

$$a) \quad \vec{\nabla} \times (\vec{\nabla} \phi) = \vec{0}$$

$$(\vec{\nabla} \times (\vec{\nabla} \phi))_i = \epsilon_{ijk} \partial_j \partial_k \phi = \frac{1}{2} (\epsilon_{ijk} \partial_j \partial_k + \epsilon_{ijk} \partial_j \partial_k) \phi \\ = \frac{1}{2} (\epsilon_{ijk} \partial_j \partial_k - \epsilon_{ikj} \partial_j \partial_k) \phi = \frac{1}{2} (\epsilon_{ijk} \partial_j \partial_k - \epsilon_{ijk} \partial_k \partial_j) \phi = \frac{1}{2} (\epsilon_{ijk} \partial_j \partial_k - \epsilon_{ijk} \partial_j \partial_k) \phi = 0$$

$$b) \quad \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A})_i = \vec{\nabla} \cdot (\epsilon_{ijk} \partial_j A_k) = \partial_i \epsilon_{ijk} \partial_j A_k = \epsilon_{ijk} \partial_i \partial_j A_k = -\epsilon_{jik} \partial_j \partial_i A_k$$

$$\Rightarrow \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$$

(2)

hier fehlt ein Argument
→ warum folgt jetzt die Null?

$$c) \quad \epsilon_{ijk} \epsilon_{kmn} = \delta_{im} \delta_{jn} - \delta_{in} \delta_{jm} \quad (*)$$

$$\vec{\nabla} \cdot [\vec{\nabla} \times (\vec{\nabla} \times \vec{A})]_i = \partial_i (\partial_j A_j) - \partial_j^2 A_i = \vec{\nabla} \cdot (\vec{\nabla} \vec{A}) - \Delta \vec{A}$$

$$[\vec{\nabla} \times (\vec{\nabla} \times \vec{A})]_i = \epsilon_{ijk} \partial_j (\vec{\nabla} \times \vec{A})_k = \epsilon_{ijk} \partial_j \epsilon_{kmn} \partial_m A_n$$

$$= \epsilon_{ijk} \epsilon_{kmn} \partial_j \partial_m A_n \stackrel{(*)}{=} (\delta_{im} \delta_{jn} - \delta_{in} \delta_{jm}) \partial_j \partial_m A_n$$

$$= \delta_{im} \delta_{jn} \partial_j \partial_m A_n - \delta_{in} \delta_{jm} \partial_j \partial_m A_n$$

$$= \partial_n \partial_i A_n - \partial_m \partial_m A_i = \partial_n \partial_i A_n - \partial_m^2 A_i = \vec{\nabla} \cdot (\vec{\nabla} \vec{A}) - \Delta \vec{A}$$

(2)

$$\textcircled{2} \quad \begin{aligned} x &= \rho \cos \varphi \\ y &= \rho \sin \varphi \\ z &= z \end{aligned} \quad \vec{v}_i = \partial_i \vec{r} \quad \vec{r} = x \hat{e}_x + y \hat{e}_y + z \hat{e}_z, \quad i \in \{\rho, \varphi, z\}$$

$$a) \quad \vec{v}_i = \partial_i (x \hat{e}_x + y \hat{e}_y + z \hat{e}_z) = \partial_i (\rho \cos \varphi \hat{e}_x + \rho \sin \varphi \hat{e}_y + z \hat{e}_z)$$

$$\vec{v}_\rho = \cos \varphi \hat{e}_x + \sin \varphi \hat{e}_y, \quad |\vec{v}_\rho| = \sqrt{\cos^2 \varphi + \sin^2 \varphi} = 1$$

$$\vec{v}_\varphi = -\rho \sin \varphi \hat{e}_x + \rho \cos \varphi \hat{e}_y, \quad |\vec{v}_\varphi| = \sqrt{\rho^2 \sin^2 \varphi + \rho^2 \cos^2 \varphi} = \rho$$

$$\vec{v}_z = \hat{e}_z, \quad |\vec{v}_z| = 1$$

$$\Rightarrow \hat{e}_\rho = \frac{\vec{v}_\rho}{|\vec{v}_\rho|} = \cos\varphi \hat{e}_x + \sin\varphi \hat{e}_y \quad \checkmark$$

$$\hat{e}_\varphi = \frac{\vec{v}_\varphi}{|\vec{v}_\varphi|} = -\sin\varphi \hat{e}_x + \cos\varphi \hat{e}_y \quad \checkmark$$

$$\hat{e}_z = \hat{e}_z \quad //$$

(5)

b) • $\hat{e}_x = \cos\varphi \hat{e}_\rho - \sin\varphi \hat{e}_\varphi$ *naja, also das selbst du ausrechnen und verifizieren*

$$= \cos^2\varphi \hat{e}_x + \sin\varphi \cos\varphi \hat{e}_y + \sin^2\varphi \hat{e}_x - \sin\varphi \cos\varphi \hat{e}_y = \hat{e}_x$$

$$\bullet \hat{e}_y = \sin\varphi \hat{e}_\rho + \cos\varphi \hat{e}_\varphi = \sin\varphi \cos\varphi \hat{e}_x + \sin^2\varphi \hat{e}_y - \cos\varphi \sin\varphi \hat{e}_x + \cos^2\varphi \hat{e}_y = \hat{e}_y$$

$$\bullet \hat{e}_z = \hat{e}_z \quad //$$

c) z: $\partial_x \phi = \left(\cos\varphi \partial_\rho - \frac{\sin\varphi}{\rho} \partial_\varphi \right) \phi$

$$\partial_y \phi = \left(\sin\varphi \partial_\rho + \frac{\cos\varphi}{\rho} \partial_\varphi \right) \phi$$

$$\partial_i \phi = \left(\frac{\partial \phi}{\partial x} \frac{\partial x}{\partial i} + \frac{\partial \phi}{\partial y} \frac{\partial y}{\partial i} \right), \quad i \in \{r, \varphi\}$$

$$(1) \partial_\rho \phi = \frac{\partial \phi}{\partial x} \frac{\partial x}{\partial \rho} + \frac{\partial \phi}{\partial y} \frac{\partial y}{\partial \rho} = \frac{\partial \phi}{\partial x} \frac{\partial(\rho \cos\varphi)}{\partial \rho} + \frac{\partial \phi}{\partial y} \frac{\partial(\rho \sin\varphi)}{\partial \rho}$$

$$= \frac{\partial \phi}{\partial x} \cos\varphi + \frac{\partial \phi}{\partial y} \sin\varphi$$

$$(2) \partial_\varphi \phi = \frac{\partial \phi}{\partial x} \frac{\partial x}{\partial \varphi} + \frac{\partial \phi}{\partial y} \frac{\partial y}{\partial \varphi} = \frac{\partial \phi}{\partial x} \frac{\partial(\rho \cos\varphi)}{\partial \varphi} + \frac{\partial \phi}{\partial y} \frac{\partial(\rho \sin\varphi)}{\partial \varphi}$$

$$= -\frac{\partial \phi}{\partial x} \rho \sin\varphi + \frac{\partial \phi}{\partial y} \rho \cos\varphi$$

Ans (1) folgt: $(\partial_\rho \phi - \partial_y \phi \sin\varphi) \cdot \frac{1}{\cos\varphi} = \partial_x \phi$

Ans (2) folgt: $(\partial_\varphi \phi + \partial_x \phi \rho \sin\varphi) \cdot \frac{1}{\rho \cos\varphi} = \partial_y \phi$

$$(1) \text{ in } (2) \quad (\partial_\varphi \phi + (\partial_\rho \phi - \partial_y \phi \sin \varphi) \frac{1}{\cos \varphi} \rho \sin \varphi) \cdot \frac{1}{\rho \cos \varphi} = \partial_y \phi$$

$$\Leftrightarrow \frac{\partial_\varphi \phi}{\rho \cos \varphi} + \partial_\rho \phi \frac{\rho \sin \varphi}{\rho \cos^2 \varphi} - \partial_y \phi \frac{\rho \sin^2 \varphi}{\rho \cos^2 \varphi} = \partial_y \phi$$

$$\Leftrightarrow \frac{\partial_\varphi \phi}{\rho \cos \varphi} + \partial_\rho \phi \frac{\sin \varphi}{\cos^2 \varphi} = \partial_y \phi \left(\frac{\sin^2 \varphi}{\cos^2 \varphi} + 1 \right)$$

$$\Leftrightarrow \frac{\partial_\varphi \phi}{\rho \cos \varphi} \cdot \frac{1}{\frac{\sin^2 \varphi + \cos^2 \varphi}{\cos^2 \varphi}} + \partial_\rho \phi \frac{\sin \varphi}{\cos^2 \varphi} \cdot \frac{1}{\frac{\sin^2 \varphi + \cos^2 \varphi}{\cos^2 \varphi}} = \partial_y \phi$$

$$\Leftrightarrow \frac{\partial_\varphi \phi}{\rho \cos \varphi} \cdot \frac{\cos^2 \varphi}{\underbrace{\sin^2 \varphi + \cos^2 \varphi}_{=1}} + \partial_\rho \phi \frac{\sin \varphi}{\cos^2 \varphi} \cdot \frac{\cos^2 \varphi}{\underbrace{\sin^2 \varphi + \cos^2 \varphi}_{=1}} = \partial_y \phi$$

$$\Leftrightarrow \partial_\varphi \phi \frac{\cos \varphi}{\rho} + \partial_\rho \phi \sin \varphi = \partial_y \phi$$

$$\Leftrightarrow (\sin \varphi \partial_\rho + \frac{\cos \varphi}{\rho} \partial_\varphi) \phi \quad \checkmark$$

Einsetzen in (1):

$$(\partial_\rho \phi - \partial_y \phi \sin \varphi) \cdot \frac{1}{\cos \varphi} = \partial_x \phi$$

$$\Leftrightarrow (\partial_\rho \phi - (\partial_\varphi \phi \frac{\cos \varphi}{\rho} + \partial_\rho \phi \sin \varphi) \sin \varphi) \frac{1}{\cos \varphi} = \partial_x \phi$$

$$\Leftrightarrow \frac{\partial_\rho \phi}{\cos \varphi} - \left(\partial_\varphi \phi \frac{\cos \varphi \sin \varphi}{\rho \cos \varphi} + \frac{\partial_\rho \phi \sin^2 \varphi}{\cos \varphi} \right) = \partial_x \phi$$

$$\Leftrightarrow \frac{\partial_\rho \phi}{\cos \varphi} - \partial_\varphi \phi \frac{\sin \varphi}{\rho} - \partial_\rho \phi \frac{\sin^2 \varphi}{\cos \varphi} = \partial_x \phi$$

$$\Leftrightarrow \partial_\rho \phi \left(\frac{1 - \sin^2 \varphi}{\cos \varphi} \right) - \partial_\varphi \phi \frac{\sin \varphi}{\rho} = \partial_x \phi \quad \left| \quad 1 - \sin^2 \varphi = \cos^2 \varphi \right.$$

$$\Leftrightarrow \partial_\rho \phi \cos\varphi - \partial_\varphi \phi \frac{\sin\varphi}{\rho} = \partial_x \phi$$

$$\Leftrightarrow (\cos\varphi \partial_\rho - \frac{\sin\varphi}{\rho} \partial_\varphi) \phi = \partial_x \phi \quad \checkmark$$

(5)

$$d) \vec{\nabla} \phi = (\hat{e}_x \partial_x + \hat{e}_y \partial_y + \hat{e}_z \partial_z) \phi$$

$$\vec{\nabla} \phi = ((\cos\varphi \hat{e}_\rho - \sin\varphi \hat{e}_\varphi) \partial_x + (\sin\varphi \hat{e}_\rho + \cos\varphi \hat{e}_\varphi) \partial_y + \hat{e}_z \partial_z) \phi$$

$$= (\cos\varphi \hat{e}_\rho - \sin\varphi \hat{e}_\varphi) (\cos\varphi \partial_\rho - \frac{\sin\varphi}{\rho} \partial_\varphi) \phi + (\sin\varphi \hat{e}_\rho + \cos\varphi \hat{e}_\varphi) (\sin\varphi \partial_\rho + \frac{\cos\varphi}{\rho} \partial_\varphi) \phi + (\hat{e}_z \partial_z) \phi$$

$$= (\cos^2\varphi \hat{e}_\rho \partial_\rho - \frac{\cos\varphi \sin\varphi}{\rho} \hat{e}_\rho \partial_\varphi - \frac{\sin\varphi \cos\varphi}{\rho} \hat{e}_\varphi \partial_\rho + \frac{\sin^2\varphi}{\rho} \hat{e}_\varphi \partial_\varphi + \sin^2\varphi \hat{e}_\rho \partial_\rho + \frac{\sin\varphi \cos\varphi}{\rho} \hat{e}_\rho \partial_\varphi + \frac{\cos\varphi \sin\varphi}{\rho} \hat{e}_\varphi \partial_\rho + \frac{\cos^2\varphi}{\rho} \hat{e}_\varphi \partial_\varphi + \hat{e}_z \partial_z) \phi$$

$$= (\hat{e}_\rho \partial_\rho + \frac{\hat{e}_\varphi}{\rho} \partial_\varphi + \hat{e}_z \partial_z) \phi \quad \checkmark$$

(5)

$$e) \vec{\nabla} \cdot \vec{A} = \frac{1}{\rho} \partial_r (\rho A_r) + \frac{1}{\rho} \partial_\varphi A_\varphi + \partial_z A_z, \quad A_\alpha = \hat{e}_\alpha \cdot \vec{A}$$

$$\vec{\nabla} \cdot \vec{A} = \partial_x A_x + \partial_y A_y + \partial_z A_z$$

$$= (\cos\varphi \partial_r - \frac{\sin\varphi}{\rho} \partial_\varphi) \cdot ((\cos\varphi \hat{e}_r - \sin\varphi \hat{e}_\varphi) \cdot \vec{A}) \\ + (\sin\varphi \partial_r + \frac{\cos\varphi}{\rho} \partial_\varphi) ((\sin\varphi \hat{e}_r + \cos\varphi \hat{e}_\varphi) \cdot \vec{A}) + \partial_z (\hat{e}_z \cdot \vec{A})$$

$$= (\cos\varphi \partial_r - \frac{\sin\varphi}{\rho} \partial_\varphi) (\cos\varphi A_r - \sin\varphi A_\varphi) \\ + (\sin\varphi \partial_r + \frac{\cos\varphi}{\rho} \partial_\varphi) (\sin\varphi A_r + \cos\varphi A_\varphi) + \partial_z A_z$$

$$= \cos^2 \partial_r A_r - \cancel{\cos\varphi \sin\varphi \partial_r A_r} - \frac{\sin\varphi \cos\varphi}{\rho} \partial_\varphi A_r + \frac{\sin^2 \varphi}{\rho} \partial_\varphi A_\varphi \\ + \sin^2 \varphi \partial_r A_r + \cancel{\sin\varphi \cos\varphi \partial_r A_r} + \frac{\cos\varphi \sin\varphi}{\rho} \partial_\varphi A_r \\ + \frac{\cos^2 \varphi}{\rho} \partial_\varphi A_\varphi + \partial_z A_z$$

$$= \partial_r A_r + \frac{1}{\rho} \partial_\varphi A_\varphi + \partial_z A_z$$

$$= \frac{1}{\rho} \partial_r (\rho A_r) + \frac{1}{\rho} \partial_\varphi A_\varphi + \partial_z A_z \quad \checkmark$$

(5)

$$f) (\vec{\nabla} \times \vec{A})_z = \partial_x A_y - \partial_y A_x$$

$$\vec{z} \cdot (\vec{\nabla} \times \vec{A})_z = \frac{1}{\rho} [\partial_r (\rho A_\varphi) - \partial_\varphi A_r]$$

$$\partial_x A_y - \partial_y A_x = (\cos\varphi \partial_r - \frac{\sin\varphi}{\rho} \partial_\varphi) A_y - (\sin\varphi \partial_r + \frac{\cos\varphi}{\rho} \partial_\varphi) A_x \\ = (\cos\varphi \partial_r - \frac{\sin\varphi}{\rho} \partial_\varphi) ((\sin\varphi \hat{e}_r + \cos\varphi \hat{e}_\varphi) \cdot \vec{A}) - (\sin\varphi \partial_r + \frac{\cos\varphi}{\rho} \partial_\varphi) \\ \cdot ((\cos\varphi \hat{e}_r - \sin\varphi \hat{e}_\varphi) \cdot \vec{A})$$

$$= (\cos \varphi \partial_r - \frac{\sin \varphi}{r} \partial_\varphi) (\sin \varphi A_r + \cos \varphi A_\varphi) - (\sin \varphi \partial_r + \frac{\cos \varphi}{r} \partial_\varphi) \cdot (\cos \varphi A_r - \sin \varphi A_\varphi)$$

$$= \cancel{\cos \varphi \sin \varphi \partial_r A_r} + \cos^2 \varphi \partial_r A_r - \frac{\sin^2 \varphi}{r} \partial_\varphi A_r - \cancel{\frac{\sin \varphi \cos \varphi}{r} \partial_\varphi A_\varphi} - \cancel{\sin \varphi \cos \varphi \partial_r A_r} + \sin^2 \varphi \partial_r A_r - \frac{\cos^2 \varphi}{r} \partial_\varphi A_r + \cancel{\frac{\cos \varphi \sin \varphi}{r} \partial_\varphi A_\varphi}$$

$$= (\underbrace{\cos^2 \varphi + \sin^2 \varphi}_{=1}) \partial_r A_r - \frac{1}{r} (\underbrace{\sin^2 \varphi + \cos^2 \varphi}_{=1}) \partial_\varphi A_\varphi$$

$$= \partial_r A_r - \frac{1}{r} \partial_\varphi A_\varphi = \frac{1}{r} [\partial_r (r A_r) - \partial_\varphi A_\varphi] \quad \checkmark \quad (5)$$

$$g) \phi(\vec{r}) = \frac{1}{\sqrt{x^2 + y^2}} = \frac{1}{\sqrt{\rho^2 (\cos^2 \varphi + \sin^2 \varphi)}} = \frac{1}{\sqrt{\rho^2 (\underbrace{\cos^2 \varphi + \sin^2 \varphi}_{=1})}} = \frac{1}{\rho} \quad \checkmark$$

$$\vec{\nabla} \phi^{(3)} = (\hat{e}_r \partial_r + \frac{\hat{e}_\varphi}{r} \partial_\varphi + \hat{e}_z \partial_z) \frac{1}{\rho}$$

$$= \hat{e}_r \partial_r \frac{1}{\rho} = -\hat{e}_r \cdot \frac{1}{\rho^2} \quad \checkmark$$

$$\vec{\nabla} (\vec{\nabla} \phi) = \vec{\nabla} \left(-\hat{e}_r \frac{1}{\rho^2} \right) \stackrel{(4)}{=} \frac{1}{\rho} \partial_r (r \hat{e}_r (-\hat{e}_r \frac{1}{\rho^2})) + \frac{1}{\rho} \partial_\varphi (\hat{e}_\varphi (-\hat{e}_r \frac{1}{\rho^2})) + \partial_z (\hat{e}_z \cdot (-\hat{e}_r \frac{1}{\rho^2}))$$

$$= \frac{1}{\rho} \partial_r \left(-\frac{1}{\rho} \right) = \frac{1}{\rho} \cdot \frac{1}{\rho^2} = \frac{1}{\rho^3} \quad \checkmark$$

$$(\vec{\nabla} \times (\vec{\nabla} \phi))_z = \frac{1}{\rho} [\partial_r (r \hat{e}_\varphi (-\hat{e}_r \cdot \frac{1}{\rho^2})) - \partial_\varphi (\hat{e}_r (-\hat{e}_r \cdot \frac{1}{\rho^2}))]$$

$$= \frac{1}{\rho} \partial_\varphi \frac{1}{\rho^2} = 0 \quad \checkmark \quad (11)$$

$$h) \vec{A}(\vec{r}) = (x^2 + y^2)^{\frac{n}{2}} (x \hat{e}_y - y \hat{e}_x)$$

$$= (\rho^2 \cos^2 \varphi + \rho^2 \sin^2 \varphi)^{\frac{n}{2}} (\rho \cos \varphi (\sin \varphi \hat{e}_r + \cos \varphi \hat{e}_\varphi) - \rho \sin \varphi (\cos \varphi \hat{e}_r - \sin \varphi \hat{e}_\varphi))$$

$$= (\rho^2)^{\frac{n}{2}} \cdot (\rho \cos \varphi \sin \varphi \hat{e}_\rho + \rho \cos^2 \varphi \hat{e}_\varphi - \rho \sin \varphi \cos \varphi \hat{e}_\rho + \rho \sin^2 \varphi \hat{e}_\varphi)$$

$$= \rho^{n+1} \hat{e}_\varphi$$

$$\vec{\nabla} \vec{A} = \frac{1}{\rho} \partial_\rho (\rho \hat{e}_\rho \cdot \rho^{n+1} \hat{e}_\varphi) + \frac{1}{\rho} \partial_\varphi (\hat{e}_\varphi \cdot \rho^{n+1} \hat{e}_\varphi) + \partial_z (\hat{e}_z \cdot \rho^{n+1} \hat{e}_\varphi)$$

$$= \frac{1}{\rho} \partial_\rho \rho^{n+1} = 0$$

$$(\vec{\nabla} \times \vec{A})_z = \frac{1}{\rho} [\partial_\rho (\rho \hat{e}_\varphi \cdot \rho^{n+1} \hat{e}_\varphi) - \partial_\varphi \hat{e}_\rho \cdot \rho^{n+1} \hat{e}_\varphi]$$

$$= \frac{1}{\rho} \partial_\rho \rho^{n+2} = \begin{cases} \frac{1}{\rho} (n+2) \cdot \rho^{n+1} = (n+2) \rho^n & n \neq -2 \\ 0 & \text{für } n = -2 \end{cases}$$

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$$\textcircled{3} a) \vec{A}(\vec{r}) = \rho^n (\cos \alpha \hat{e}_\rho + \sin \alpha \hat{e}_\varphi)$$

$$\oint_{\partial F} \vec{A} d\vec{r} = \oint_{\partial F} R^n (\cos \alpha \hat{e}_\rho + \sin \alpha \hat{e}_\varphi) \hat{e}_\varphi R d\varphi$$

$$= \oint_{\partial F} R^n \sin \alpha R d\varphi = 2\pi R^{n+1} \sin \alpha \quad \checkmark$$

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$$b) \int_F (\vec{\nabla} \times \vec{A}) d\vec{f} = \int_0^R \int_0^{2\pi} (\vec{\nabla} \times \vec{A}) \cdot \hat{e}_z \rho d\varphi d\rho = \int_0^R \int_0^{2\pi} [\vec{\nabla} \times \vec{A}]_z \rho d\varphi d\rho$$

$$\stackrel{(5)}{=} \int_0^R \int_0^{2\pi} \frac{1}{\rho} [\partial_\rho (\rho A_\varphi) - \partial_\varphi A_\rho] \rho d\varphi d\rho$$

$$= \int_0^R \int_0^{2\pi} \frac{1}{\rho} [\partial_\rho (\rho \rho^n \sin \alpha) - \partial_\varphi (\rho \rho^n \cos \alpha)] \rho d\varphi d\rho = \begin{cases} \dots \text{für } n \neq -1 \\ 0 & \text{für } n = -1 \end{cases}$$

$$= \int_0^R \int_0^{2\pi} \sin \alpha (n+1) \rho^n \, d\varphi \, d\rho = \int_0^R 2\pi \sin \alpha (n+1) \rho^n \, d\rho \quad (8)$$

$$= \left[2\pi \sin \alpha \rho^{n+1} \right]_0^R = 2\pi \sin \alpha R^{n+1} \quad \text{für } n \neq -1$$

$$= 0 \quad \text{für } n = -1$$

$\Rightarrow$ Gleiches Ergebnis wie in a) für $n \neq -1$

$$c) \oint_{\partial V} \vec{A} \, d\vec{S} = \oint_{\partial V} R^n (\cos \alpha \hat{e}_\rho + \sin \alpha \hat{e}_\varphi) \hat{e}_\rho \, R \, d\varphi$$

$$= \oint_{\partial V} R^{n+1} \cos \alpha \, d\varphi = 2\pi R^{n+1} \cos \alpha \quad (4)$$

$$d) \int_V (\vec{\nabla} \cdot \vec{A}) \, dV = \int_V \left(\frac{1}{\rho} \partial_\rho (\rho A_\rho) + \frac{1}{\rho} \partial_\varphi A_\varphi + \partial_z A_z \right) \rho \, d\rho \, d\varphi$$

$$= \int_0^{2\pi} \int_0^R \left(\partial_\rho \rho^{n+1} \cos \alpha + \frac{1}{\rho} \partial_\varphi \rho^n \sin \alpha \right) d\rho \, d\varphi = \begin{cases} \dots & \text{für } n \neq -1 \\ 0 & \text{für } n = -1 \end{cases}$$

$$= \int_0^{2\pi} \int_0^R (n+1) \rho^n \cos \alpha \, d\rho \, d\varphi = \int_0^{2\pi} 2\pi (n+1) \rho^n \cos \alpha \, d\rho$$

$$= \left[\rho^{n+1} \cos \alpha \right]_0^R = 2\pi R^{n+1} \cos \alpha \quad (8)$$

$$= 0 \quad \text{für } n = -1$$

$\Rightarrow$ gleiches Ergebnis wie in c) für $n \neq -1$ wie oben