

$$1) \vec{\nabla} \cdot (\vec{v} \times \vec{w}) =$$

$$a) \partial_i \epsilon_{ijk} v_j w_k = \epsilon_{ijk} [(\partial_i v_j) w_k + v_j (\partial_i w_k)] \quad (1)$$

$$= \underbrace{\epsilon_{kij} w_k (\partial_i v_j)} - \underbrace{\epsilon_{jik} v_j (\partial_i w_k)}$$

$$(0,5) \quad \vec{w} \cdot (\vec{\nabla} \times \vec{v}) = 0 \quad \vec{v} \cdot (\vec{\nabla} \times \vec{w}) \quad (0,5)$$

$$= - \vec{v} \cdot (\vec{\nabla} \times \vec{w}), \text{ mit } \vec{v}(\vec{r}) = \vec{r}, \vec{\nabla} \times \vec{r} = 0$$

$$b) j^\mu A_\mu \rightarrow j^\mu (A_\mu + \partial_\mu \Lambda) = j^\mu A_\mu + j^\mu (\partial_\mu \Lambda) \quad (1)$$

$$= j^\mu A_\mu + \partial_\mu (j^\mu \Lambda) = j^\mu A_\mu + \partial_\mu K^\mu,$$

$$\text{wg. } \partial_\mu j^\mu = 0. \quad \boxed{K^\mu = j^\mu \Lambda} \quad (1)$$

$$c) \varphi_{\text{Punkt}} = \frac{Q}{r} \quad (0,5) \quad - \frac{p}{r^2} < \varphi_{\text{Dip.}} < \frac{p}{r^2} \quad (0,5) \quad \left(\text{wg. } \varphi_{\text{Dip.}} = \frac{\vec{p} \cdot \vec{r}}{r^3} \right)$$

$$\Rightarrow \delta\varphi = \frac{\delta\varphi_{\text{Dip.}}}{\varphi_{\text{Punkt}}} = (p/r^2) / (Q/r) = \frac{p}{Qr} = \frac{3 \text{ Ccm}}{1 \text{ m}} = \underline{\underline{3\%}}$$

$$d) \text{Maxwell-Gl.: } \vec{\nabla} \cdot \vec{E} = \vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \times \vec{E} = -\partial_t \vec{B}, \quad \vec{\nabla} \times \vec{B} = \frac{1}{c^2} \partial_t \vec{E}$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \underbrace{\vec{\nabla} (\vec{\nabla} \cdot \vec{E})}_{=0} - \Delta \vec{E} \quad (\text{mit Hinweis}) = -\Delta \vec{E} \quad (0,5)$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \vec{\nabla} \times (-\partial_t \vec{B}) = -\frac{1}{c^2} \partial_t^2 \vec{E} \Rightarrow \left(\frac{1}{c^2} \partial_t^2 \vec{E} - \Delta \vec{E} \right) = 0 \quad (0,5)$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{B}) = -\Delta \vec{B} = \vec{\nabla} \times \left(\frac{1}{c^2} \partial_t \vec{E} \right) = -\frac{1}{c^2} \partial_t^2 \vec{B} \quad (0,5)$$

$$\Rightarrow \left(\frac{1}{c^2} \partial_t^2 - \Delta \right) \vec{B} = 0$$

$$e) j^\mu = (cs, \vec{j}) \text{ ist 4. Vektor} \quad (1)$$

$$\Rightarrow cs' = \gamma(cs - \beta j_x), \quad j_x' = \gamma(j_x - \beta cs),$$

$$j_y' = j_y, \quad j_z' = j_z \quad (1)$$

(*)

$$\epsilon_{ijk} \partial_j \epsilon_{klm} \partial_l E_m = (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) \partial_j \partial_l E_m = \partial_i (\partial_m E_m) - \partial_j^2 E_i$$

$$\begin{aligned}
 \underline{2} \quad p(\vec{r}) &= \delta(r-R) \sigma_0 (\cos^2 \theta - \frac{1}{2} \sin^2 \theta) \\
 &= \delta(r-R) \sigma_0 \left(\frac{3}{2} \cos^2 \theta - \frac{1}{2} \right) = \delta(r-R) \underbrace{\sigma_0 \sqrt{\frac{8\pi}{5}}}_{\equiv k} Y_{20} \\
 &= \delta(r-R) k Y_{20}(\theta) \equiv \delta(r-R) \sigma(\theta) \quad (1)
 \end{aligned}$$

$$\begin{aligned}
 a) \varphi(\vec{r}) &= \frac{1}{4\pi\epsilon_0} \int d^3r' \delta(r'-R) k Y_{20}(\theta') \\
 &\quad \times \sum_{l,m} \frac{4\pi}{2l+1} \frac{r_{<}^l}{r_{>}^{l+1}} Y_{lm}^*(\theta', \varphi') Y_{lm}(\theta, \varphi) \\
 &= \frac{1}{5\epsilon_0} \int_0^\infty dr' r'^2 \frac{r_{<}^2}{r_{>}^3} k \delta(r'-R) Y_{20}(\theta) \quad (1)
 \end{aligned}$$

Hier wurde die Orthogonalität d. Y_{lm} verwendet.

$$\underline{r < R:} \quad \varphi_{<}(\vec{r}) = \frac{1}{5\epsilon_0} \frac{r^2}{R} k Y_{20}(\theta) \equiv f(\theta) \frac{r^2}{R} \quad (1)$$

$$\underline{r > R:} \quad \varphi_{>}(\vec{r}) = \frac{1}{5\epsilon_0} \frac{R^4}{r^3} k Y_{20}(\theta) \equiv f(\theta) \frac{R^4}{r^3} \quad (1)$$

$$\begin{aligned}
 b) \vec{E}_{<}(\vec{r}) &= -\vec{\nabla} \varphi_{<}(\vec{r}) = -\frac{2}{R} \frac{r}{f(\theta)} \vec{e}_r - \frac{1}{R} \frac{r}{f(\theta)} \partial_\theta f(\theta) \vec{e}_\theta \quad (2) \\
 \vec{E}_{>}(\vec{r}) &= -\frac{3}{r^4} \frac{R^4}{f(\theta)} \vec{e}_r - \frac{1}{r^4} \frac{R^4}{f(\theta)} \partial_\theta f(\theta) \vec{e}_\theta \quad (2)
 \end{aligned}$$

c) Normalkomponente: $(\vec{e}_r \cdot \vec{e}_\theta = 0)$

$$\vec{e}_r \cdot (\vec{E}_{<} - \vec{E}_{>})|_{r=R} = -\frac{5}{R} f(\theta) = -\frac{\sigma(\theta)}{\epsilon_0} \quad (1)$$

Tangentiale Komponente:

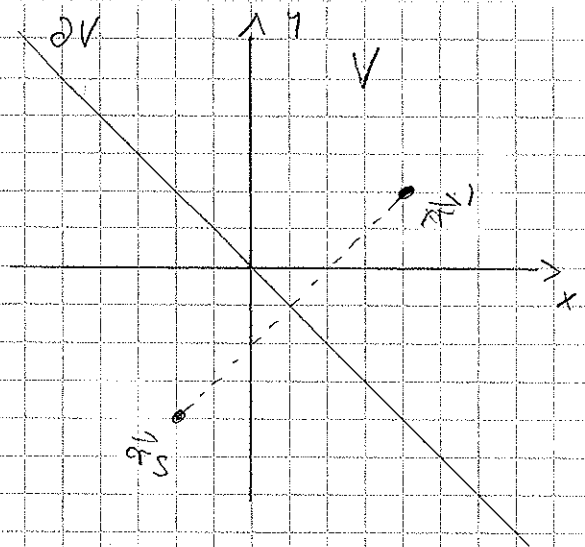
$$\vec{e}_r \times (\vec{E}_{<} - \vec{E}_{>})|_{r=R} = 0 \quad (1)$$

3) Allgemein:

Ladung q' bei $\vec{r}'$,

Spiegelladung $q_s = -q'$ bei

$\vec{r}_s$



a) Sei $q_s = -q'$ ①

$$\Rightarrow \Phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left[\frac{1}{\sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}} - \frac{1}{\sqrt{(x-x_s)^2 + (y-y_s)^2 + (z-z_s)^2}} \right] \quad ①$$

Sei $\Phi(\vec{r}) = 0$ für $x = -y$ ①

$$\Rightarrow \sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2} = \sqrt{(-y-x_s)^2 + (y-y_s)^2 + (z-z_s)^2}$$

$$\Rightarrow \boxed{x_s = -y', \quad y_s = -x', \quad z_s = z'} \quad ①$$

b) Sei Ladung q bei $\vec{r}' = (a, a, 0)^T$

$\Rightarrow$ Spiegelladung $-q$ bei $\vec{r}_s = (-a, -a, 0)^T$ ②

Man erhält:

$$\Phi_b(\vec{r}) = \frac{q}{4\pi\epsilon_0} \left[\frac{1}{((x-a)^2 + (y-a)^2 + z^2)^{1/2}} - \frac{1}{((x+a)^2 + (y+a)^2 + z^2)^{1/2}} \right] \quad ②$$

c) i) $\Phi_b(\vec{r}, \vec{r}')$ unverändert ②

$$\text{ii) } \Phi_c(\vec{r}) = \Phi_b(\vec{r}) + \Phi_0 \quad ②$$

$$4) \vec{A} = \frac{1}{2}(\vec{h} \times \vec{r}) = \frac{1}{2}[\vec{e}_x(h_y z - h_z y) + \vec{e}_y(h_z x - h_x z) + \vec{e}_z(h_x y - h_y x)]$$

$$a) \vec{B} = \vec{\nabla} \times \vec{A} = \frac{1}{2}[\vec{e}_x(2h_x) + \vec{e}_y(2h_y) + \vec{e}_z(2h_z)] = \vec{h} \quad \textcircled{2} \quad \textcircled{*}$$

$$b) h_x = h_y = 0, h = h_z \Rightarrow \vec{A} = \frac{1}{2}[(-h \cdot y)\vec{e}_x + h x \vec{e}_y] \quad \textcircled{2}$$

$$c) \vec{A}' = -h y \vec{e}_x \quad \textcircled{1}, \quad \vec{B}' = \vec{\nabla} \times \vec{A}' = -\vec{e}_z \partial_y A'_x = -h \vec{e}_z = \vec{B} \quad \textcircled{1}$$

$$d) \vec{A}' = \vec{A} - \vec{\nabla} \Lambda(\vec{r}) \Rightarrow \vec{\nabla} \Lambda(\vec{r}) = \vec{A} - \vec{A}' = \frac{1}{2}h y \vec{e}_x + \frac{1}{2}h x \vec{e}_y \Rightarrow \Lambda(\vec{r}) = \frac{1}{2}h(x y) \quad \textcircled{1}$$

⊗ Alternativ:

$$[\vec{\nabla} \times (\vec{h} \times \vec{r})]_i = \epsilon_{ijk} \partial_j \epsilon_{klm} h_l x_m = \epsilon_{ijk} \epsilon_{klm} h_l \delta_{jm}$$

$$= (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) h_l \delta_{jm}$$

$$= 3h_i - \delta_{ij} h_j = 3h_i - h_i = 2h_i$$

$$\Rightarrow \vec{\nabla} \times \frac{1}{2}(\vec{h} \times \vec{r}) = \vec{h}$$