

KIT Department of Physics

Classical Theoretical Physics I

WS 2025/2026

Prof. Dr. Anja Metelmann

Najmeh Etehad Abari
Tobias Herrig
Varna Shenoy

Practice Exam / Solutions

Problem 1. Warm-up

[4 Points]

Answer the following questions in a few keywords:

- (a) [1 Point] What are the properties of orthogonal matrices? Is a rotation matrix orthogonal? A square matrix Q is called orthogonal if its transpose is equal to its inverse: [0.5 Points]

$$Q^T = Q^{-1}$$

The determinant of an orthogonal matrix is always either $+1$ or -1 :

$$\det(Q) \in \{+1, -1\}$$

Yes. A rotation matrix is the most common type of orthogonal matrix with the determinant: [0.5 Points]

$$\det(Q) = 1$$

- (b) [1 Point] Through which expression do you determine the associated potential for a given potential force field $\mathbf{F}(\mathbf{r})$?

$$U(\mathbf{r}) - U(\mathbf{r}_0) = - \int_{\mathbf{r}_0}^{\mathbf{r}} d\mathbf{r}' \cdot \mathbf{F}(\mathbf{r}')$$

- (c) [2 Points] A one-dimensional harmonic oscillator with Stokes friction is described by the equation of motion $m\ddot{x} = -r\dot{x} - kx$. What is the natural frequency of the undamped oscillator? Which qualitatively different types of motion are observed and for which friction r ?

Answer:

The natural frequency is $\omega_0 = \sqrt{\frac{k}{m}}$.

[0.5 Points]

The following cases must be considered separately:

$$\omega_0^2 < \left(\frac{r}{2m}\right)^2 \quad \text{Overdamped case (Kriechfall)} \quad [0.5 \text{ Points}]$$

$$\omega_0^2 = \left(\frac{r}{2m}\right)^2 \quad \text{Critically damped case, and} \quad [0.5 \text{ Points}]$$

$$\omega_0^2 > \left(\frac{r}{2m}\right)^2 \quad \text{Underdamped case (Schwingfall).} \quad [0.5 \text{ Points}]$$

Problem 2. Conservative Force Field, Potential**[5 Points]**

Given is the force field:

$$\mathbf{F}(\mathbf{r}) = \begin{pmatrix} ax + by \\ cx + dy \\ ez \end{pmatrix}$$

- (a) [1 Point] What condition must the constants $a, b, c, d, e \neq 0$ satisfy for $\mathbf{F}(\mathbf{r})$ to be a conservative force field?

We consider the condition $\nabla \times \mathbf{F}(\mathbf{r}) = 0$ and obtain:**[0.25 Points]**

$$\begin{pmatrix} 0 \\ 0 \\ c - b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

[0.5 Points]For $c = b$, the force field is conservative.**[0.25 Points]**

- (b) [1.5 Points] Determine the potential $U(\mathbf{r})$. As a check, calculate the force field resulting from the found potential.

We calculate the potential $U(\mathbf{r})$ via the line integral using the parametrization $\mathbf{r}(t) = (xt, yt, zt)$ with $t \in [0, 1]$:

$$\begin{aligned} U(x, y, z) - U(0, 0, 0) &= - \int_0^1 \begin{pmatrix} ax + by \\ bx + dy \\ ez \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} dt \\ &= - [(ax + by)x + (bx + dy)y + ez^2] \int_0^1 t dt \\ &= - \frac{1}{2} (ax^2 + 2bxy + dy^2 + ez^2) \end{aligned}$$

[1 Point]

Check:

$$\mathbf{F}(\mathbf{r}) = -\nabla U(\mathbf{r}) = \begin{pmatrix} ax + by \\ bx + dy \\ ez \end{pmatrix}.$$

[0.5 Points]

- (c) [2 Points] Determine, by explicit calculation of the line integrals, the work done on a mass point along the paths:

- (i) C_1 : **On a direct path from** $(x, y, z) = (0, 0, 0)$ **to** $(1, 0, 1)$.

With the parametrization $\mathbf{r}(t) = (t, 0, t)$ for $t \in [0, 1]$:

$$W_1 = - \int_0^1 \begin{pmatrix} at \\ bt \\ et \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} dt = -(a + e) \int_0^1 t dt = -\frac{a + e}{2}$$

[0.5 Points]

(ii) C_2 : In a semicircle in the xy -plane from $(1, 0, 1)$ via $(0, -1, 1)$ to $(-1, 0, 1)$.

With the parametrization $\mathbf{r}(t) = (\cos(t), -\sin(t), 1)$ for $t \in [0, \pi]$: [1 Point]

$$\begin{aligned} W_2 &= - \int_0^\pi \begin{pmatrix} a \cos(t) - b \sin(t) \\ b \cos(t) - d \sin(t) \\ e \end{pmatrix} \cdot \begin{pmatrix} -\sin(t) \\ -\cos(t) \\ 0 \end{pmatrix} dt \\ &= \int_0^\pi (a \sin t \cos t - b \sin^2 t + b \cos^2 t - d \sin t \cos t) dt \\ &= \int_0^{\frac{\pi}{2}} [(a-d) \sin t \cos t + b(\cos^2 t - \sin^2 t)] dt \\ &\quad + \int_{\frac{\pi}{2}}^\pi [(a-d) \cos t (-\sin t) + b(\sin^2 t - \cos^2 t)] dt = 0 \end{aligned}$$

(iii) C_3 : On a direct path from $(-1, 0, 1)$ to $(0, 0, 0)$.

With the parametrization $\mathbf{r}(t) = (-t, 0, t)$ for $t \in [1, 0]$:

$$W_3 = - \int_1^0 \begin{pmatrix} -at \\ bt \\ et \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} dt = (a+e) \int_0^1 t dt = \frac{a+e}{2}$$

[0.5 Points]

(d) [0.5 Points] Now use the fact that the force field is conservative and verify your results from part c).

$$\begin{aligned} W_1 &= U(1, 0, 1) - U(0, 0, 0) = -\frac{1}{2}(a+e) \\ W_2 &= U(-1, 0, 1) - U(1, 0, 1) = 0 \\ W_3 &= U(0, 0, 0) - U(-1, 0, 1) = \frac{1}{2}(a+e) \end{aligned}$$

$$W_1 + W_2 + W_3 = 0$$

Problem 3. Particular Solution

[2 Points]

We want to derive a general formula for calculating a particular solution of the differential equation:

$$\ddot{x} + \omega^2 x = f(t)$$

(a) [2 Points] Decompose the left side of this equation into linear factors:

$$\left(\frac{d}{dt} + i\omega \right) \left(\frac{d}{dt} - i\omega \right) x(t) = f(t)$$

and set:

$$y(t) = \left(\frac{d}{dt} - i\omega \right) x(t).$$

You obtain an inhomogeneous linear first-order ODE for $y(t)$. Solve this ODE by variation of constants with the ansatz:

$$y(t) = u(t)e^{-i\omega t}.$$

Solution

(a) [2 Points] We first factor the differential operator:

$$\ddot{x} + \omega^2 x = \left(\frac{d}{dt} + i\omega \right) \left(\frac{d}{dt} - i\omega \right) x(t).$$

Define:

$$y(t) = \left(\frac{d}{dt} - i\omega \right) x(t).$$

Then it follows:

$$\left(\frac{d}{dt} + i\omega \right) y(t) = f(t),$$

which is the linear first-order differential equation:

$$\dot{y} + i\omega y = f(t).$$

[0.5 Points]

Variation of Constants We set:

$$y(t) = u(t)e^{-i\omega t}.$$

Then:

$$\dot{y} = \dot{u}e^{-i\omega t} - i\omega u e^{-i\omega t}.$$

Substituting into the differential equation:

$$\dot{u}e^{-i\omega t} - i\omega u e^{-i\omega t} + i\omega u e^{-i\omega t} = f(t).$$

[process : 0.5 Points] The terms with $i\omega$ cancel out:

$$\dot{u}e^{-i\omega t} = f(t).$$

[process: 0.25 Points]

Thus:

$$\dot{u} = f(t)e^{i\omega t}.$$

Integration yields:

$$u(t) = \int f(t')e^{i\omega t'} dt'.$$

This results in:

$$y(t) = e^{-i\omega t} \int f(t')e^{i\omega t'} dt'.$$

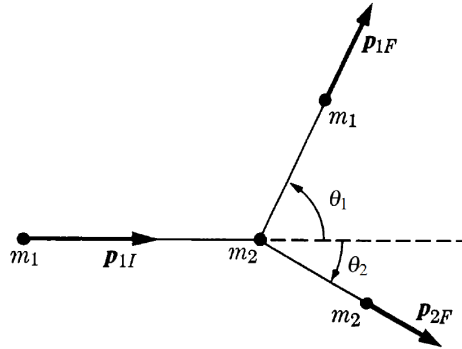
[Process and main answer 0.5 + 0.25 Points]

This is the general solution for $y(t)$.

Problem 4. Elastic Collision**[4 Points]**

Consider a "projectile" particle of mass m_1 and initial momentum p_{1I} , which collides with a "target" particle of mass m_2 that is initially at rest.

After the collision, particle m_1 is scattered by an angle θ_1 and has the final momentum p_{1F} . Particle m_2 recoils with momentum p_{2F} at an angle θ_2 relative to the original direction of p_{1I} .



- (a) [1 Point] Set up the equations for the conservation of linear momentum along the direction of p_{1I} and perpendicular to it.

The conservation of momentum $\vec{p}_{before} = \vec{p}_{after}$ is decomposed into components:

- **Parallel to the incident direction (x-axis):**

$$p_{1I} = p_{1F} \cos \theta_1 + p_{2F} \cos \theta_2$$

[0.5 Points]

- **Perpendicular to the incident direction (y-axis):**

$$0 = p_{1F} \sin \theta_1 - p_{2F} \sin \theta_2 \implies p_{2F} \sin \theta_2 = p_{1F} \sin \theta_1$$

[0.5 Points]

- (b) [1 Point] Use your equations from (a) to show that:

$$p_{2F}^2 = p_{1I}^2 + p_{1F}^2 - 2p_{1I}p_{1F} \cos \theta_1$$

To eliminate θ_2 , we isolate the terms with θ_2 and use $\sin^2 \theta + \cos^2 \theta = 1$:

$$(p_{2F} \cos \theta_2)^2 = (p_{1I} - p_{1F} \cos \theta_1)^2 = p_{1I}^2 - 2p_{1I}p_{1F} \cos \theta_1 + p_{1F}^2 \cos^2 \theta_1$$

$$(p_{2F} \sin \theta_2)^2 = (p_{1F} \sin \theta_1)^2 = p_{1F}^2 \sin^2 \theta_1$$

[0.5 Points]

Adding both equations yields:

$$p_{2F}^2 = p_{1I}^2 + p_{1F}^2 - 2p_{1I}p_{1F} \cos \theta_1$$

[0.5 Points]

(c) [2 Points] Given the energy conservation relationship:

$$\frac{p_{1I}^2 - p_{1F}^2}{m_1} = \frac{p_{2F}^2}{m_2}.$$

Substitute the expression from (b) to derive the quadratic equation for the ratio $\frac{p_{1F}}{p_{1I}}$. Show in particular that:

$$\frac{p_{1F}}{p_{1I}} = \frac{m_1}{m_1 + m_2} \cos \theta_1 \pm \left[\left(\frac{m_1}{m_1 + m_2} \right)^2 \cos^2 \theta_1 + \frac{m_2 - m_1}{m_1 + m_2} \right]^{1/2}.$$

Substituting p_{2F}^2 into the energy conservation $\frac{p_{1I}^2 - p_{1F}^2}{m_1} = \frac{p_{2F}^2}{m_2}$:

$$\frac{p_{1I}^2 - p_{1F}^2}{m_1} = \frac{p_{1I}^2 + p_{1F}^2 - 2p_{1I}p_{1F} \cos \theta_1}{m_2}$$

Rearranging for p_{1F} :

$$(m_1 + m_2)p_{1F}^2 - (2m_1p_{1I} \cos \theta_1)p_{1F} + (m_1 - m_2)p_{1I}^2 = 0$$

Dividing by $(m_1 + m_2)p_{1I}^2$ and applying the quadratic formula for $x = \frac{p_{1F}}{p_{1I}}$: [process 1.75 Points]

$$\frac{p_{1F}}{p_{1I}} = \frac{m_1}{m_1 + m_2} \cos \theta_1 \pm \left[\left(\frac{m_1}{m_1 + m_2} \right)^2 \cos^2 \theta_1 + \frac{m_2 - m_1}{m_1 + m_2} \right]^{1/2}$$

[0.25 Points]