

/1a)

$$\begin{aligned} Q_i &= \sum_{j=1}^2 C_{ij} \phi_j \\ \phi_i &= \sum_{j=1}^2 C_{ij}^{-1} Q_j \end{aligned} \quad \text{Sei } \underline{C} = \begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} \quad \vec{Q} = \begin{pmatrix} Q \\ -Q \end{pmatrix}$$

Da zwei Leiter vorhanden sind ist C_{ij} eine 2×2 Matrix

Für die skalare Kapazität gilt:

$$\bar{C} = \frac{Q}{U} = \frac{Q}{\phi_1 - \phi_2}$$

$$\begin{aligned} \phi_i &= C_{ij} Q_j \Rightarrow \begin{pmatrix} 1 \\ -1 \end{pmatrix} \vec{\phi} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \underline{C}^{-1} \vec{Q} \\ &\quad \text{Matrix} \\ \phi_1 - \phi_2 &= \begin{pmatrix} 1 \\ -1 \end{pmatrix} \frac{1}{\det \underline{C}} \begin{pmatrix} C_{22} - C_{12} \\ -C_{21} + C_{11} \end{pmatrix} \begin{pmatrix} Q \\ -Q \end{pmatrix} \\ &= \frac{1}{\det \underline{C}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} Q \begin{pmatrix} C_{22} + C_{12} \\ -C_{21} - C_{11} \end{pmatrix} \\ &= Q \frac{C_{22} + C_{12} + C_{21} + C_{11}}{\det \underline{C}} \\ \Rightarrow \frac{Q}{\phi_1 - \phi_2} &= \frac{C_{11} C_{22} - C_{12} C_{21}}{C_{22} + C_{12} + C_{21} + C_{11}} \stackrel{*}{=} \bar{C} \quad \checkmark \end{aligned}$$

b)

$$C = \epsilon_0 \epsilon_r \frac{A}{d} \stackrel{\text{in qts}}{\Rightarrow} [C] = 1 \cdot 1 \cdot \frac{\text{cm}^2}{\text{cm}} = \text{cm} \quad \checkmark$$

c)

 \vec{E} und ϕ sind aus Blatt 3 bekannt:

$$\vec{E} = \frac{Q}{2\pi\epsilon_0 r} \vec{e}_r \quad \text{falls } a \leq r \leq b$$

$$\vec{E} = 0 \quad \text{sonst}$$

$$\rho: \text{ Fall } b < r: \varphi(r) = 0$$

$$\text{Fall } a < r \leq b: \varphi(r) = -\frac{Q}{2\pi\epsilon_0 l} \left[\ln(r') \right]_a^r = \frac{Q}{2\pi\epsilon_0 l} \ln\left(\frac{b}{r}\right)$$

$$\text{Fall } r \leq a: \varphi(r) = -\frac{Q}{2\pi\epsilon_0 l} \left[\ln(r') \right]_a^r = \frac{Q}{2\pi\epsilon_0 l} \ln\left(\frac{b}{a}\right)$$

c).1

$$\begin{aligned} W &= \frac{\epsilon_0}{2} \int_V \vec{E}^2 dV' = \frac{\epsilon_0}{2} \int_0^l \int_0^{2\pi} \int_0^\infty \left(\frac{Q}{4\pi\epsilon_0 r'} \right)^2 \theta(r'-a) \theta(b-r') r' dr' d\varphi dz \\ &= \frac{\epsilon_0}{2l} \int_a^b \frac{Q^2}{2\pi\epsilon_0^2 r'} dr' = \frac{Q^2}{4\pi\epsilon_0 l} \left[\ln(r') \right]_a^b = \frac{Q^2}{4\pi\epsilon_0 l} \ln\left(\frac{b}{a}\right) \end{aligned}$$

$$\begin{aligned} W &= \frac{1}{2} \int_V \rho \varphi dV' = \frac{1}{2} \int_0^l \int_0^{2\pi} \int_0^\infty (\alpha \delta(r'-a) + \alpha \delta(r'-b)) \varphi(r') r' dr' d\varphi \quad \text{Mit } \alpha = \frac{Q}{2\pi l} \text{ bzw } \alpha = \frac{-Q}{2\pi l} \\ &= \pi l \left(\frac{Q}{2\pi l a} \varphi(a) a - \frac{Q}{2\pi l b} \varphi(b) b \right) \\ &= \frac{Q^2}{4\pi\epsilon_0 l} \ln\left(\frac{b}{a}\right) - 0 \quad \checkmark \end{aligned}$$

c).2 $W = \frac{1}{2} C U^2$

$$\begin{aligned} \Rightarrow C &= \frac{2W}{U^2} = \frac{Q^2}{2\pi\epsilon_0 l} \ln\left(\frac{b}{a}\right) \cdot \left(\frac{Q}{2\pi\epsilon_0 l} \ln\left(\frac{b}{a}\right) \right)^{-2} \\ &= 2\pi\epsilon_0 l \frac{1}{\ln\left(\frac{b}{a}\right)} \quad \checkmark \end{aligned}$$

c).3

$$C = 2\pi\epsilon_0 l \frac{1}{\ln\left(\frac{b}{a}\right)}$$

$$\ln\left(\frac{b}{a}\right) = \frac{2\pi\epsilon_0 l}{C}$$

$$b = a e^{\left(\frac{2\pi\epsilon_0 l}{C}\right)}$$

$$= 0,0005 \text{ m für } C = 3 \cdot 10^{11}$$

$$\text{oder } 0,00313 \text{ m} \hat{=} 3,13 \text{ mm für } C = 3 \cdot 10^{11}$$

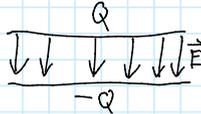
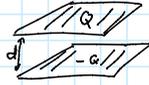
falls das gemeint war

d).1

$$\oint \vec{E} d\vec{f} = \frac{Q}{\epsilon_0}$$

$$E \cdot A + dA = \frac{Q}{\epsilon_0}$$

$$E = \frac{Q}{A\epsilon_0}$$



$$\Delta\phi = \left| -\int_0^d E \, dr' \right| = E d = \frac{Q d}{A\epsilon_0}$$

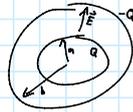
$$C = \frac{Q}{\Delta\phi} = \epsilon_0 \frac{A}{d} \quad \checkmark$$

d).2 $a < r < b$

$$\int_1 E dA' = \frac{Q}{\epsilon_0}$$

$$4\pi r^2 E = \frac{Q}{\epsilon_0}$$

$$E = \frac{Q}{4\pi\epsilon_0 r^2}$$



$$\Delta\phi = \left| -\int_a^b E dr' \right| = \left| \int_a^b \frac{Q}{4\pi\epsilon_0 r'^2} dr' \right|$$

$$= \left| \frac{Q}{4\pi\epsilon_0} \left[-\frac{1}{r'} \right]_a^b \right| = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$= \frac{Q}{4\pi\epsilon_0} \frac{b-a}{ab}$$

$$C = \frac{Q}{\Delta\phi} = 4\pi\epsilon_0 \frac{ab}{b-a} \quad \checkmark$$

/2 a)

$$\int_V dy^3 (\phi \nabla^2 \psi - \psi \nabla^2 \phi) = \oint_S d\vec{n} \left[\phi \frac{\partial \psi}{\partial n} - \psi \frac{\partial \phi}{\partial n} \right]$$

$$\int_V dy^3 \left(G(x,y) \left(-\frac{1}{\epsilon_0} \delta(x'-y)\right) - G(x',y) \left(-\frac{1}{\epsilon_0} \delta(x-y)\right) \right) = \oint_S \left[G(x,y) \frac{\partial G(x',y)}{\partial n} - G(x',y) \frac{\partial G(x,y)}{\partial n} \right]$$

$$-\frac{1}{\epsilon_0} G(x,x') + \frac{1}{\epsilon_0} G(x',x) = \oint_S \left[G(x,y) \frac{\partial G(x',y)}{\partial n} - G(x',y) \frac{\partial G(x,y)}{\partial n} \right]$$

$$G(x,x') - G(x',x) = -\epsilon_0 \oint_S \left[G(x,y) \frac{\partial G(x',y)}{\partial n} - G(x',y) \frac{\partial G(x,y)}{\partial n} \right]$$

b)

Aus der Definition von G folgt:

$$\nabla_{x'}^2 G_D(x, x') = -\frac{1}{\epsilon_0} \delta(x - x') \quad \delta(r - r') = -\frac{1}{4\pi} \Delta \frac{1}{|r - r'|}$$

$$\Delta G_D(x, x') = \frac{1}{4\pi\epsilon_0} \Delta \frac{1}{|x - x'|}$$

$$G_D(x, x') = \frac{1}{4\pi\epsilon_0} \frac{1}{|x - x'|} + f(x, x') \quad \text{Mit beliebigurf: } \Delta f(x, x') = 0 \text{ in } V$$

Dirichlet Randbedingung bedeutet $\varphi(x')$ ist auf S gegeben.

Man wähle $f(x, x')$ so, dass $G_D(x, x') = 0 \quad \forall x' \in S$

Dann gilt nach a):

$$\begin{aligned} G_D(x, x') - G_D(x', x) &= -\epsilon_0 \oint_{\partial V} \left[\overbrace{G_D(x, y)}^{=0 \forall y \in S} \frac{\partial G_D(x', y)}{\partial n} - \overbrace{G_D(x', y)}^{=0 \forall y \in S} \frac{\partial G_D(x, y)}{\partial n} \right] \\ &= -\epsilon_0 [0 - 0] \\ &= 0 \end{aligned}$$

Eine Differenz von 0 bedeutet, dass $G_D(x, x') = G_D(x', x)$

\Rightarrow Symmetrie

c)

$$\begin{aligned} G_W(x, x') - G_W(x', x) &= -\epsilon_0 \oint_S \left[G_W(x, y) \frac{\partial G_W(x', y)}{\partial n} - G_W(x', y) \frac{\partial G_W(x, y)}{\partial n} \right] \\ &= -\epsilon_0 \oint_S \left[-G_W(x, y) \frac{1}{\epsilon_0 S} + G_W(x', y) \frac{1}{\epsilon_0 S} \right] \\ &= \frac{1}{S} \oint_S \left[G_W(x, y) - G_W(x', y) \right] \end{aligned}$$

im Allgemeinen ungleich 0

\Rightarrow keine zwingende Symmetrie von $G_W(x, x')$ und $G_W(x', x)$

$$H(x, x') = G_D(x, x') - F(x)$$

$$\phi' = G_W(x, y) - F(x) = H(x, y) \quad \Psi' = G_W(x', y) - F(x') = H(x', y)$$

Damit $G_W(x, x') - F(x)$ noch eine die Poisson Gleichung löst, muss $\Delta(F(x)) = 0$ gelten. (siehe b))

Außerdem ist $F(x)$ unabhängig von y und es handelt sich um $\Delta_y F(x) = 0$

$$\int_V dy^3 (\phi' \nabla^2 \Psi - \Psi \nabla^2 \phi) = \int_S da \left[\Psi \frac{\partial \phi'}{\partial n} - \phi' \frac{\partial \Psi}{\partial n} \right]$$

$$\int_V dy^3 (\phi' (-\frac{1}{\epsilon_0} \delta(x-x') - \Delta F(x)) - \Psi (-\frac{1}{\epsilon_0} \delta(x-x') - \Delta F(x))) = \dots$$

$$-\frac{1}{\epsilon_0} H(x, x') + \frac{1}{\epsilon_0} H(x', x) + \int_V dy^3 (\Delta F(x) \Psi' - \Delta F(x) \phi') = \dots$$

$$-\frac{1}{\epsilon_0} (H(x, x') - H(x', x)) = \oint_S da \left[\phi' \frac{\partial (G_W(x', y) - F(x'))}{\partial n} - \Psi' \frac{\partial (G_W(x, y) - F(x))}{\partial n} \right]$$

$$= \oint_S da \left[\Psi' \left(\frac{1}{\epsilon_0} \frac{\partial F(x)}{\partial n} \right) - \phi' \left(\frac{\partial F(x)}{\partial n} - \frac{1}{\epsilon_0} \right) \right] \quad \text{Mit } da \cdot \vec{n} = d\vec{f}$$

$$-\frac{1}{\epsilon_0} (H(x, x') - H(x', x)) = -\frac{1}{\epsilon_0} \oint_S da \left[\Psi' - \phi' \right] + \oint_S d\vec{f} \left[\Psi' \Delta F(x) - \phi' \Delta F(x) \right]$$

$$H(x, x') - H(x', x) = \frac{1}{S} \oint_S da \left[\Psi' - \phi' \right]$$

$$= \frac{1}{S} \oint_S da \left[G(x', y) - F(x) - G(x, y) + F(x) \right]$$

$$= \frac{1}{S} \oint_S da \left[G(x', y) - G(x, y) \right] + \frac{1}{S} \oint_S d\vec{f} \left[F(x) - F(x) \right] \quad | \quad \oint_S d\vec{f} = S$$

$$= \frac{1}{S} \oint_S da \left[G(x', y) - G(x, y) \right] + F(x) - F(x)$$

$$= \frac{1}{S} \oint_S da \left[G(x', y) - G(x, y) \right] + \frac{1}{S} \oint_S da_y \left[G_W(x, y) - G_W(x', y) \right]$$

$$= \frac{1}{S} \oint_S da \left[G(x', y) - G(x, y) \right] - \frac{1}{S} \oint_S da \left[G(x', y) - G(x, y) \right]$$

$$= 0$$

\Rightarrow Symmetrie von $H(x, x') = G_W(x, x') - F(x)$

$$= \frac{1}{2} \oint da [G(x', y) - G(x, y)] - \frac{1}{2} \oint da [G(x', y) - G(x, y)]$$

$$= 0 \Rightarrow \text{Symmetrie von } H(x, x') = G_W(x, x') - F(x)$$

d)

Aus Vorlesung:

$$\varphi_E(x) = \int_V dx'^3 \rho(x') G(x, x') - \epsilon_0 \oint_S da \left[\varphi(x') \frac{\partial G(x, x')}{\partial n} - G(x, x') \frac{\partial \varphi(x')}{\partial n} \right]$$

ersetze $G(x, x')$ mit $H(x, x') = G(x, x') - F(x)$. Dann gilt für $\varphi(x) = \varphi_H(x)$:

$$\varphi_H(x) = \int_V dx'^3 \rho(x') H(x, x') - \epsilon_0 \oint_S da \left[\varphi(x') \frac{\partial H(x, x')}{\partial n} - H(x, x') \frac{\partial \varphi(x')}{\partial n} \right]$$

φ_H ist die Summe der folgenden 3 Integrale:

1. Integral: $\int_V dx'^3 \rho(x') H(x, x') = \int_V dx'^3 \rho(x') G(x, x') - \int_V dx'^3 \rho(x') F(x)$

2. Integral: $-\epsilon_0 \oint_S da \varphi(x') \frac{\partial H(x, x')}{\partial n} = -\epsilon_0 \oint_S da \varphi(x') \left[\frac{\partial G(x, x')}{\partial n} - \frac{\partial F(x)}{\partial n} \right]$

$$= -\epsilon_0 \oint_S da \varphi(x') \frac{\partial G(x, x')}{\partial n}$$

3. Integral: $\epsilon_0 \oint_S da H(x, x') \frac{\partial \varphi(x')}{\partial n} = -\epsilon_0 \oint_S da F(x) \frac{\partial \varphi(x')}{\partial n} + \epsilon_0 \oint_S da G(x, x') \frac{\partial \varphi(x')}{\partial n}$

$$= -\epsilon_0 \oint_S d\vec{f} F(x) \nabla \varphi(x') + \epsilon_0 \oint_S da G(x, x') \frac{\partial \varphi(x')}{\partial n}$$

$$\stackrel{\text{Gauss}}{=} -\epsilon_0 \int_V dx'^3 F(x) \Delta \varphi(x') + \epsilon_0 \oint_S da G(x, x') \frac{\partial \varphi(x')}{\partial n}$$

$$= \int_V dx'^3 F(x) \rho(x') + \epsilon_0 \oint_S da G(x, x') \frac{\partial \varphi(x')}{\partial n}$$

Die Summe aller drei Integrale ergibt:

$$\varphi_H(x) = \int_V dx'^3 \rho(x') G(x, x') - \int_V dx'^3 \rho(x') F(x) - \epsilon_0 \oint_S da \varphi(x') \frac{\partial G(x, x')}{\partial n} + \int_V dx'^3 F(x) \rho(x') + \epsilon_0 \oint_S da G(x, x') \frac{\partial \varphi(x')}{\partial n}$$

$$= \varphi_G(x)$$

Also bleibt das Potential unverändert

3a)

$$W = \frac{1}{2} C \phi_0^2 = \frac{\epsilon_0}{2} \int_{\mathbb{R}^3} F^2 dx^3 \quad \text{Näherung: Äußeres E-Feld kann vernachlässigt werden}$$

$$= \frac{\epsilon_0}{2} \int_V E^2 dx^3$$

$$= \frac{\epsilon_0}{2} \int_V (\nabla \phi)^2 dx^3$$

$$\Rightarrow C = \frac{\epsilon_0}{\phi_0^2} \int_V (\nabla \phi)^2 dx^3$$

Man kann nun $\phi_0^2 = 1$ setzen und erhält die Annahme, allerdings stimmen dann die Einheiten nicht mehr. ✓

b) $\Psi = \phi + \delta\psi$

$$\epsilon_0 \int_V |\nabla \Psi|^2 dx^3$$

$$= \epsilon_0 \int_V |\nabla \phi|^2 dx^3 + 2\epsilon_0 \int_V \nabla \phi \nabla \delta\psi dx^3 + \epsilon_0 \int_V |\nabla \delta\psi|^2 dx^3 \quad | \text{1. Gren}$$

$$= C - \underbrace{2\epsilon_0 \int_V (\Delta \phi) \delta\psi dx^3}_{=0} + \underbrace{2 \int_V \delta\psi \frac{\partial \phi}{\partial n} da}_{=0} + \underbrace{\epsilon_0 \int_V |\nabla \delta\psi|^2 dx^3}_{\geq 0} \geq C \quad \square \quad \checkmark$$