

an 1)

$\oplus: \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}^+ \quad \checkmark$

$\odot: \mathbb{R} \times \mathbb{R}^+ \rightarrow \mathbb{R}^+ \quad \checkmark$

V1: $x \cdot (y \cdot z) = x \cdot y \cdot z = (x \cdot y) \cdot z$ Assoziativgesetz

V2: $x \cdot 1 = x = 1 \cdot x$ Existenz eines neutralen Elements

V3: $x \cdot \frac{1}{x} = 1 = \frac{1}{x} \cdot x$ Existenz eines inversen Elements

V4: $x \cdot y = y \cdot x$ Kommutativgesetz

S1: $(x \cdot y)^\alpha = x^\alpha \cdot y^\alpha$

S2: $x^{\alpha+\beta} = x^\alpha \cdot x^\beta$

S3: $(x^\alpha)^\beta = (x^\alpha)^\beta$

S4: $x^1 = x$

$$\left(\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & 0 \\ 1 & 3 & 3 & 31 \end{array} \right)$$

$$\left(\begin{array}{ccc} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & 3 & 3 \end{array} \right) \cdot \begin{pmatrix} 31 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 31 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0 \\ 31 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & 3 & 3 \end{pmatrix}$$

Vektorraum

Eigenschaften $\forall m, n, r \in V, \forall \alpha, \beta \in K$:

- V1: $m \oplus (n \oplus r) = (m \oplus n) \oplus r$
- V2: $\exists 0_V \in V: m \oplus 0_V = 0_V \oplus m = m$
- V3: $\exists -r \in V: r \oplus (-r) = (-r) \oplus r = 0_V$
- V4: $r \oplus m = m \oplus r$
- S1: $\alpha \odot (m \oplus n) = (\alpha \odot m) \oplus (\alpha \odot n)$
- S2: $(\alpha + \beta) \odot n = (\alpha \odot n) \oplus (\beta \odot n)$
- S3: $(\alpha \cdot \beta) \odot n = \alpha \odot (\beta \odot n)$
- S4: $\exists 1_K \in K: 1_K \odot n = n$

Da 2. man muss zeigen \oplus, \odot abgeschlossen $\forall \wedge 0_V \in V$

a) nein: $\odot: \mathbb{C} \times V \not\rightarrow V$

$$i \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} i \\ 0 \\ 0 \end{pmatrix}$$

\uparrow \downarrow
 V $\not\rightarrow V$

b) ja: $\oplus: \begin{pmatrix} 0 \\ a_1 \\ a_2 \end{pmatrix} \oplus \begin{pmatrix} 0 \\ r_1 \\ r_2 \end{pmatrix} = \begin{pmatrix} 0 \\ a_1+r_1 \\ a_2+r_2 \end{pmatrix}$

2) $\odot: \alpha \begin{pmatrix} 0 \\ a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ \alpha a_1 \\ \alpha a_2 \end{pmatrix}$ 3) $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \in V$

c) nein: $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \oplus \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$

\uparrow \downarrow
 V $\not\rightarrow V$

d) ja: $\begin{pmatrix} 2a_1 \\ -a_1 \\ a_2 \end{pmatrix} + \begin{pmatrix} 2r_1 \\ -r_1 \\ r_2 \end{pmatrix} = \begin{pmatrix} 2(r_1+a_1) \\ -(a_1+r_1) \\ a_2+r_2 \end{pmatrix}$

2) $\alpha \begin{pmatrix} 2a_1 \\ -a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 2\alpha a_1 \\ -\alpha a_1 \\ -\alpha a_2 \end{pmatrix}$ 3) $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \in V$

e) nein: $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \notin V$

f) nein: $\begin{pmatrix} a_1 \\ a_1 \\ a_2 \end{pmatrix} + \begin{pmatrix} a_2 \\ a_2 \\ a_1 \end{pmatrix} = \begin{pmatrix} a_1+a_2 \\ a_1+a_2 \\ a_1+a_2 \end{pmatrix}$

\uparrow
 $\not\rightarrow V$

g) ja: $\begin{pmatrix} a_1 \\ a_1 \\ a_2 \end{pmatrix} + \begin{pmatrix} r_1 \\ r_1 \\ r_2 \end{pmatrix} = \begin{pmatrix} a_1+r_1 \\ a_1+r_1 \\ a_2+r_2 \end{pmatrix}$, $\alpha \begin{pmatrix} a_1 \\ a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} \alpha a_1 \\ \alpha a_1 \\ \alpha a_2 \end{pmatrix}$, $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \in V$

h) nein: $\begin{pmatrix} a_1 \\ a_2 \\ 0 \end{pmatrix} + \begin{pmatrix} a_2 \\ a_1 \\ 0 \end{pmatrix} = \begin{pmatrix} a_1+a_2 \\ a_1+a_2 \\ 0 \end{pmatrix} \notin V$ $a_1 \neq a_2$

Am 3)

⊕: V x V → V

p(x) + q(x) = r(x) √ $\sum_{j=0}^m a_j x^j + \sum_{k=0}^n b_k x^k = \sum_{l=0}^{\max(m,n)} (a_l + b_l) x^l$

⊙: R x V → V

α · p(x) = q(x) √ $q(x) = (\alpha a_0) + (\alpha a_1) x + \dots + (\alpha a_n) x^n$

V1: p(x) + (q(x) + r(x)) = (p(x) + q(x)) + r(x)

V2: p(x) + 0 = p(x) = 0 + p(x) 0_V = 0

V3: p(x) + (-p(x)) = 0 = (-p(x)) + p(x) (-p(x)) = -a_0 - a_1 x + \dots - a_n x^n

V4: p(x) + q(x) = q(x) + p(x)

S1: α(p(x) + q(x)) = α p(x) + α q(x)

S2: (α + β) p(x) = α p(x) + β p(x)

S3: (α · β) p(x) = α(β p(x))

S4: 1 · p(x) = p(x)

2. (D p)(x) = (∑_{j=0}^n a_j x^j)' = ∑_{j=0}^n a_j (x^j)' = ∑_{j=0}^{n-1} a_j j x^{j-1}

D(α p + q)(x) = D(α ∑_{j=0}^m a_j x^j + ∑_{k=0}^n b_k x^k) = D ∑_{j=0}^{\max(m,n)} (α a_j + b_j) x^j a_j = 0, b_k = 0 j > m, k > n

= ∑ (α a_j + b_j) j x^{j-1} = ∑ α a_j j x^{j-1} + ∑ b_j j x^{j-1}

= α D(∑ a_j x^j) + D(∑ b_j x^j)

J(α p + q)(x) = ∫_0^x (α p(t) + q(t)) dt = α ∫_0^x p(t) dt + ∫_0^x q(t) dt = α J(p)(x) + J(q)(x)

3. (DJ p)(x) = D ∫_0^x p(t) dt = [P(x) - P(0)]' = p(x) P'(x) = p(x)

(JD p)(x) = J ∑_{j=0}^n j a_j x^{j-1} = J ∑_{j=1}^n j a_j x^{j-1} = ∑_{j=1}^n a_j J(j x^{j-1}) = ∑_{j=1}^n a_j x^j

JD(∑_{j=0}^n a_j x^j) = ∑_{j=1}^n a_j x^j

4. nein, weil JD ≠ DJ

Ans 4:

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_d \end{pmatrix} (b_1, b_2, \dots, b_d) = \begin{pmatrix} a_1 b_1 & a_1 b_2 & \dots & a_1 b_d \\ a_2 b_1 & a_2 b_2 & \dots & a_2 b_d \\ \vdots & \vdots & \ddots & \vdots \\ a_d b_1 & a_d b_2 & \dots & a_d b_d \end{pmatrix}$$

$$C_x = \begin{pmatrix} a_1 b_1 & a_1 b_2 & \dots & a_1 b_d \\ a_2 b_1 & & & \vdots \\ \vdots & & & \vdots \\ a_d b_1 & & & a_d b_d \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_d \end{pmatrix} = \begin{pmatrix} \sum_j a_1 b_j x_j \\ \sum_j a_2 b_j x_j \\ \vdots \\ \sum_j a_d b_j x_j \end{pmatrix} = \begin{pmatrix} a_1 \sum b_j x_j \\ a_2 \sum b_j x_j \\ \vdots \\ a_d \sum b_j x_j \end{pmatrix}$$

$$\langle b, x \rangle a = \sum b_j x_j \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_d \end{pmatrix} = \begin{pmatrix} a_1 \sum b_j x_j \\ a_2 \sum b_j x_j \\ \vdots \\ a_d \sum b_j x_j \end{pmatrix}$$

Au 5)
nein

$$x^d - x^d = 0 \leftarrow \text{Even Grad 0}$$

\uparrow P. von Grad d \uparrow P. von Grad d

...

$$C^1(\mathbb{R}) = \{ f(x) \in C(\mathbb{R}) \mid f'(x) \text{ existiert} \}$$

$$C^2(\mathbb{R}) = \{ f(x) \in C^1(\mathbb{R}) \mid f''(x) \text{ existiert} \}$$

$$C^k(\mathbb{R}) = \{ f(x) \in C^{k-1}(\mathbb{R}) \mid f^{(k)}(x) \text{ existiert} \}$$

$$C^\infty(\mathbb{R}) = \bigcap_{k \in \mathbb{N}} C^k(\mathbb{R})$$

...

$$C^1(\mathbb{R}) \supset C^2(\mathbb{R}) \supset C^3(\mathbb{R}) \supset \dots \supset C^\infty(\mathbb{R})$$

$$C^k(\mathbb{R}) \cap C^l(\mathbb{R}) = C^{\min(k,l)}(\mathbb{R})$$

$$C^k(\mathbb{R}) \cup C^l(\mathbb{R}) \supset C^{\min(k,l)}(\mathbb{R})$$

...

$$C^1(\mathbb{R}) \cap C^2(\mathbb{R}) = C^1(\mathbb{R})$$

$$C^1(\mathbb{R}) \cup C^2(\mathbb{R}) \supset C^1(\mathbb{R})$$

...

$$C^1(\mathbb{R}) \cap C^2(\mathbb{R}) = C^1(\mathbb{R})$$

$$C^1(\mathbb{R}) \cup C^2(\mathbb{R}) \supset C^1(\mathbb{R})$$

Ans.

1) Beweis von Definition: $(\exists a, b: a\vec{x} + b\vec{y} = 0 \Rightarrow a, b = 0)$

$$\exists a, b \quad \forall x: a \sin x + b \cos x = 0$$

$$x_1 = \frac{\pi}{4}: a \sin \frac{\pi}{4} + b \cos \frac{\pi}{4} = 0 \Rightarrow a = -b \Rightarrow b = -a$$

$$x_2 = 0: 0 = a \sin 0 + b \cos 0 \Rightarrow b = 0 \Rightarrow a = 0$$

2) Beweis von Definition

$$\exists a, b \quad \forall x: a e^x + b \cos x = 0$$

$$x_1 = 0: a e^0 + b \cos 0 = 0 \Rightarrow a = -b \Rightarrow b = -a$$

$$x_2 = \frac{\pi}{2}: a e^{\frac{\pi}{2}} + b \cos \frac{\pi}{2} = 0 \Rightarrow a = 0 \Rightarrow b = 0$$

3) Beweis von Definition

$$\exists a, b, c, \quad a, b, c \in \mathbb{R} \quad \forall x: a e^{ix} + b \sin x + c \cos x = 0$$

$$x = 0: a e^0 + b \sin 0 + c \cos 0 = 0 \Rightarrow a = -c$$

$$x = \frac{\pi}{2}: a e^{i\frac{\pi}{2}} + b \sin \frac{\pi}{2} + c \cos \frac{\pi}{2} = 0 \Rightarrow a i + b = 0 \Rightarrow a = 0, b = 0 \Rightarrow c = 0$$

mit \mathbb{R} lin. unabhängig

$$\text{mit } \mathbb{C}: \sin x = \frac{e^{ix} - e^{-ix}}{2i}$$

$$\cos x = \frac{e^{ix} + e^{-ix}}{2}$$

$$\Rightarrow i \sin x + \cos x = e^{ix} \Rightarrow i \cdot \sin x + 1 \cdot \cos x - e^{ix} = 0$$

Ans 7)

$$\begin{pmatrix} 1 & 2 & 3 & | & 31 \\ 0 & 1 & -1 & | & 6 \\ 1 & 0 & 1 & | & 7 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 3 & | & 31 \\ 0 & 1 & -1 & | & 6 \\ 0 & -2 & -2 & | & -24 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 3 & | & 31 \\ 0 & 1 & -1 & | & 6 \\ 0 & -1 & -1 & | & -12 \end{pmatrix} \sim$$

$$\sim \begin{pmatrix} 1 & 2 & 3 & | & 31 \\ 0 & 1 & -1 & | & 6 \\ 0 & 0 & -2 & | & -6 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & | & 4 \\ 0 & 1 & 0 & | & 9 \\ 0 & 0 & 1 & | & 3 \end{pmatrix}$$

$$x_1 = 4$$

$$x_2 = 9$$

$$x_3 = 3$$

Am 8.

1) \mathbb{R} mit std. Verknüpfungen Körper $\Rightarrow V_1 \rightarrow V_4 \mathbb{S}_3$ sind natv
S4: $1 \in \mathbb{Q} \quad 1 \cdot x = x \quad \checkmark$

\mathbb{R} über \mathbb{Q} Vektorraum \checkmark

2) nein $\circ: \mathbb{R} \otimes \mathbb{Q} \rightarrow \mathbb{Q}$
z.B. $\pi \cdot 1 = \pi \notin \mathbb{Q}$