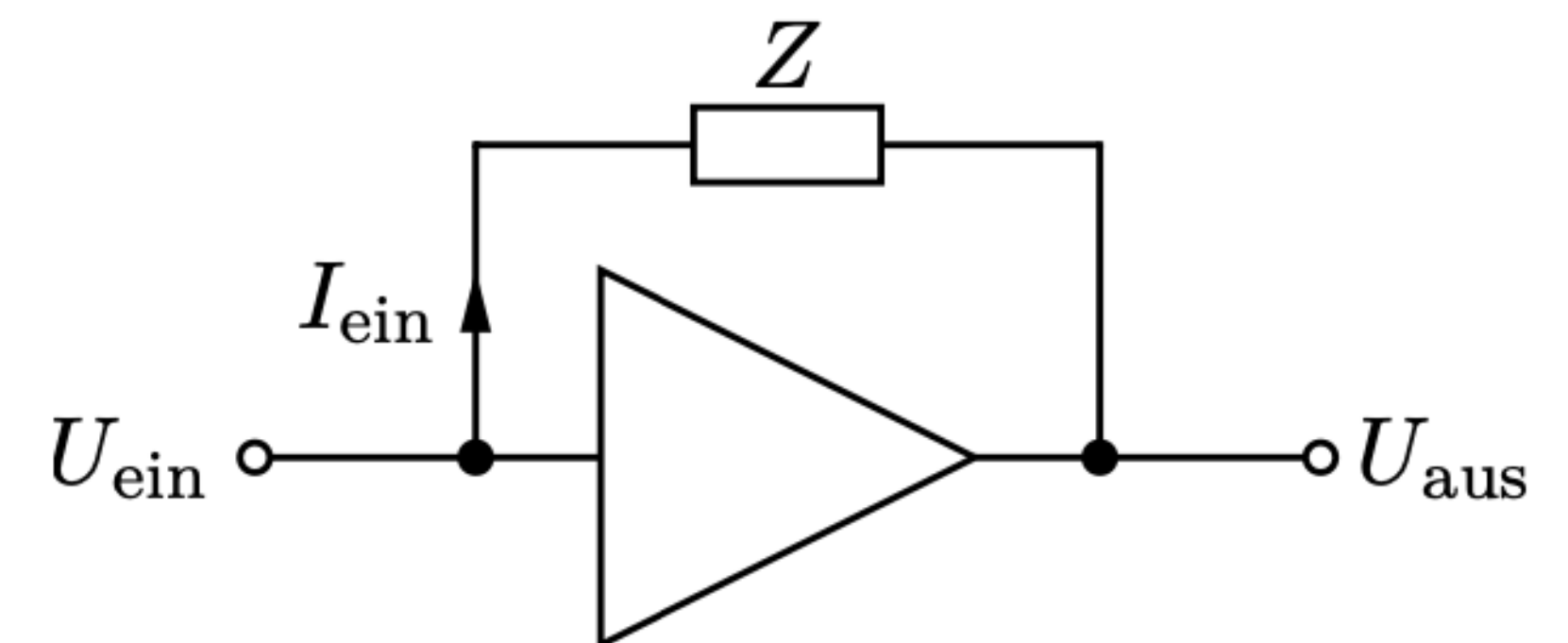
- Capacitances change frequency dependence - and they are everywhere:



Main impact in amplifier circuits:

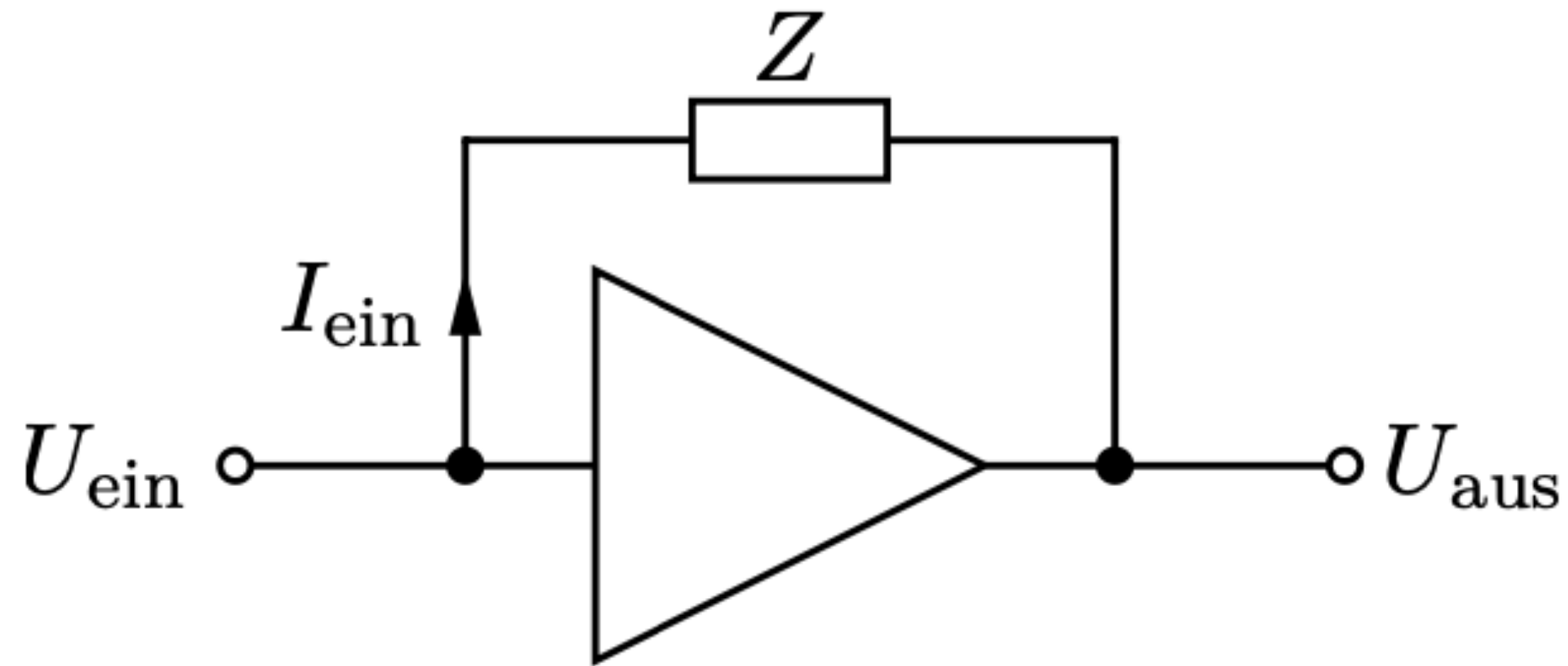


Here: Considering an amplifier with negative feedback.



# The Miller Effect

## Inverting Amplifier



- The impact of feedback

$$I_{ein} = \frac{U_{ein} - U_{aus}}{Z} = \frac{U_{ein} + A U_{ein}}{Z} = U_{ein} \frac{A + 1}{Z}$$

(A: gain of the circuit)

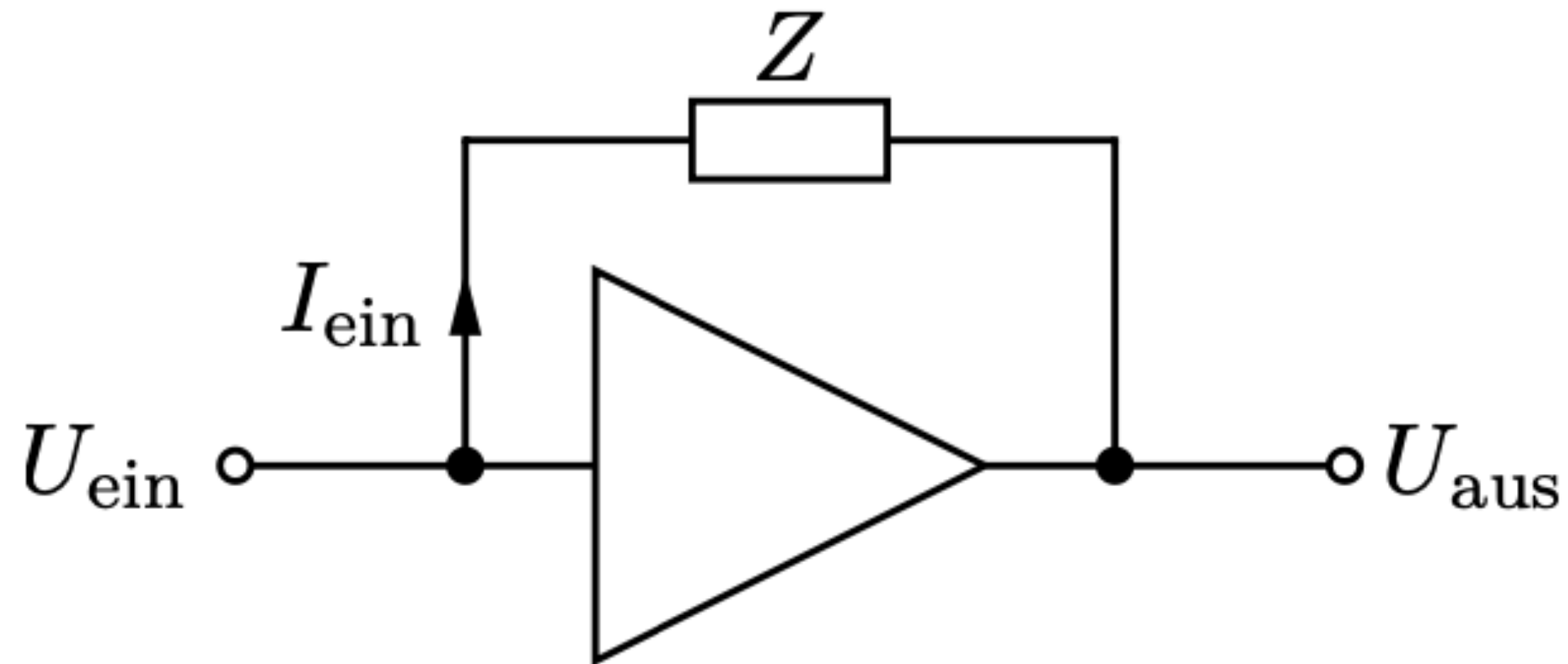
With this: input impedance of the circuit:

$$Z_{ein} = \frac{dU_{ein}}{dI_{ein}} = \frac{Z}{A + 1} \quad \text{and} \quad Z = \frac{1}{j\omega C} \quad \Rightarrow \quad Z_{ein} = \frac{1}{j\omega C (A + 1)}$$



# The Miller Effect

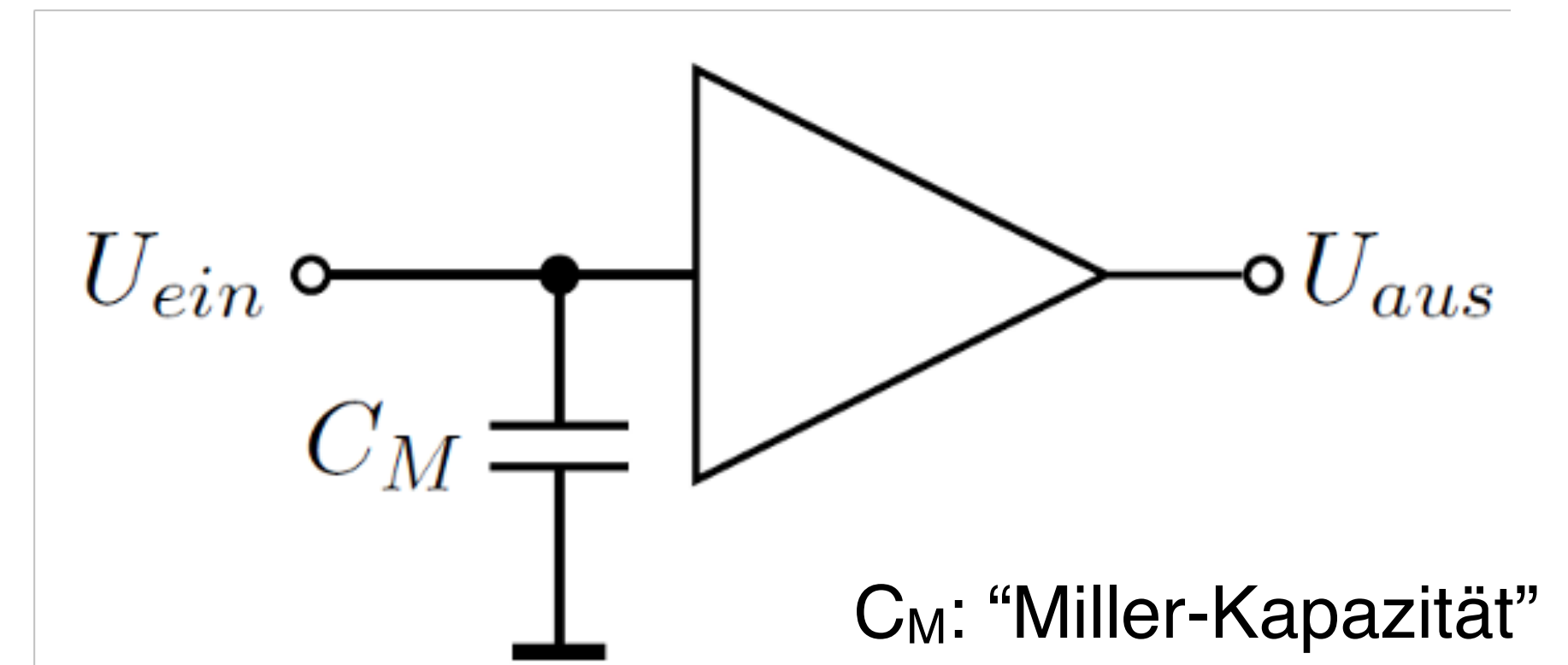
## Inverting Amplifier



$$Z_{\text{ein}} = \frac{1}{j\omega C (A + 1)}$$

Consequences:

- Reduction of input impedance
- Effective increase of input capacitance by gain factor: Often several orders of magnitude (from a few pF to many)



Result: Low pass with time constant  $\tau = R_s C_M$

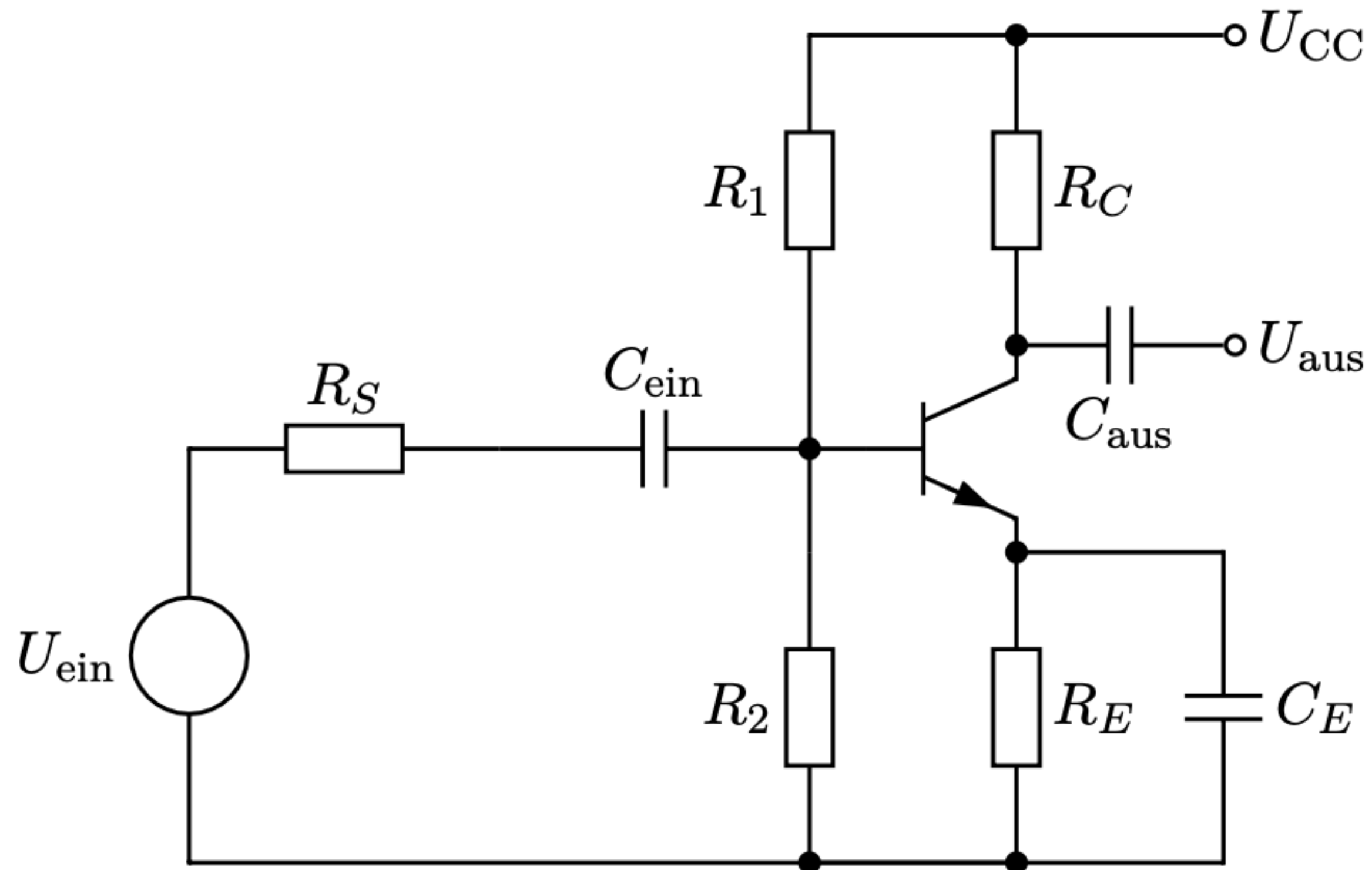
$R_s$ : internal resistance of signal source

=> "slow down" of the amplifier



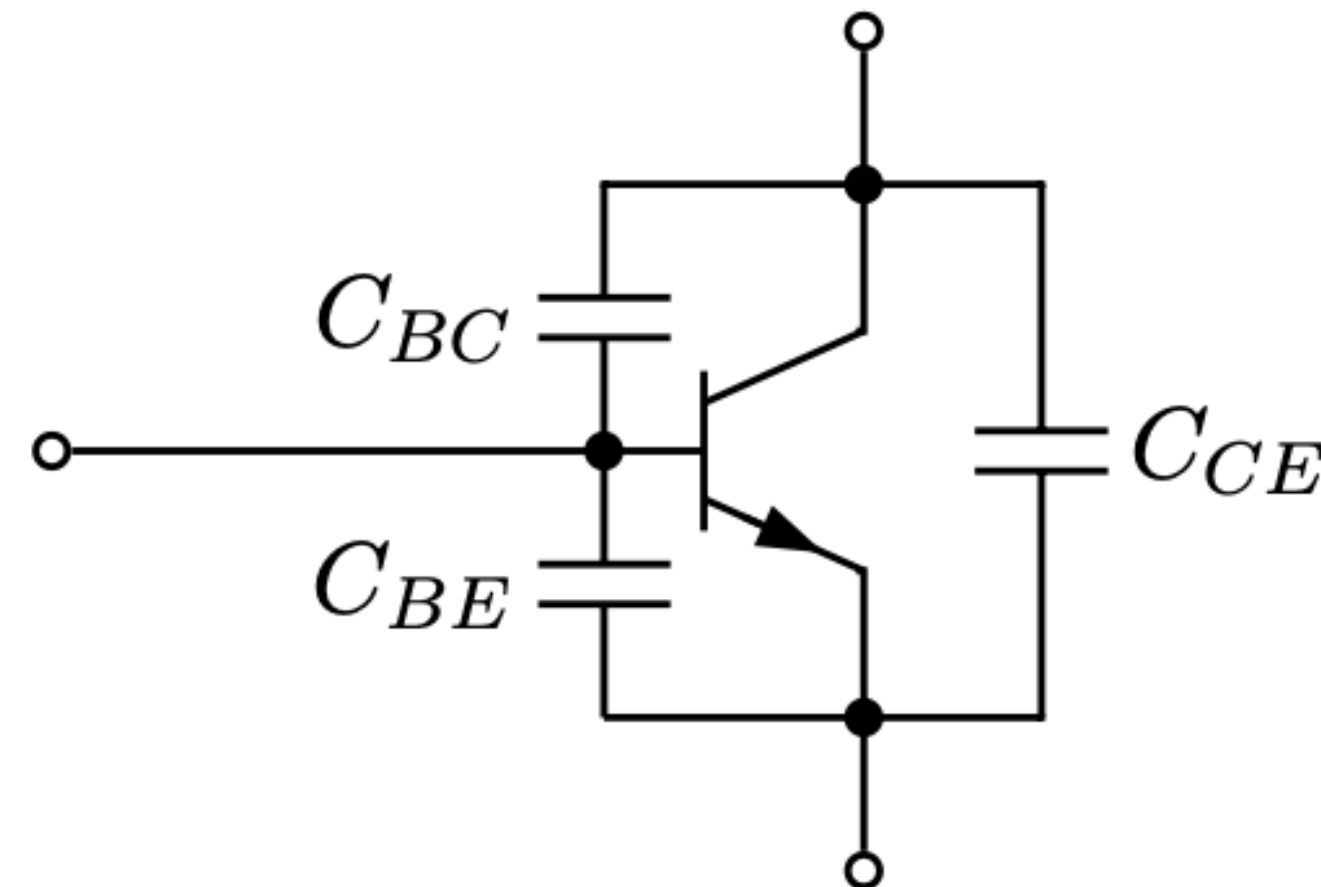
# Frequency Dependence of Amplifiers

## 1-Transistor Amplifier



- Illustration (of a few) capacitances in a typical common emitter amplifier

On top: internal capacitances of the transistor



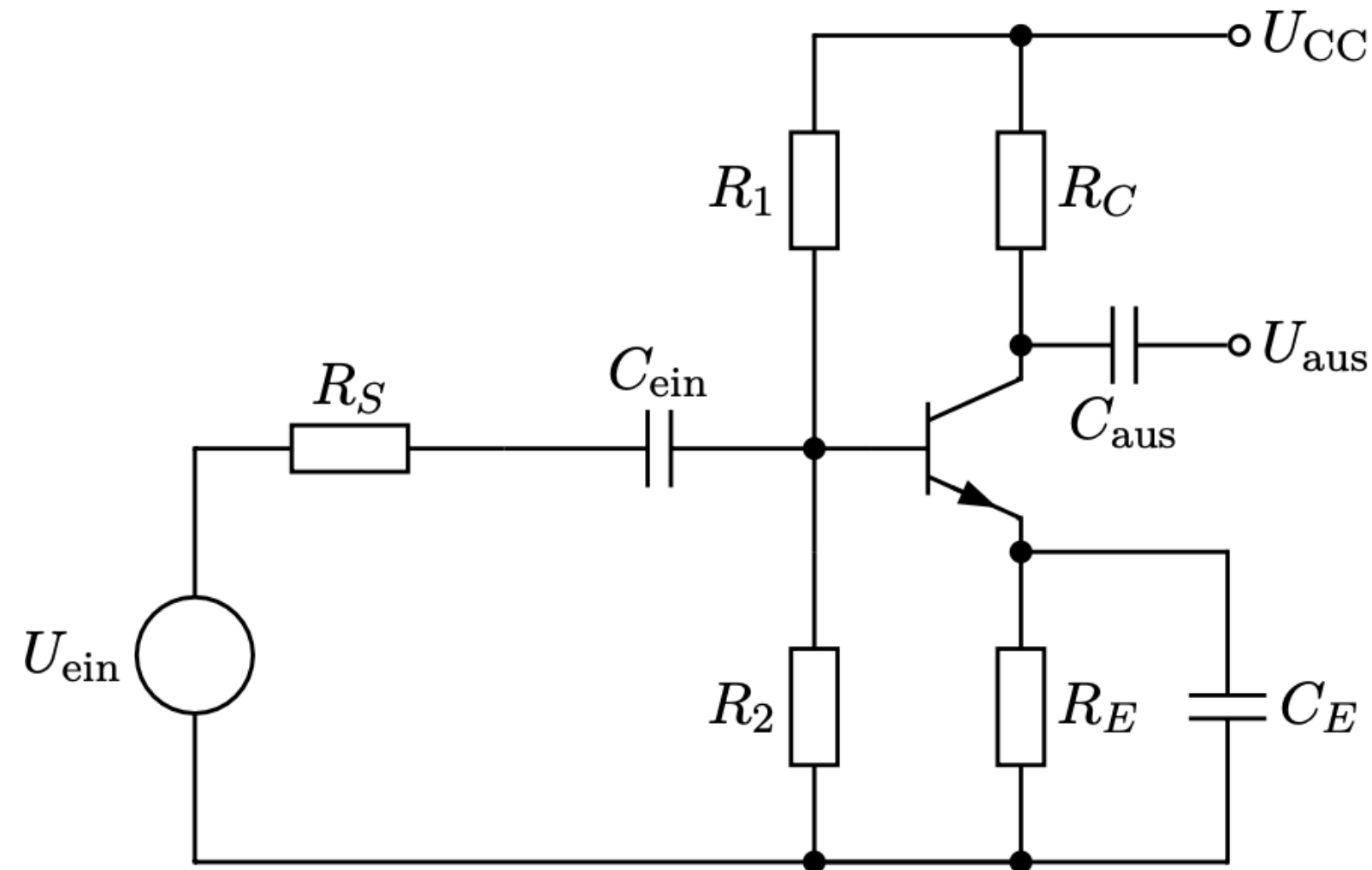
normally small compared to “external” capacitances

*But:* Miller effect for  $C_{BC}$ !

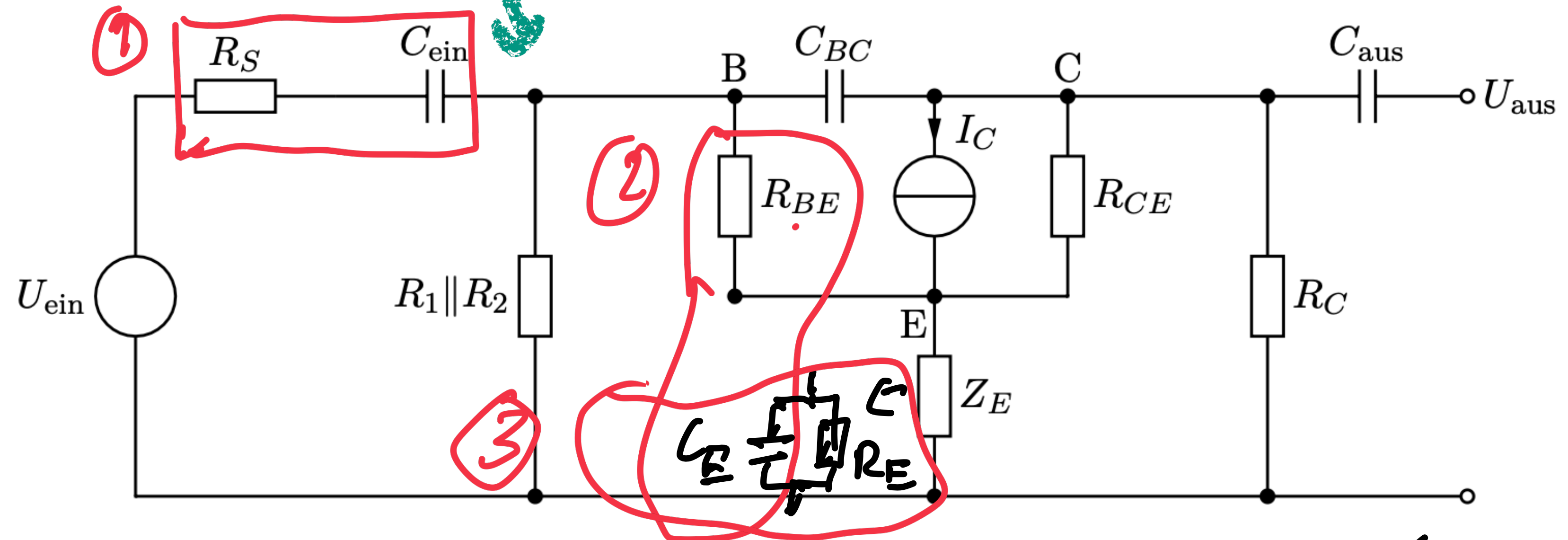
# Frequency Dependence of Amplifiers

## 1-Transistor Amplifier

- Different critical frequencies due to external and internal capacitances and resistors.



Small-signal equivalent circuit



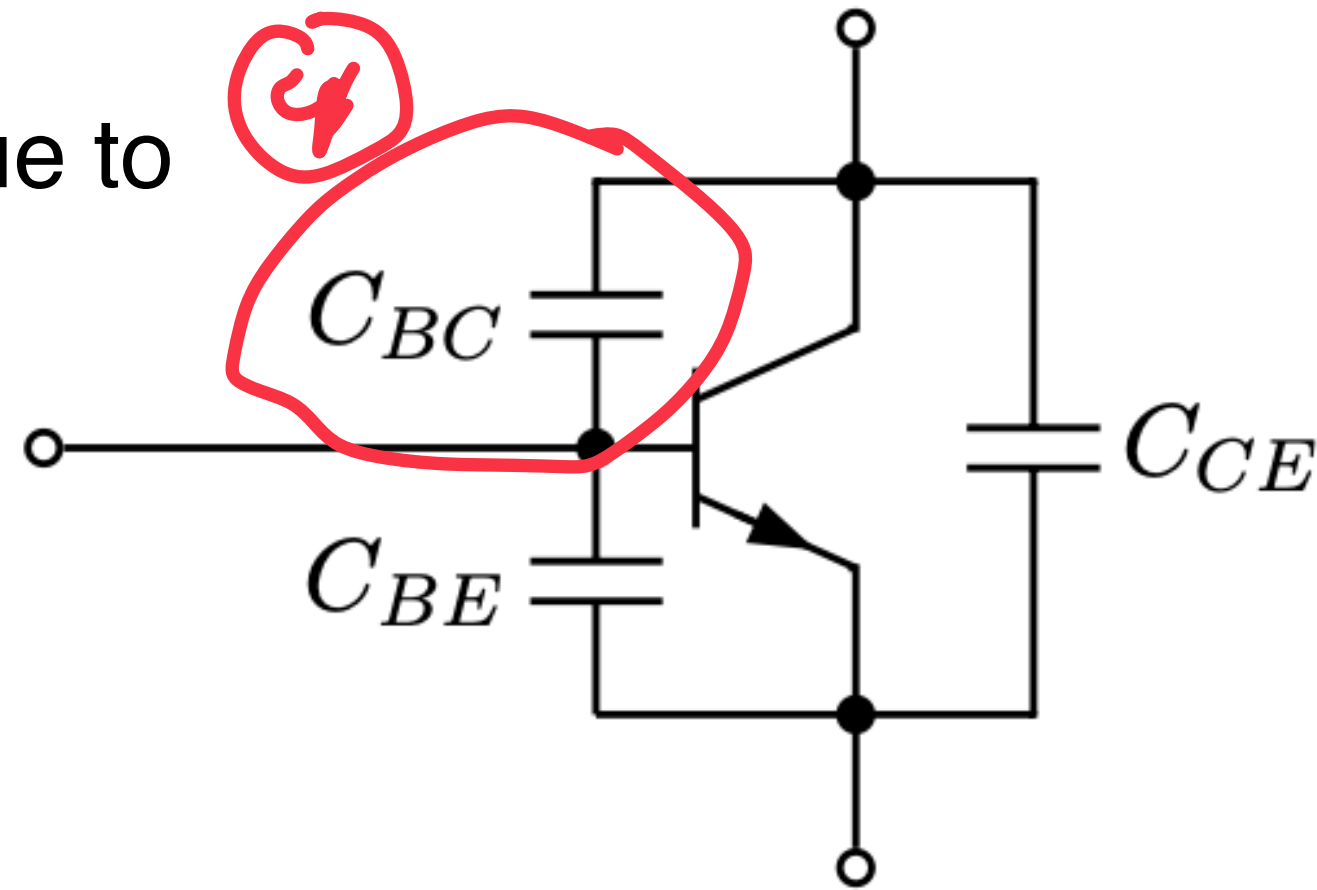
- (1) High pass:  $f_1$
- (2) Low pass:  $f_2$
- (3) High pass:  $f_3$

$$Z_E \approx R_E \parallel \frac{1}{j\omega C_E}$$

# Frequency Dependence of Amplifiers

## 1-Transistor Amplifier

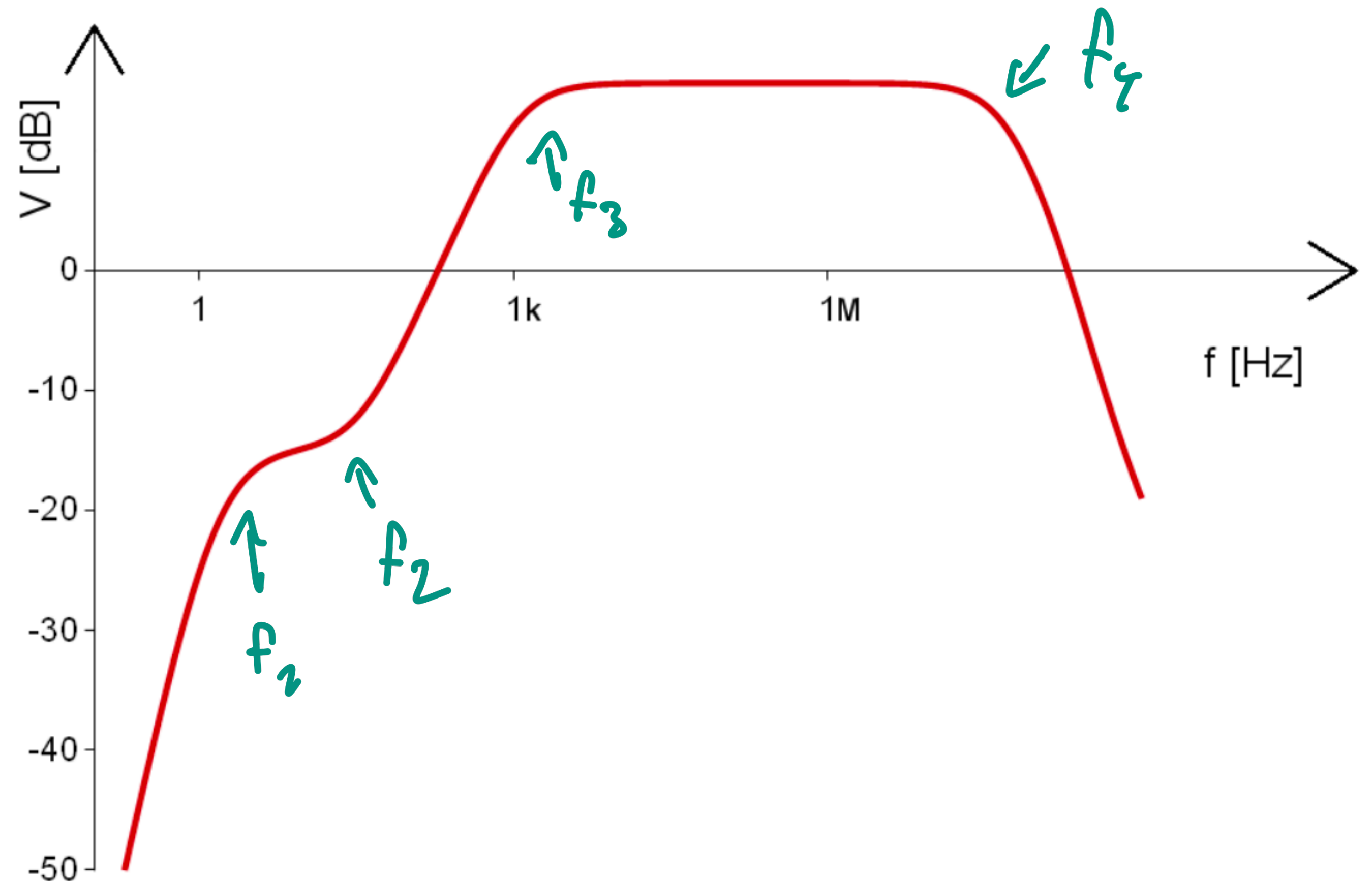
(4) Low pass due to Miller effect



Results in:

- (1): High pass on input -  $f_1$
- (2): Low pass on input/emitter -  $f_2$
- (3): High pass in feedback -  $f_3$
- (4): Low pass between base and collector -  $f_4$

- Different critical frequencies due to external and internal capacitances and resistors.



# Electronics for Physicists

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*Chapter 6; Lecture 10 Part II*

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# ***Chapter 6***

## **2-Transistor Circuits**

- Current Mirrors
- Amplifier Circuits

### ***Overview***

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# Current Mirrors

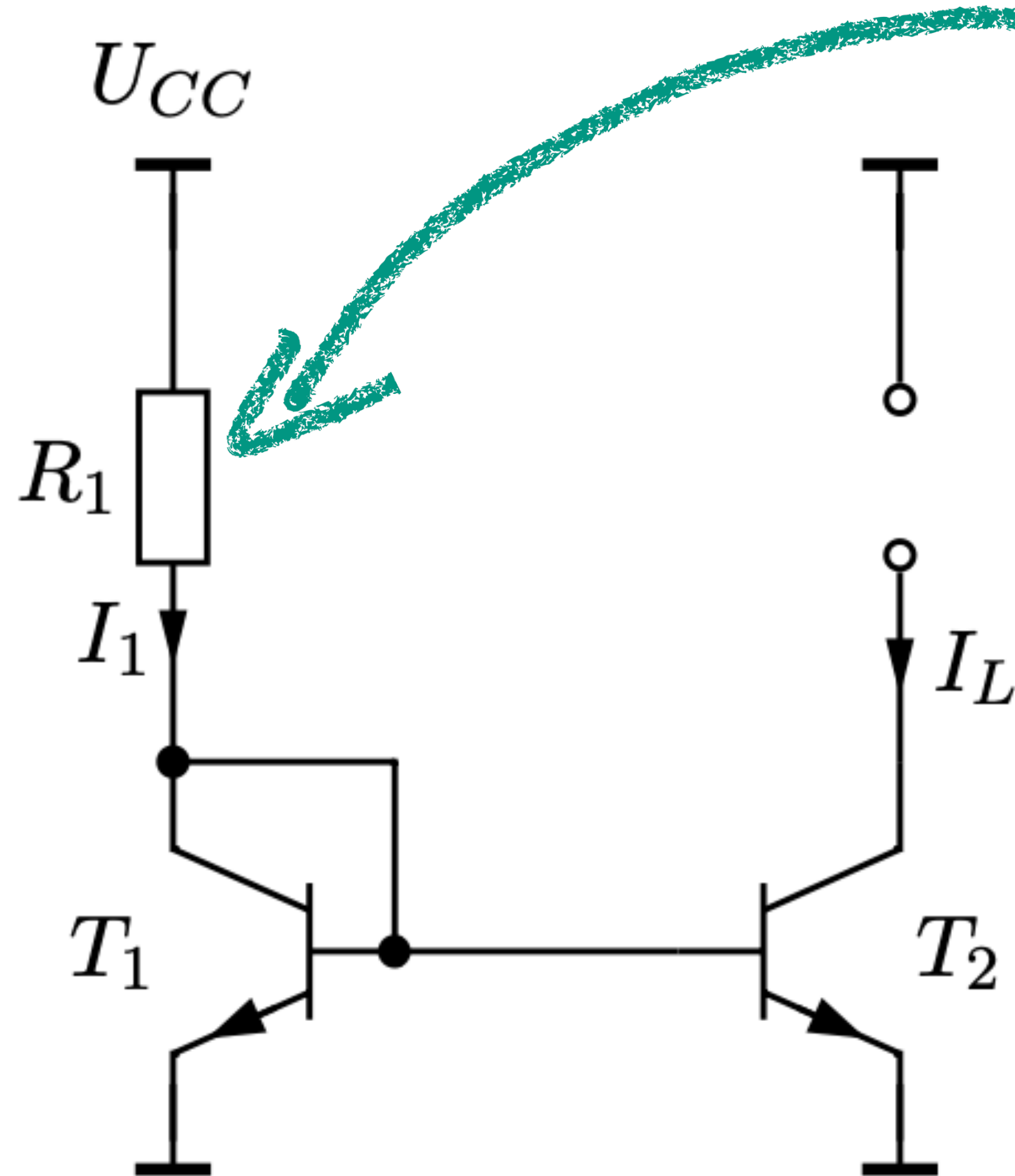
*In: Chapter 6: 2-Transistor Circuits*



- A circuit which can derive a current from a reference current:  
***A current-driven current source***
  - Copying or scaling (multiplying, dividing) of the input current
- Applications:
  - Bias currents for transistor circuits to set working points
  - Active loads
  - “Copy” of current signals for different circuit elements ...
- Desired properties:
  - Linearity: Output current precisely follows input current
  - High output impedance (= good current source)
  - Large dynamic range (depending on application)

# Current Mirror

With Resistor



Defines the current:

$T_1$ : B and C connected  $\Rightarrow$  diode (BE)!

$$\text{defines: } I_1 = \frac{U_{CC} - 0.7 \text{ V}}{R_1}$$

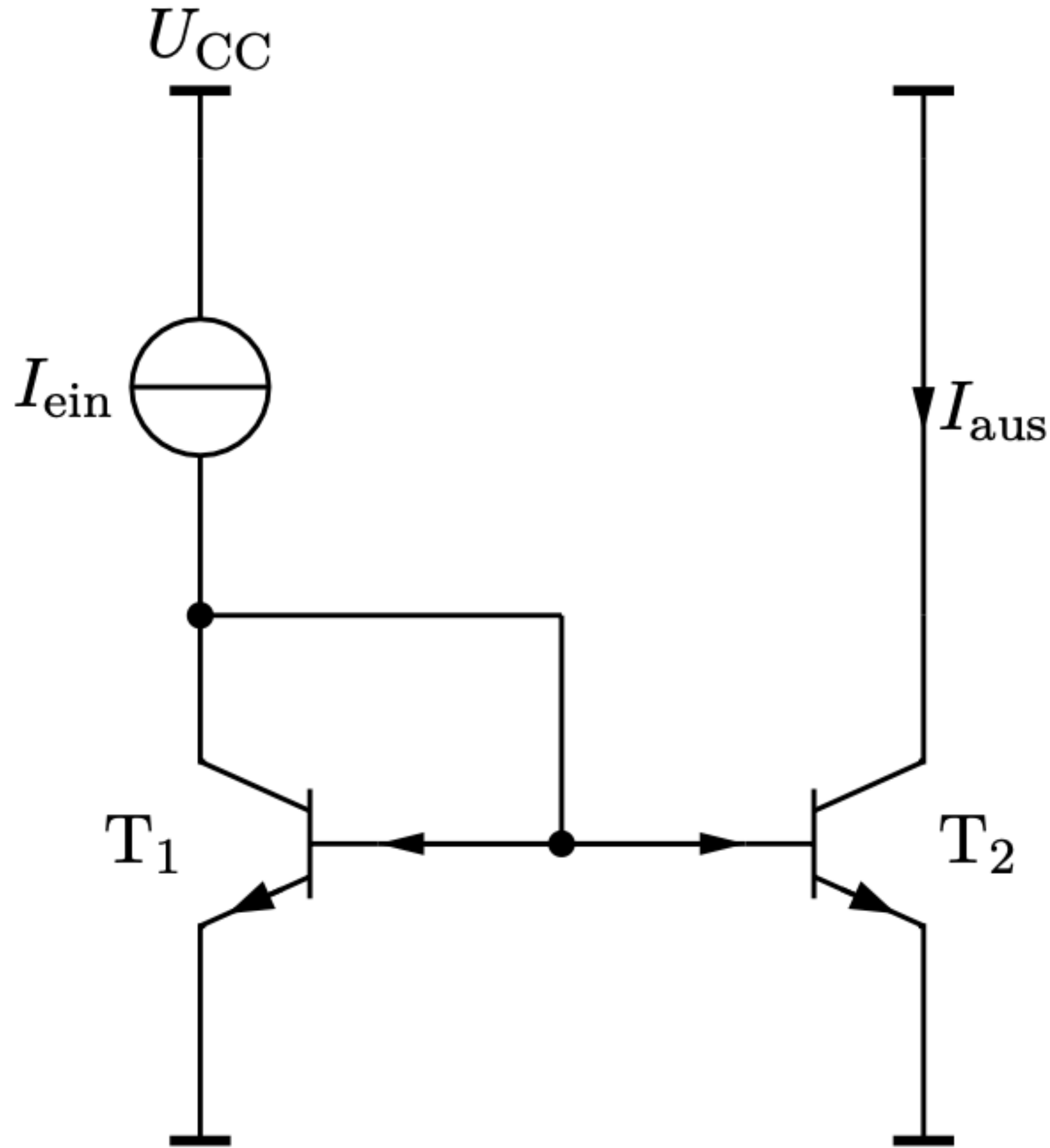
In addition:  $U_{BE1} = U_{BE2}$

Remember (Ch 5):  $I_C = \beta I_S (e^{\frac{U_{BE}}{U_T}} - 1)$

$\Rightarrow$  For identical transistors  $T_1$  and  $T_2$ :  
Same collector current  $I_C$

And:  $I_{C1} = I_1 - I_{BE1} - I_{BE2}$

resulting in:  $I_L = I_1 - 2 I_{BE}$



- Here: With current source instead of resistor - the more general application.
- Identical consideration!

$$I_{\text{aus}} = I_{C2} = I_{\text{ein}} - 2 I_{BE} = I_{\text{ein}} - 2 \frac{I_C}{\beta}$$

Consequences:

$U_L$  is defined by  $R_L$  - within the limits set by the operational parameters of the transistors:  $U_L = U_{\text{CC}} - U_{\text{CE2}}$

$U_{\text{CE2}}$  has to be within the active region, not in the saturation region (Ch 5:  $> \sim 0.2 \text{ V}$ )

# Current Mirror

## With Base Current Compensation

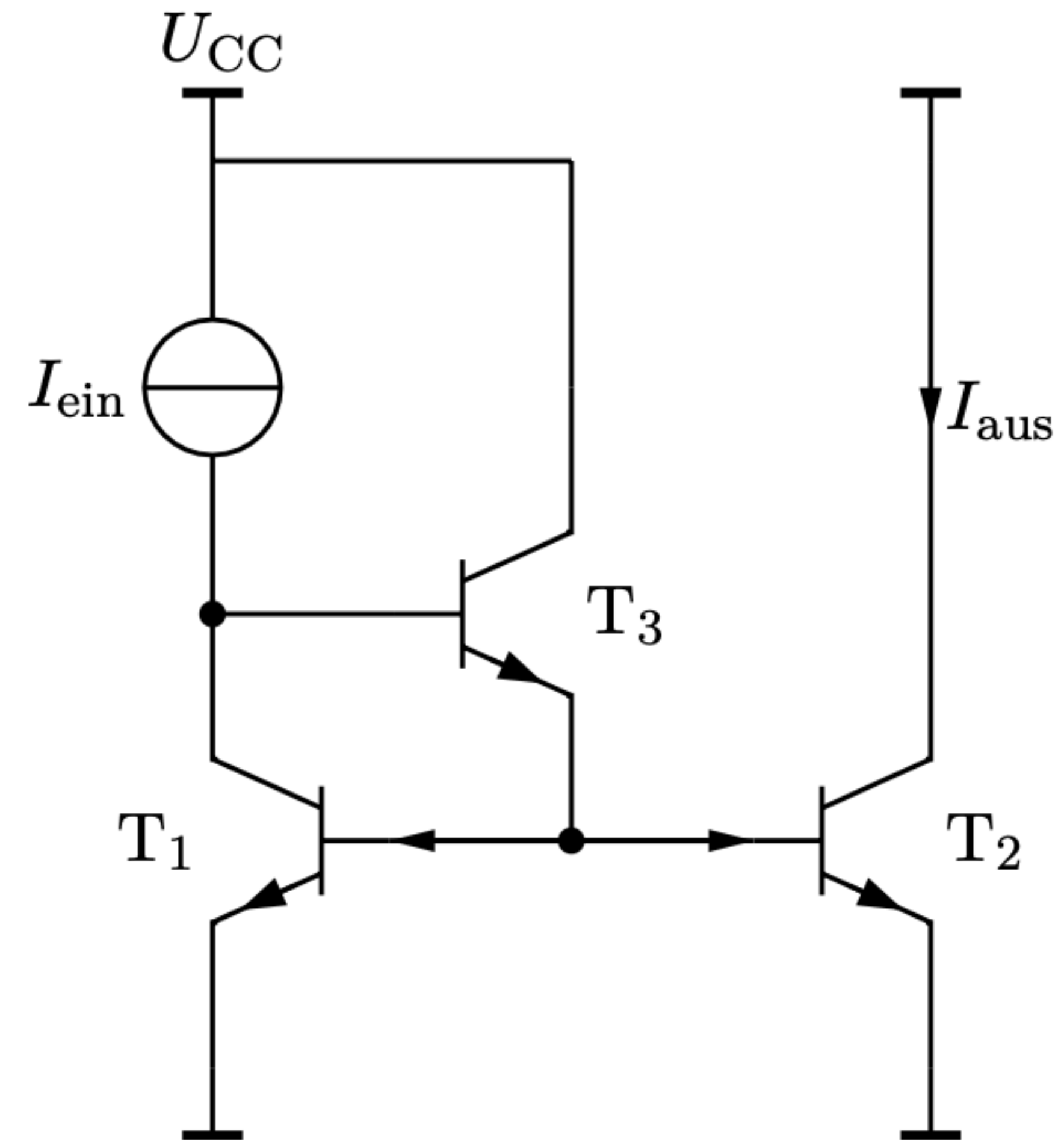
- Can we get closer to  $I_{\text{aus}} = I_{\text{ein}}$ ?  
Requires the compensation for the “lost” base current.

Possible with one additional transistor:

$$I_{E3} = I_{B1} + I_{B2}$$

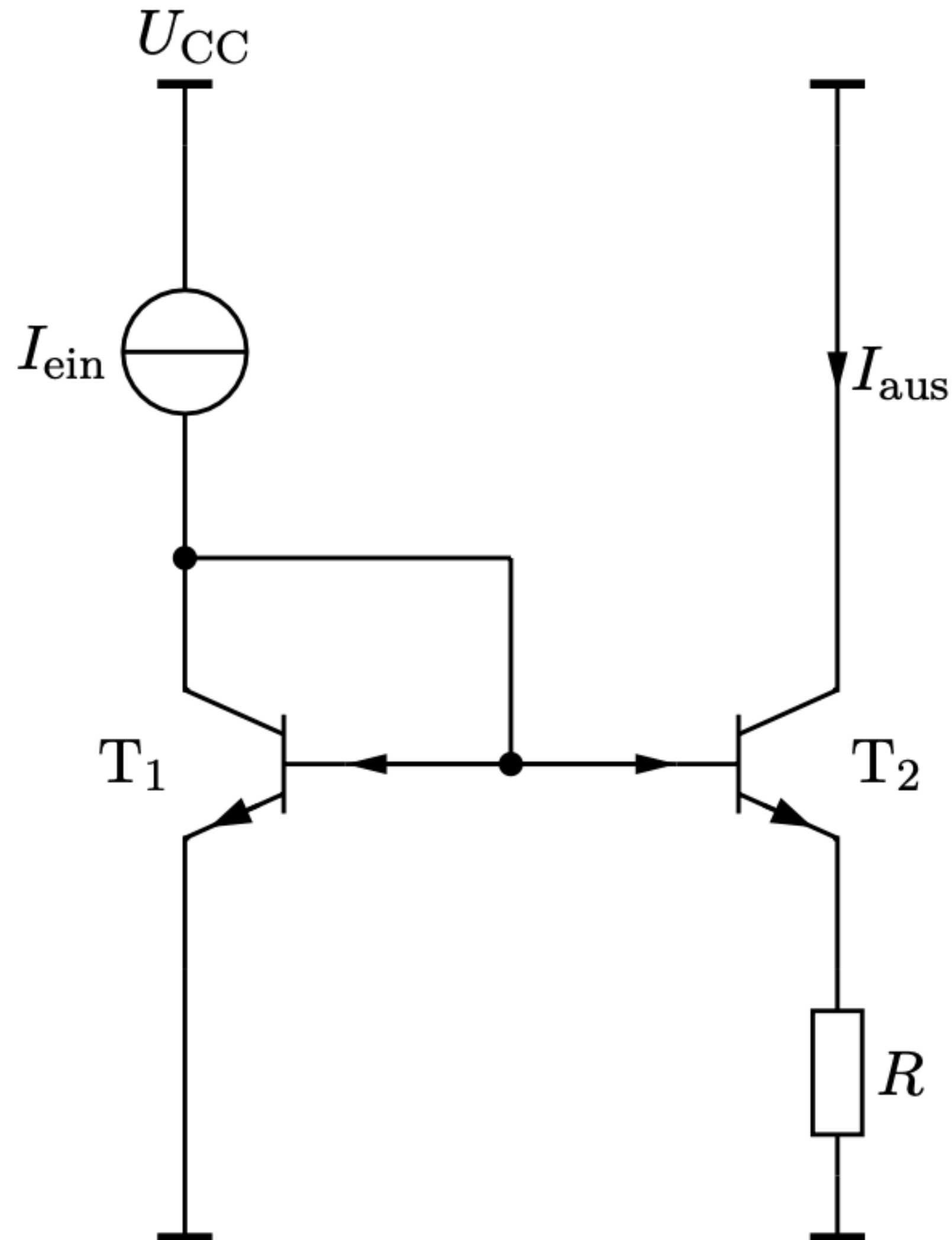
There remains a small “current loss” due to the base current of the 3<sup>rd</sup> transistor:

$$I_{B3} = \frac{I_{B1} + I_{B2}}{\beta_3}$$



# Widlar Current Mirror

*For small Currents*



- One additional resistor R on the “output arm”

How it works:

$$U_{BE1} = U_{BE2} + I_{aus}R \quad (\text{neglecting } I_{BE2} \text{ through } R)$$

Shockley equation:  $I_{BE} \approx I_S e^{\frac{U_{BE}}{U_T}} \Rightarrow U_{BE} \approx U_T \ln \frac{I_C}{\beta I_S}$

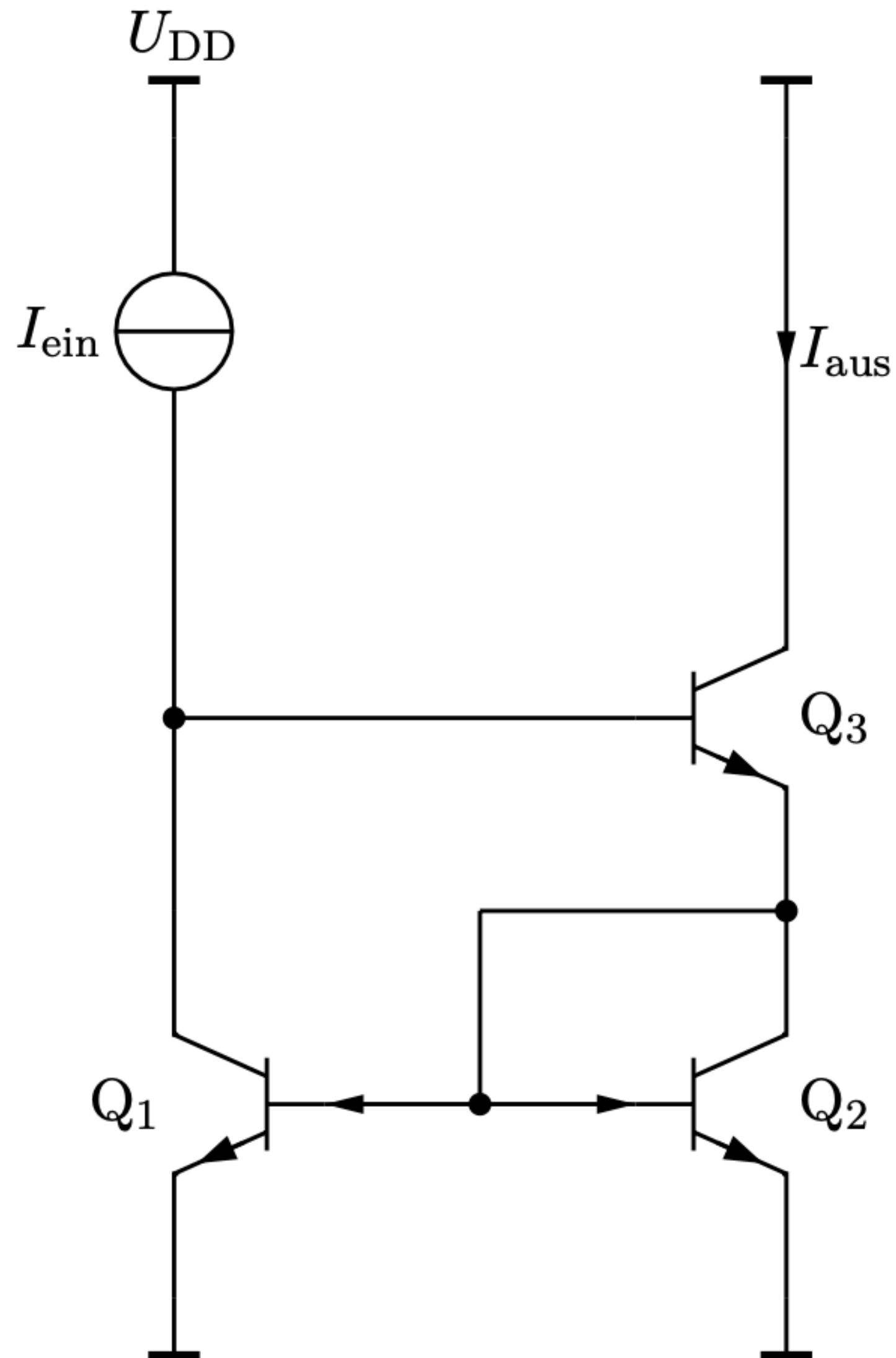
$I_C = \beta I_{BE}$  (gain)

results in:  $I_{aus} = \frac{U_T}{R} \ln \frac{I_{ein}}{I_{aus}}$

(no analytic solution, is solved analytically)

# Wilson Current Mirror

*A frequent Solution*



- Same principle as for the current mirror with base current compensation - here in the “output arm”:  
Transistor 3 provides the base current for  $T_1$  und  $T_2$



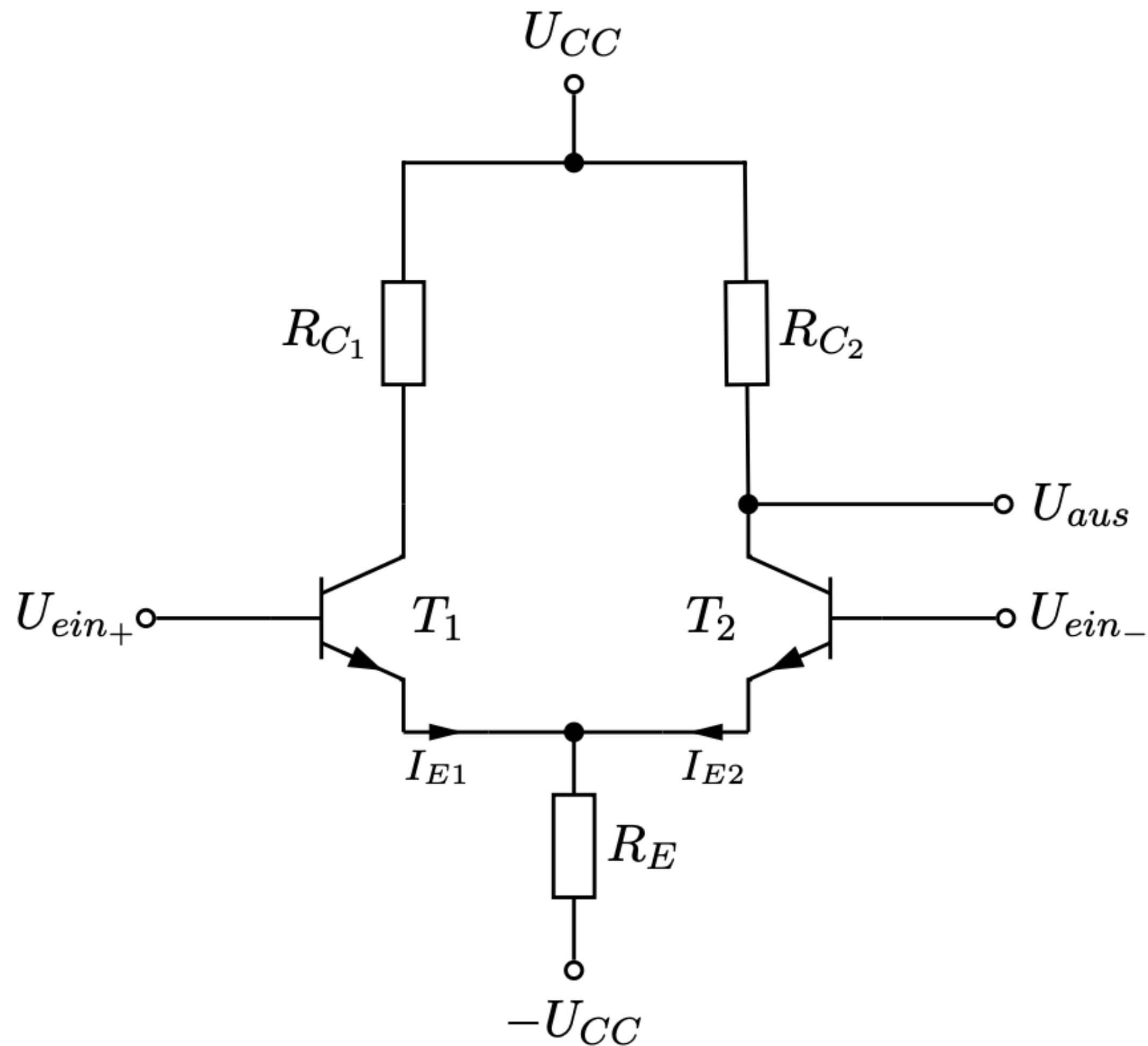
# Amplifiers - Part 1

*In: Chapter 6: 2-Transistor Circuits*

- Large gain
- High input impedance
- Low output impedance
- Large bandwidth
- Good linearity
- Low noise
- Low power
- Small temperature dependence

# Differential Amplifier

Differenzverstärker



- Used (for example) as input stage of op amps

- Differential input:  $U_{ein+}$ ,  $U_{ein-}$
- One output  $U_{aus}$
- Two coupled common emitter amplifiers  
normally:  $R_{C1} = R_{C2} = R_C$

To understand the circuit: Consider input as:

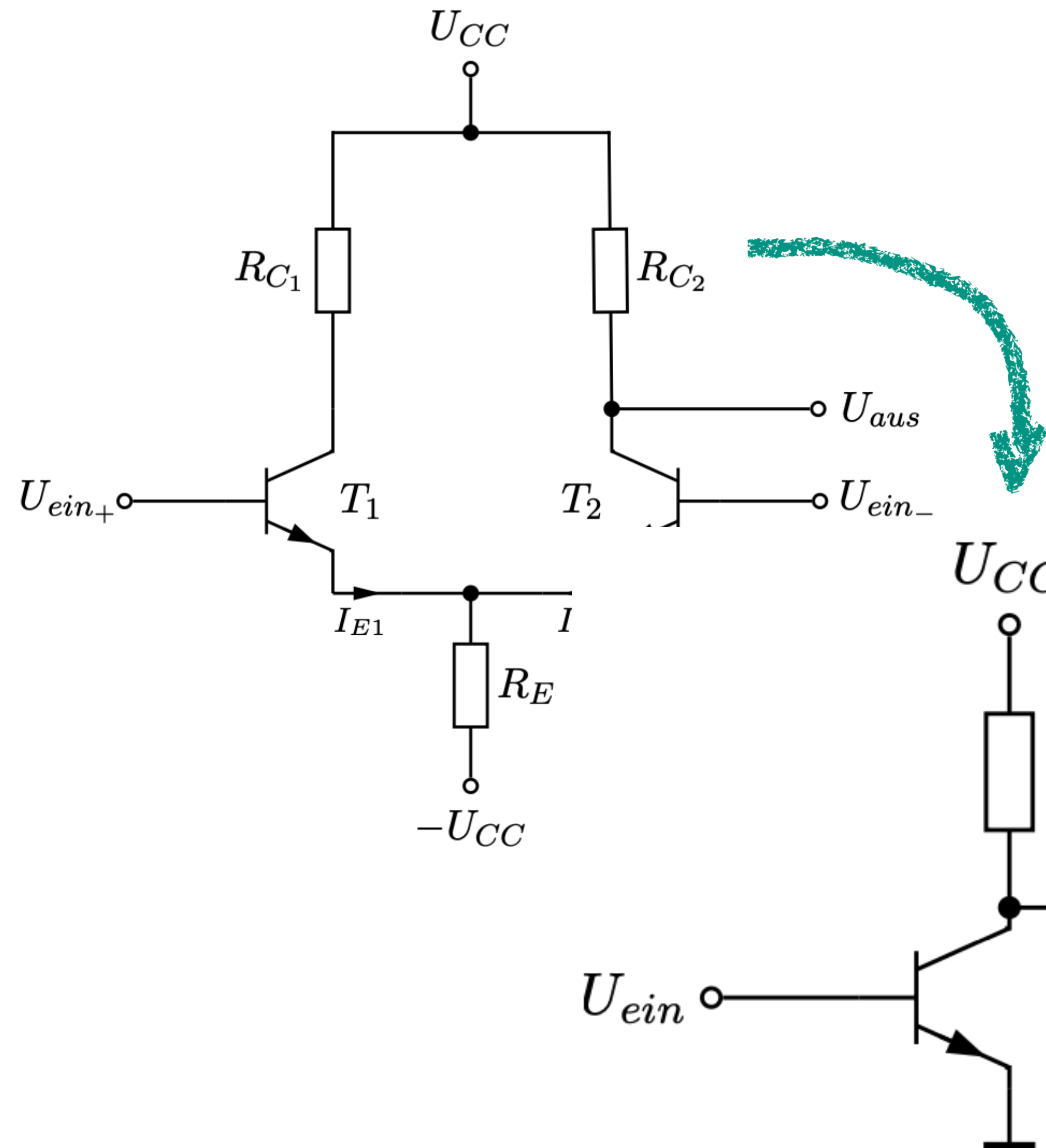
- $U_D = U_{ein+} - U_{ein-}$
- $U_{Gl} = (U_{ein+} + U_{ein-})/2$

Results in: 
$$U_{ein+} = U_{Gl} + \frac{U_D}{2}$$

$$U_{ein-} = U_{Gl} - \frac{U_D}{2}$$

# Differential mode amplification

Differenzverstärkung



- Consider the differential voltage:
  - Increasing  $U_{ein+}$  increases the current in arm 1
  - Reducing  $U_{ein-}$  reduces current in arm 2
- ⇒ Current sum remains constant, common emitter potential remains unchanged

With that: Behavior as the common emitter amplifier (Ch 05):

$$\frac{dU_{aus}}{dU_{ein}} = -R_C S$$

In differential amplifier: Output on “negative” arm, and only half of the differential signal: only half of the current

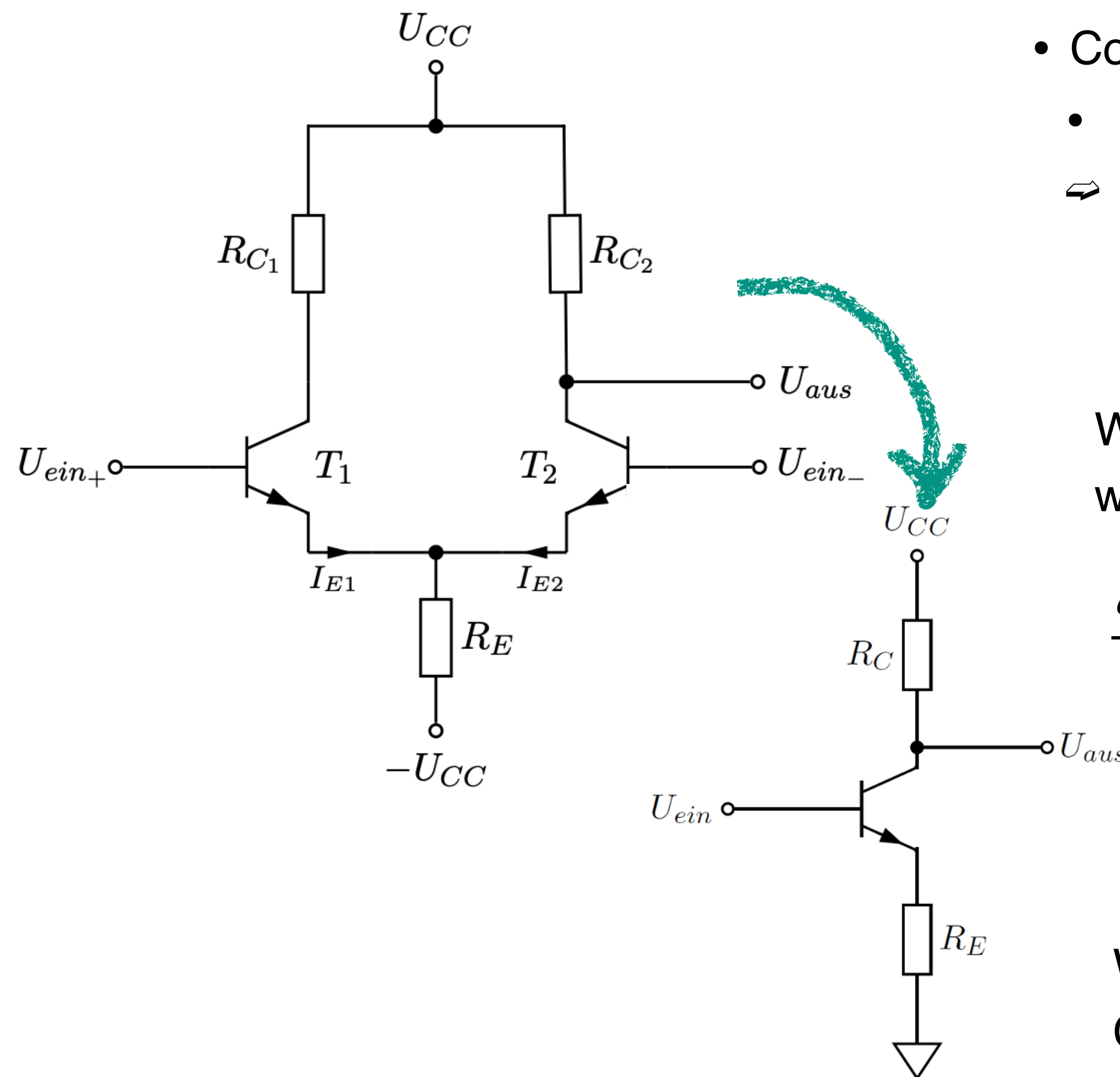
$$V_D = \frac{dU_{aus}}{dU_D} = R_C \frac{S}{2} = R_C \frac{I_C}{4U_T}$$

From Ch 05:  
(single transistor)

$$S = \frac{dI_C}{dU_{BE}} = \beta \frac{dI_B}{dU_{BE}} = \frac{\beta}{R_{BE}} = \frac{\beta I_B}{U_T} = \frac{I_C}{U_T}$$

# Common Mode Amplification

Gleichtaktverstärkung



- Consider the common mode voltage:
  - $U_{ein+}$  and  $U_{ein-}$  increase together
  - ⇒ Current increases by equal amounts in both arms. Results in a change of voltage on emitters due to higher current through  $R_E$ . Here  $U_E$  is not constant!

With that: Behavior as common emitter amplifier with current feedback (Ch 5):

$$\frac{dU_{aus}}{dU_{ein}} = -\frac{R_C}{R_E}$$

In differential amplifier: Output on “negative” arm, and only half of the differential signal: only half of the current

$$V_G = \frac{dU_{aus}}{dU_G} \approx -\frac{R_C}{2R_E}$$

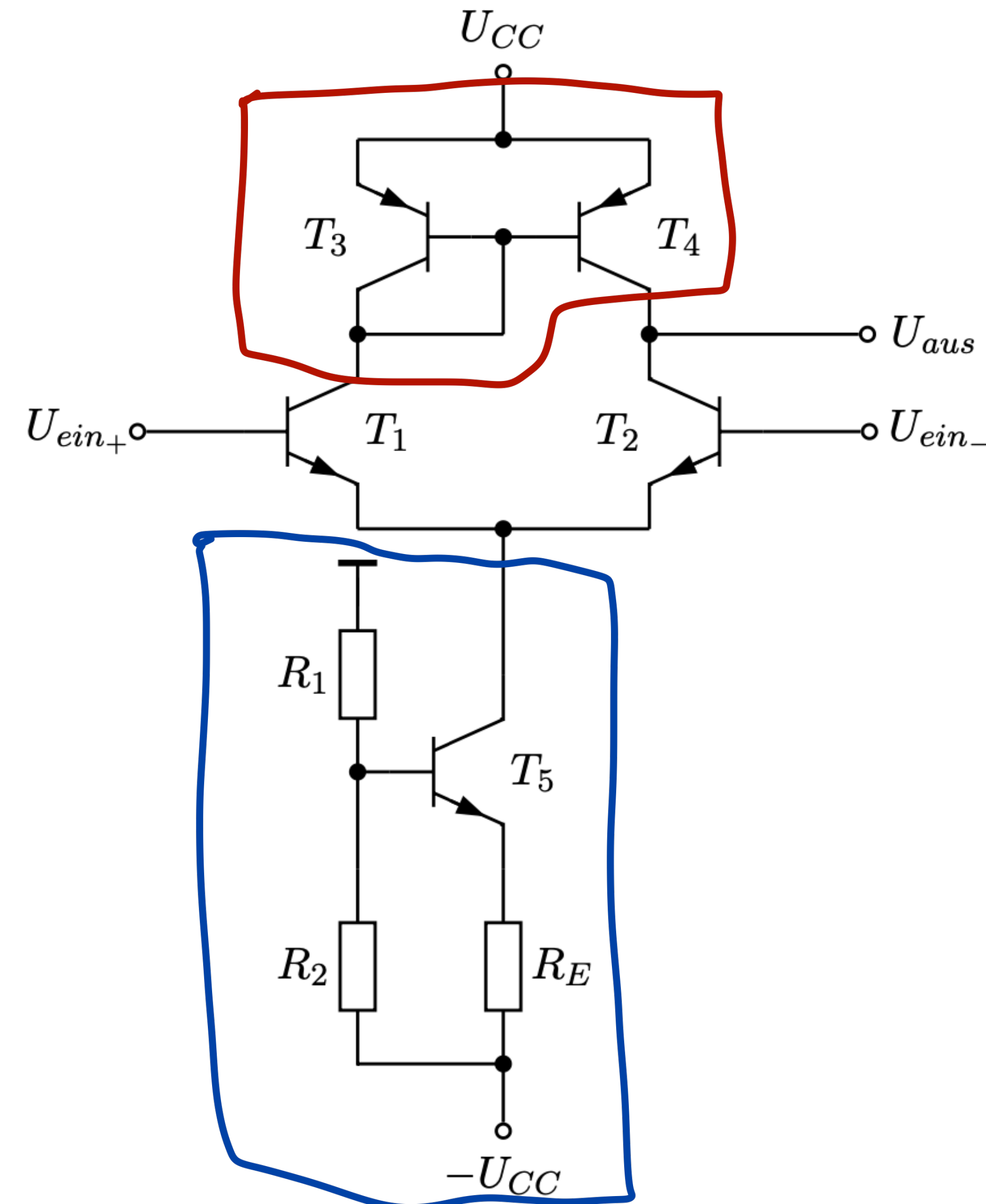
With result from previous slide:  
Common-mode suppression

$$\left| \frac{V_D}{V_G} \right| = SR_E$$



# Differential Amplifiers

## More Sophistication: Additional Transistors

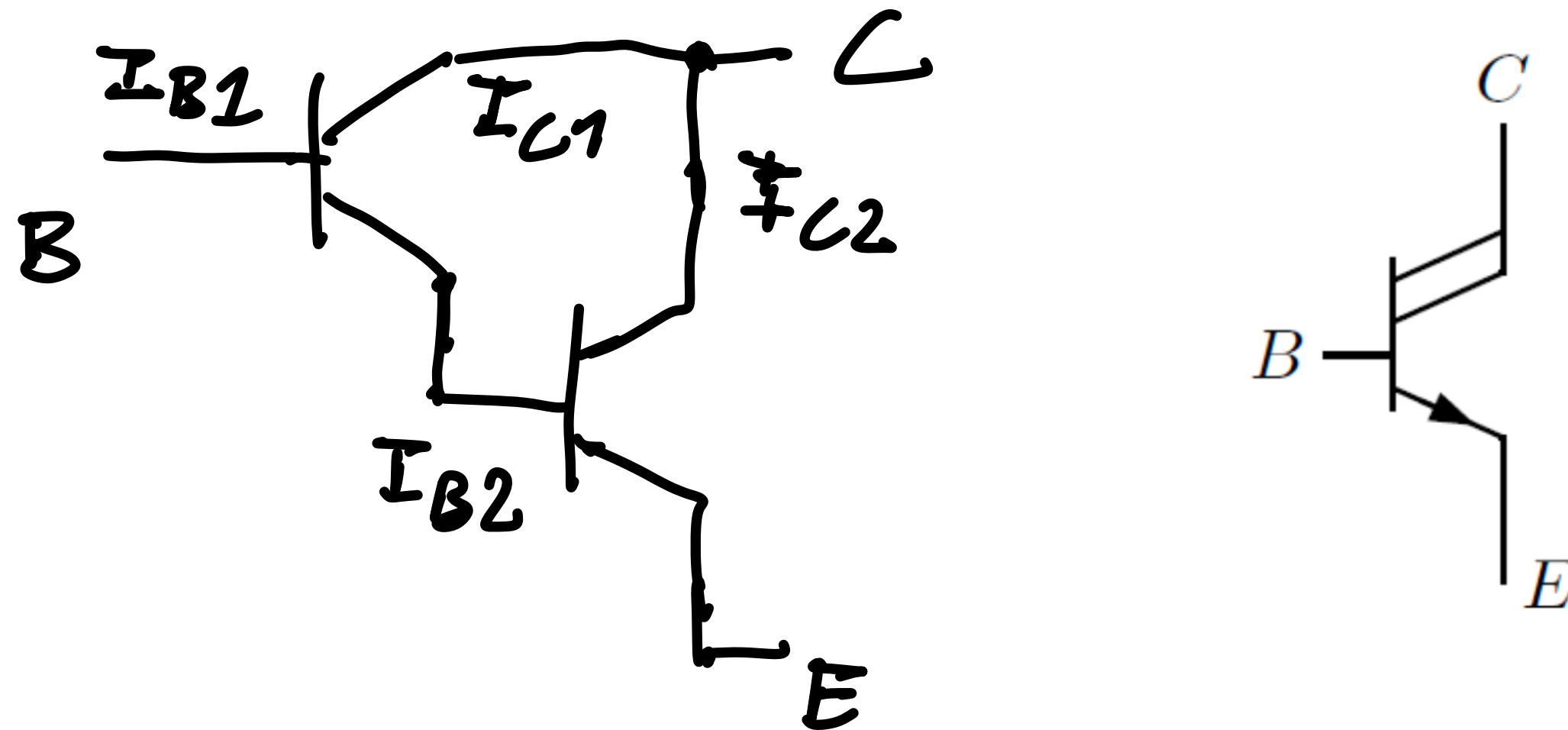


- A simple improvement of the differential amplifier:
  - ❏ Current mirror instead of  $R_C$  (current source with two identical outputs): Significant increase of gain (both  $V_D$  and  $V_G$ ): Effective increase of  $R_C$   
NB: Current mirror consisting of pnp-transistors so that the voltages fit.
  - ❏ Current source instead of  $R_E$ :  
Common mode amplification decreases with increasing  $R_E$ : Current source with high internal resistance improves behavior.



# The Darlington Transistor

*Two Transistors in one*



$$I_{C1} = \beta_1 I_{B1} \quad I_{C2} = \beta_2 I_{B2}$$

$$\Rightarrow I_{C2} = \beta_2 (I_{C1} + I_{B1}) = \beta_2 (\beta_1 + 1) I_{B1}$$

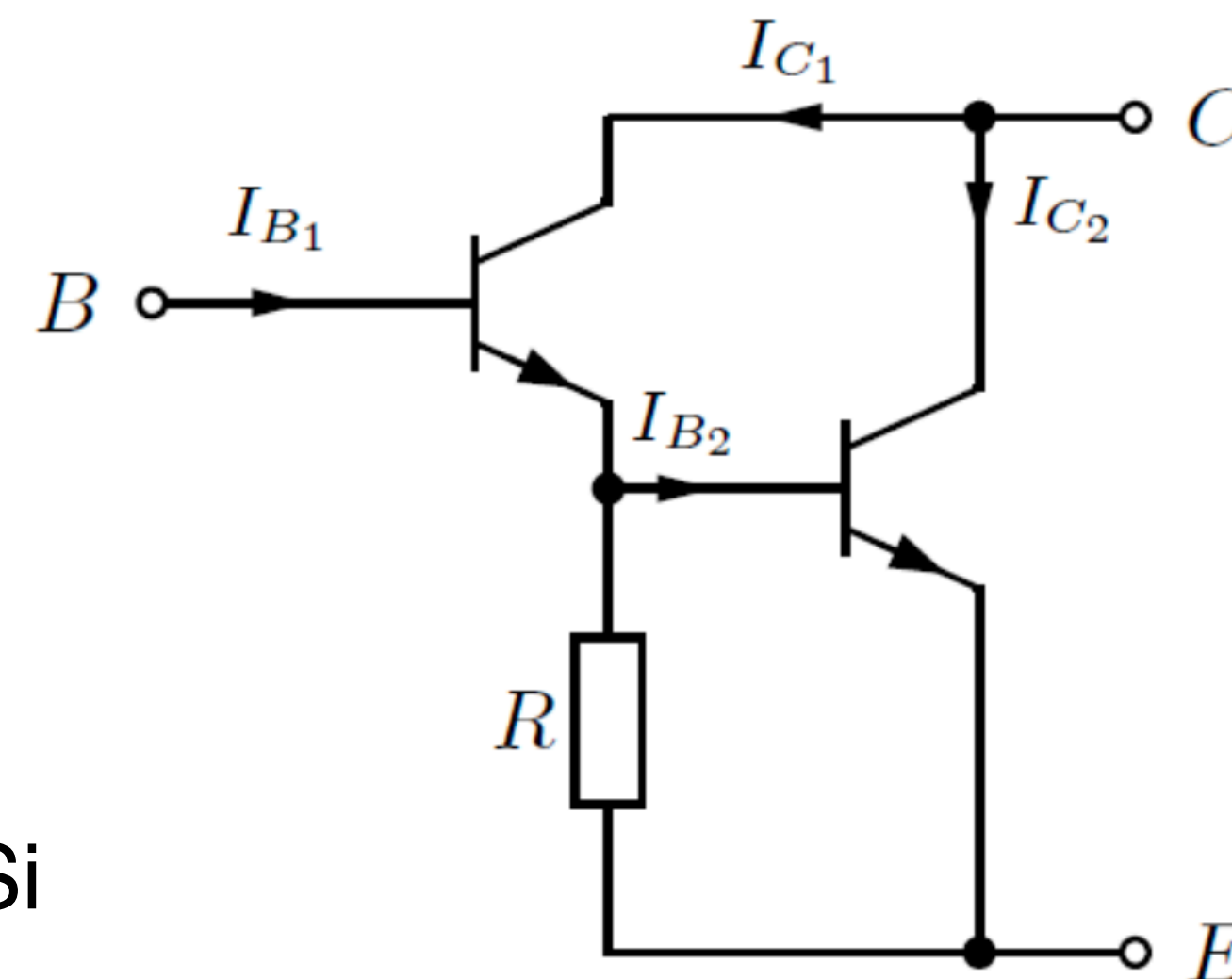
Gain  $\sim \beta_1 \beta_2$

But also:

- Doubling of base-emitter voltage: 1.2 - 1.4 V for Si
- Increased collector-emitter-voltage  $\rightarrow \sim 0.9$  V instead of 0.2 V to reach the active region: Higher power losses
- And: slower switching, larger phase shift

- Invented 1952 by Sidney Darlington (Bell Labs)
- Often available as dedicated component (2 transistors on one chip, integrated in one package)

Common modification: Resistor at the 2<sup>nd</sup> transistor



Speeds up switching, but costs gain.

Don't choose R too small:  $I_{B2}$  and  $U_{B2}$  have to be sufficiently large to switch the 2<sup>nd</sup> transistor.

## **Next Lectures:**

**Digital - Thursday, January 11, Tuesday, January 16 and  
Thursday, January 18**

**Analog 11 - Chapters 06, 07 - Tuesday, January 23, 2024**

# Time Plan for Next Lectures

*A few Changes coming up!*

Calender Week	Tuesday	Thursday
45	07.11. <b>Analog</b>	09.11. <b>Digital</b>
46	14.11. <b>Analog</b>	16.11. <b>Digital</b>
47	21.11. <b>Digital</b>	23.11. <b>Analog</b>
48	28.11. <b>Digital</b>	30.11. <b>Digital</b>
49	05.12. <b>Digital</b>	07.12. <b>Analog</b>
50	12.12. <b>Digital</b>	14.12. <b>Analog</b>
51	19.12. <b>Analog</b>	21.12. <b>Digital</b>
2	09.01. <b>Analog</b>	11.01. <b>Digital</b>
3	16.01. <b>Digital</b>	18.01. <b>Digital</b>
4	23.01. <b>Analog</b>	25.01. <b>Digital</b>
5	30.01. <b>Analog</b>	01.02. <b>Digital</b>
6	06.02. <b>Analog</b>	08.02. <b>Analog</b>
7	13.02. <b>Analog</b>	15.02. <b>Digital</b>

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