

$$\textcircled{1} \quad \int_{-\infty}^{\infty} dx \, \delta(x-x_0) f(x) = f(x_0), \quad \int_{-\infty}^{\infty} dx \, \delta(x-x_0) = 1$$

a) (i) $\mathbb{Z}: \delta(-x) = \delta(x)$

$$\begin{aligned} \int_{-\infty}^{\infty} dx \, \delta(-x) f(x) &= \int_{-\infty}^{\infty} dy \, \delta(x) f(-y) \quad \left| \text{subst. } y = -x \right. \\ &= \int_{-\infty}^{\infty} dy \, \delta(x) f(-y) = f(0) = \int_{-\infty}^{\infty} dx \, \delta(x) f(x) \quad \checkmark \end{aligned}$$

(ii) $\mathbb{Z}: x \delta(x) = 0$

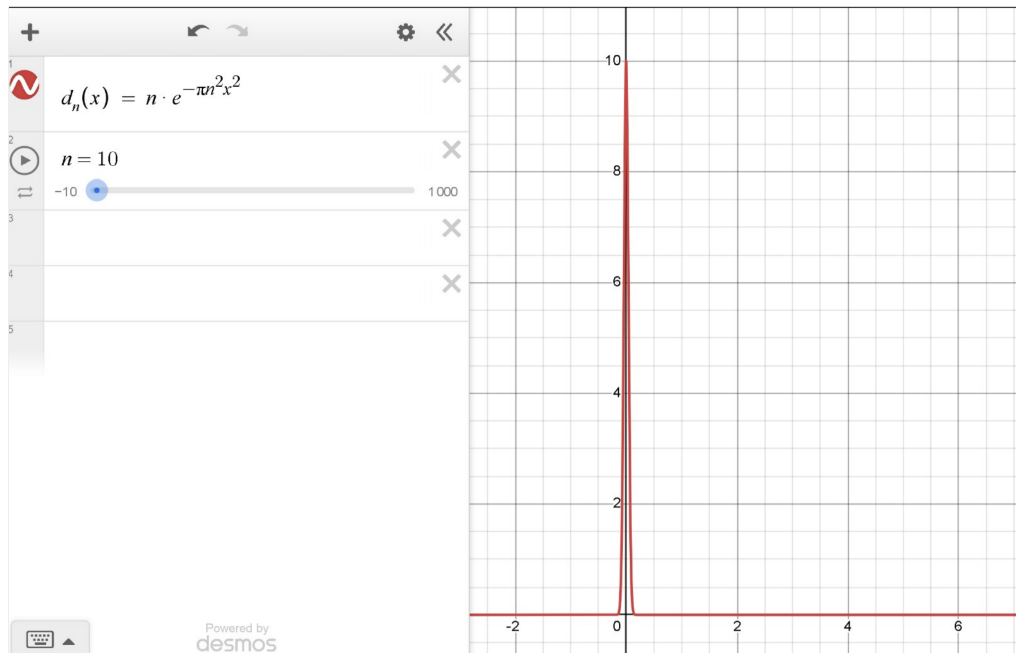
$$\int_{-\infty}^{\infty} dx \, \delta(x) f(x) \quad \text{mit } f(x) = x: \int_{-\infty}^{\infty} dx \, \delta(x) x = 0 \Leftrightarrow \delta(x) x = 0$$

(iii) $\mathbb{Z}: \delta(ax) = \frac{1}{|a|} \delta(x)$

$$\begin{aligned} \int_{-\infty}^{\infty} dx \, \delta(ax) f(x) &= \int_{-\infty}^{\infty} dy \, \frac{1}{|a|} \delta(y) f\left(\frac{y}{a}\right) = \frac{1}{|a|} f(0) \quad \left| \text{subst. } \begin{array}{l} ax = y \\ x = \frac{y}{a} \\ dx = \frac{dy}{a} \end{array} \right. \\ &= \int_{-\infty}^{\infty} dx \, \frac{1}{|a|} \delta(x) f(x) \quad \checkmark \end{aligned}$$

b) $f(x) = \lim_{n \rightarrow \infty} f_n(x)$ mit $f_n(x) = n \cdot e^{-\pi n^2 x^2}$

Für $n = 10$:



$$\int_{-\infty}^{\infty} dx f_n(x) = \int_{-\infty}^{\infty} dx n e^{-\pi n^2 x^2} = \int_{-\infty}^{\infty} du \frac{e^{-u^2}}{\sqrt{\pi}} \quad \left| \begin{array}{l} \text{Subst. } u = \sqrt{\pi} n x, du = \sqrt{\pi} n dx \\ \Leftrightarrow dx = \frac{du}{\sqrt{\pi} n} \end{array} \right.$$

Über die Definition des Gaußintegrals $\int_{-\infty}^{\infty} du e^{-u^2} = \sqrt{\pi}$ erhalten wir:

$$\int_{-\infty}^{\infty} dx f_n(x) = 1 \quad \checkmark$$

$$\int_{-\infty}^{\infty} f_n(x - x_0) f(x) dx$$

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} (x-x_0)^k = f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)(x-x_0)^2}{2}$$

$$\begin{aligned} - \int_{-\infty}^{\infty} \delta_n(x-x_0) f(x) dx &= \int_{-\infty}^{\infty} dx \delta_n(x-x_0) \cdot \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} (x-x_0)^k \\ &= \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} \int_{-\infty}^{\infty} dx \delta_n(x-x_0) (x-x_0)^k \end{aligned}$$

$$\underline{k=0}: \int_{-\infty}^{\infty} dx \delta_n(x-x_0) = 1$$

$$\underline{k=1}: \int_{-\infty}^{\infty} dx \delta_n(x-x_0) (x-x_0) = 0$$

$$\underline{k=2}: \int_{-\infty}^{\infty} dx \delta_n(x-x_0) (x-x_0)^2$$

$$= \int_{-\infty}^{\infty} dx \cdot n e^{-\pi n^2 (x-x_0)^2} (x-x_0)^2$$

$$= \int_{-\infty}^{\infty} \frac{dy}{n} \cdot n e^{-\pi y^2} \frac{y^2}{n^2} = \int_{-\infty}^{\infty} dy e^{-\pi y^2} \frac{y^2}{n^2}$$

$$= \sqrt{\frac{\pi}{\pi}} \cdot \frac{1!!}{2\pi n^2} = \frac{1}{2\pi n^2} \quad \checkmark$$

$$\left| \text{Subst. } y = n(x-x_0) \right.$$

$$dy = n dx \Leftrightarrow dx = \frac{dy}{n}$$

$$y^2 = n^2 (x-x_0)^2$$

$$\int_{-\infty}^{\infty} y^{2b} e^{-ay^2} dy = \sqrt{\frac{\pi}{a}} \frac{(2b-1)!!}{(2a)^b}$$

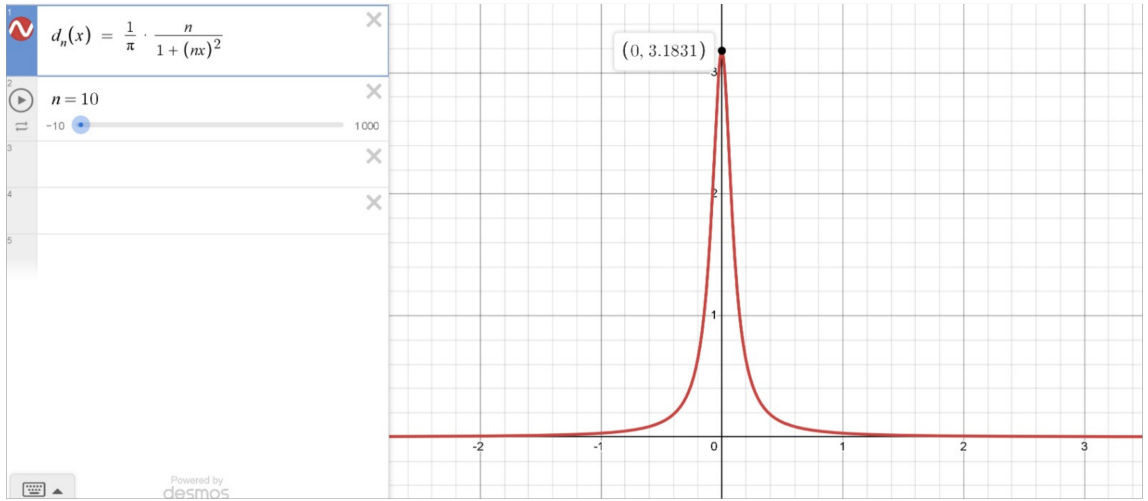
(Nachschlagen) mit $b=1$ und $a=\pi$

Damit ergibt sich:

$$f(x_0) + f''(x_0) \cdot \frac{1}{4\pi n^2} + o\left(\frac{1}{n^3}\right) \underset{n \rightarrow \infty}{=} f(x_0) \quad \checkmark$$

Die Taylorentwicklung kann auf wenige Glieder beschränkt werden, weil höhere Ordnungen den Faktor $\frac{1}{n^q}$ mit $q = \text{Ordnung}$ haben, die für $n \gg 1$ vernachlässigbar sind.

$$c) \quad \delta_n(x) = \frac{1}{\pi} \cdot \frac{n}{1+(nx)^2}$$



$$\int_{-\infty}^{\infty} dx \delta_n(x) = \int_{-\infty}^{\infty} dx \frac{1}{\pi} \cdot \frac{n}{1+(nx)^2} \quad \left(\text{Subst. } u = nx, \quad du = n dx \Leftrightarrow dx = \frac{du}{n} \right)$$

$$= \frac{1}{\pi} \int_{-\infty}^{\infty} du \frac{n}{n(1+u^2)} = \frac{1}{\pi} \left[\arctan(u) \right]_{-\infty}^{\infty} = \frac{1}{\pi} \left[\arctan(nx) \right]_{-\infty}^{\infty}$$

$$= \frac{1}{\pi} \left[\lim_{b \rightarrow \infty} \arctan(n \cdot b) - \lim_{a \rightarrow -\infty} \arctan(n \cdot a) \right] = \frac{1}{\pi} \left[\frac{\pi}{2} - \left(-\frac{\pi}{2} \right) \right] = 1 \quad \checkmark$$

$$\int_{-\infty}^{\infty} \delta_n(x-x_0) f(x) dx = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{n}{1+n^2(x-x_0)^2} f(x) dx = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{n}{1+n^2(x-x_0)^2} \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} (x-x_0)^k dx$$

$$= \frac{1}{\pi} \int_{-\infty}^{\infty} \sum_{k=0}^{\infty} \frac{n(x-x_0)^k}{1+n^2(x-x_0)^2} f^{(k)}(x_0) \frac{1}{k!} dx, \quad \text{Subst. } y = n(x-x_0) \Rightarrow dx = \frac{1}{n} dy$$

$$\int_{-\infty}^{\infty} \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} \frac{y^k}{1+y^2} \frac{1}{n^k} dy \quad \text{Die Funktion } T(y) = \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{n^k} \frac{y^k}{1+y^2} \text{ ist}$$

nicht i.A. nicht analytisch lösbar, da sie sich nicht als Potenzreihe der Form $\sum_{k=0}^{\infty} a_k y^k$ schreiben lässt. Wir können also nicht wie in b) vorgehen. (Integrale divergieren)

d)

$$\vec{z}: \vec{\nabla} \cdot \frac{\vec{r}}{r^3} = 4\pi \delta(\vec{r}) \quad \text{mit} \quad \delta(\vec{r}) = \delta(x)\delta(y)\delta(z)$$

$$(i) \quad 4\pi \int_{\mathbb{R}^3} \delta(x)\delta(y)\delta(z) f(r) dx dy dz = f(0), \quad \delta(\vec{r}) \text{ liegt also}$$

außerhalb $r=0$ keine Beiträge und es gilt

$$4\pi \delta(\vec{r}) = 0 \quad \text{für alle } r \neq 0$$

(ii)

$$\int_V \vec{\nabla} \cdot \left(\frac{\vec{r}}{r^3} \right) dV \stackrel{\text{Satz von Gauss}}{=} \oint_{\partial V} \frac{\vec{r}}{r^3} \cdot d\vec{A} = \oint_{\partial V} \frac{\hat{e}_r}{r^2} \hat{e}_r dA$$

$$= \oint_{\partial V} \frac{1}{r^2} dA = \frac{1}{R^2} \cdot 4\pi R^2 = 4\pi$$

(iii) Integriert man $\vec{\nabla} \cdot \left(\frac{\vec{r}}{r^3} \right)$ über eine beliebige, also insbesondere auch eine infinitesimale Kugel, die den Ursprung enthält, so erhält man immer den Wert 4π . Integriert man über ein Volumen, das den Ursprung nicht enthält, so erhält man Null. Dieses Verhalten wird durch eine Deltafunktion im Ursprung beschrieben:

$$\vec{\nabla} \cdot \frac{\vec{r}}{r^3} = 4\pi \delta(\vec{r})$$

$$e) \quad \vec{z}: \vec{\nabla} \times \left(\frac{\hat{e}_z \times \vec{p}}{\rho^2} \right) = 2\pi \delta(x)\delta(y) \hat{e}_z, \quad \vec{p} = x\hat{e}_x + y\hat{e}_y$$

$$= \vec{\nabla} \times \left(\frac{\hat{e}_z \times (x\hat{e}_x + y\hat{e}_y)}{\rho^2} \right) = \vec{\nabla} \times \left(\frac{x\hat{e}_y - y\hat{e}_x}{\rho^2} \right)$$

$$\text{Vektorfeld aus 2h): } A_n(\vec{r}) = (x^2 + y^2)^{\frac{n}{2}} (x\hat{e}_y - y\hat{e}_x)$$

Das Vektorfeld entspricht also $A_{-2}(\vec{r}) = (x^2 + y^2)^{-1} (x \hat{e}_y - y \hat{e}_x)$

$$= \frac{(x \hat{e}_y - y \hat{e}_x)}{\rho^2}$$

$$(i) \vec{\nabla} \times \left(\frac{x \hat{e}_y - y \hat{e}_x}{x^2 + y^2} \right) = \vec{\nabla} \times \left(\frac{\hat{e}_y \cdot x}{x^2 + y^2} \right) - \vec{\nabla} \times \left(\frac{\hat{e}_x \cdot y}{x^2 + y^2} \right)$$

$$= (\partial_x \hat{e}_x + \partial_y \hat{e}_y + \partial_z \hat{e}_z) \times \left(\frac{\hat{e}_y \cdot x}{x^2 + y^2} \right) - (\partial_x \hat{e}_x + \partial_y \hat{e}_y + \partial_z \hat{e}_z) \times \left(\frac{\hat{e}_x \cdot y}{x^2 + y^2} \right)$$

$$= \partial_x \frac{x}{x^2 + y^2} \hat{e}_z - \partial_z \underbrace{\frac{x}{x^2 + y^2}}_{=0} \hat{e}_x - \left(-\partial_y \frac{y}{x^2 + y^2} \hat{e}_z + \partial_z \underbrace{\frac{y}{x^2 + y^2}}_{=0} \hat{e}_y \right)$$

$$= \left(\partial_x \frac{x}{x^2 + y^2} + \partial_y \frac{y}{x^2 + y^2} \right) \hat{e}_z$$

$$= \left(\frac{y^2 - x^2}{(x^2 + y^2)^2} + \frac{x^2 - y^2}{(x^2 + y^2)^2} \right) \hat{e}_z = \vec{0} \quad \text{für } \rho = \sqrt{x^2 + y^2} \neq 0 \quad \checkmark$$

$$(ii) \int_F d\vec{f} \left(\vec{\nabla} \times \left(\frac{x \hat{e}_y - y \hat{e}_x}{x^2 + y^2} \right) \right) = \int_{\partial F} d\vec{s} \frac{x \hat{e}_y - y \hat{e}_x}{x^2 + y^2}$$

$$= \int_{\partial F} ds \hat{e}_\varphi \frac{\cos \varphi (\sin \varphi \hat{e}_\rho + \cos \varphi \hat{e}_\varphi) - \sin \varphi (\cos \varphi \hat{e}_\rho - \sin \varphi \hat{e}_\varphi)}{\rho}$$

$$= \int_{\partial F} ds \frac{\cos^2 \varphi + \sin^2 \varphi}{\rho} = \frac{2\pi R}{R} = 2\pi \quad \checkmark \quad \left| \text{mit } \rho = R \right.$$

(iii) Wählt man eine infinitesimale Kreisscheibe um die z-Achse, so erhält man ebenfalls den Wert 2π . Es muss also für jeden Punkt auf der z-Achse ein Delta-Areal existieren (mit Vorfaktor 2π)

$$\Rightarrow \vec{\nabla} \times \left(\frac{\hat{e}_z \times \vec{p}}{\rho^2} \right) = 2\pi \delta(x) \delta(y) \hat{e}_z \quad \checkmark$$

② $\vec{A}(\vec{r}) = \psi \vec{\nabla} \phi$

a) $\vec{z}$: $\int_V dV [(\vec{\nabla} \psi)(\vec{\nabla} \phi) + \psi \vec{\nabla}^2 \phi] = \oint_{\partial V} d\vec{f} \psi \vec{\nabla} \phi$

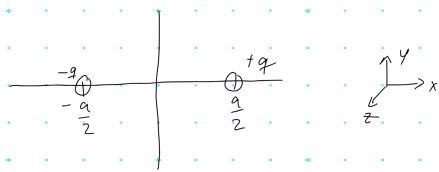
$$= \int_V dV \vec{\nabla} \vec{A} = \int_V dV \vec{\nabla} (\psi \vec{\nabla} \phi) \stackrel{\text{Produktregel}}{=} \int_V dV (\vec{\nabla} \psi)(\vec{\nabla} \phi) \vec{\nabla}^2 \phi$$

Satz v. Gauss $\Rightarrow \oint_{\partial V} d\vec{f} \vec{A} = \oint_{\partial V} d\vec{f} \psi \vec{\nabla} \phi \quad \checkmark$

b) $\vec{B}(\vec{r}) = \phi \vec{\nabla} \psi$, $\vec{z}$: $\int_V dV [\psi \vec{\nabla}^2 \phi - \phi \vec{\nabla}^2 \psi] = \oint_{\partial V} d\vec{f} [\psi \vec{\nabla} \phi - \phi \vec{\nabla} \psi]$

$$\begin{aligned} \int_V dV [\vec{\nabla}(\vec{A} - \vec{B})] &= \int_V dV [\vec{\nabla}(\psi \vec{\nabla} \phi) - \vec{\nabla}(\phi \vec{\nabla} \psi)] \\ &\stackrel{\text{Produktregel}}{=} \int_V dV [\cancel{(\vec{\nabla} \psi)(\vec{\nabla} \phi)} (\psi \vec{\nabla}^2 \phi) - \cancel{(\vec{\nabla} \phi)(\vec{\nabla} \psi)} (\phi \vec{\nabla}^2 \psi)] = \int_V dV [\psi \vec{\nabla}^2 \phi - \phi \vec{\nabla}^2 \psi] \\ &\stackrel{\text{Satz v. Gauss}}{=} \oint_{\partial V} d\vec{f} [\vec{A} - \vec{B}] = \oint_{\partial V} d\vec{f} [\psi \vec{\nabla} \phi - \phi \vec{\nabla} \psi] \quad \checkmark \end{aligned}$$

$$\textcircled{3} \quad \vec{E}(\vec{r}) = \frac{q_1}{4\pi\epsilon_0} \frac{\vec{r} - \vec{r}_1}{|\vec{r} - \vec{r}_1|^3}$$



$$\vec{E}_{\text{ges}}(\vec{r}) = \vec{E}_q(\vec{r}) + \vec{E}_{-q}(\vec{r})$$

Ladung q am Ort $\vec{r}_+ = \frac{a}{2} \hat{e}_x \Rightarrow \vec{r} - \vec{r}_+ = (x - \frac{a}{2})\hat{e}_x + y\hat{e}_y + z\hat{e}_z$

Ladung $-q$ am Ort $\vec{r}_- = -\frac{a}{2} \hat{e}_x \Rightarrow \vec{r} - \vec{r}_- = (x + \frac{a}{2})\hat{e}_x + y\hat{e}_y + z\hat{e}_z$

$$\Rightarrow \vec{E}_{\text{ges}}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \left[\frac{(x - \frac{a}{2})\hat{e}_x + y\hat{e}_y + z\hat{e}_z}{\sqrt{(x - \frac{a}{2})^2 + y^2 + z^2}^3} - \frac{(x + \frac{a}{2})\hat{e}_x + y\hat{e}_y + z\hat{e}_z}{\sqrt{(x + \frac{a}{2})^2 + y^2 + z^2}^3} \right] \quad \checkmark$$

b) $|\vec{a}| < |\vec{r}|$ Hinweis: $|\vec{a} + \vec{b}|^2 = a^2 + 2ab\cos\phi + b^2$

$$\begin{aligned} \frac{1}{|\vec{r} - \vec{r}_+|^3} &= \frac{1}{|\vec{r} - \frac{a}{2}\hat{e}_x|^3} = \frac{1}{|\vec{r} - \frac{a}{2}\hat{e}_x|^3} \stackrel{(*)}{=} \frac{1}{(r^2 + \frac{a^2}{4} - r a \cos\phi)^{\frac{3}{2}}} \\ &= \frac{1}{r^3 \left(\sqrt{1 + \frac{1}{4} \frac{a^2}{r^2} - \frac{a}{r} \cos\phi} \right)^3} \end{aligned}$$

Die Taylorentwicklung liefert:

$$\frac{1}{r^3 \left(\sqrt{1 + \frac{1}{4} \frac{a^2}{r^2} - \frac{a}{r} \cos\phi} \right)^3} = \frac{1}{r^3} \pm \frac{3\cos\phi}{2} \frac{a}{r^4} + \mathcal{O}\left(\frac{|\vec{a}|^2}{|\vec{r}|^2}\right) \quad \checkmark$$

$$\text{c) z: } \vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left[\frac{3\vec{r}(\vec{r} \cdot \vec{p})}{|\vec{r}|^5} - \frac{\vec{p}}{|\vec{r}|^3} \right] + \mathcal{O}\left(\frac{|\vec{a}|^3}{|\vec{r}|^5}\right)$$

mit dem $\vec{p}$ -Feld aus a): $\vec{E}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \left[\frac{\vec{r} - \frac{a}{2}\hat{e}_x}{\sqrt{(x - \frac{a}{2})^2 + y^2 + z^2}^3} - \frac{\vec{r} + \frac{a}{2}\hat{e}_x}{\sqrt{(x + \frac{a}{2})^2 + y^2 + z^2}^3} \right]$

$$= \frac{q}{4\pi\epsilon_0} \left[\frac{\vec{r} - \frac{a}{2}\hat{e}_x}{|\vec{r} - \vec{r}_+|^3} - \frac{\vec{r} + \frac{a}{2}\hat{e}_x}{|\vec{r} - \vec{r}_-|^3} \right]$$

$$\approx \frac{q}{4\pi\epsilon_0} \left[\left(\vec{r} - \frac{\vec{a}}{2} \right) \left(\frac{1}{r^3} + \frac{3}{2} \cos\phi \frac{a}{r^4} + O\left(\frac{a^2}{r^2}\right) \right) \right. \\ \left. + \left(-\vec{r} - \frac{\vec{a}}{2} \right) \left(\frac{1}{r^3} - \frac{3}{2} \cos\phi \frac{a}{r^4} + O\left(\frac{a^2}{r^2}\right) \right) \right]$$

$$= \frac{q}{4\pi\epsilon_0} \left[\frac{\vec{r}}{r^3} + \frac{3}{2} \cos\phi \frac{\vec{r}}{r^4} a - \frac{\vec{a}}{2} \cdot \frac{1}{r^3} - \frac{3}{4} \cos\phi \frac{\vec{a}}{r^4} a \right. \\ \left. - \frac{\vec{r}}{r^3} + \frac{3}{2} \cos\phi \frac{\vec{r}}{r^4} a - \frac{\vec{a}}{2} \cdot \frac{1}{r^3} + \frac{3}{4} \cos\phi \frac{\vec{a}}{r^4} a \right]$$

$$= \frac{q}{4\pi\epsilon_0} \left[a \cos\phi \frac{3}{r^4} \vec{r} - \frac{\vec{a}}{r^3} q \right] \quad \boxed{* \frac{\vec{r} \cdot \vec{a}}{r \cdot a} = \cos\phi}$$

$$= * \frac{1}{4\pi\epsilon_0} \left[\frac{\vec{r} \cdot \vec{a}}{r} \frac{3}{r^4} q - \frac{\vec{a}}{r^3} q \right] = \frac{1}{4\pi\epsilon_0} \left[\frac{3 \vec{r} (\vec{r} \cdot \vec{a})}{r^5} - \frac{\vec{a}}{r^3} \right] + O\left(\frac{a^3}{r^3}\right)$$

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d)

Im Folgenden wird das E-Feld des Dipols exakt und genähert grafisch betrachtet. Dabei wurde die Ladung q , die Permittivität ϵ_0 auf 1 und der Vektor $\vec{a}$ auf (1,0,0) gesetzt.

In[306]:=

```
a := {1, 0, 0}
aBetrag := 1
ε := 1
q := 1
```

```
VectorPlot[ { 1 / (4 * Pi * ε) * ((x - 0.5 * 1) / (sqrt((x - 0.5 * 1)^2 + y^2))^3 -
              (x + 0.5 * 1) / (sqrt((x + 0.5 * 1)^2 + y^2))^3), 1 / (4 * Pi * ε) *
              ((y) / (sqrt((x - 0.5 * 1)^2 + y^2))^3 - (y) / (sqrt((x + 0.5 * 1)^2 + y^2))^3) },
{x, -10, 10}, {y, -10, 10}, PlotLabel -> "exaktes E-Feld",
PlotLegends -> Automatic, Axes -> True, AxesLabel -> {x, y} ]
```

```
VectorPlot[ { 1 / (4 * Pi * ε) *
              ((3 * x * x * q) / ((sqrt((x - 0.5)^2 + y^2))^5) - 1 / ((sqrt((x - 0.5)^2 + y^2))^3)),
              1 / (4 * Pi * ε) * ((3 * y * x * q) / ((sqrt((x - 0.5)^2 + y^2))^5) ) },
{x, -10, 10}, {y, -10, 10}, PlotLabel -> "approximiertes E-Feld",
PlotLegends -> Automatic, Axes -> True, AxesLabel -> {x, y} ]
```

```
DensityPlot[
  ((1 / (4 * Pi * ε) * ((x - 0.5 * 1) / (sqrt((x - 0.5 * 1)^2 + y^2))^3 - (x + 0.5 * 1) /
    (sqrt((x + 0.5 * 1)^2 + y^2))^3)) -
  (1 / (4 * Pi * ε) * ((3 * x * x * q) / ((sqrt((x - 0.5)^2 + y^2))^5) -
    1 / ((sqrt((x - 0.5)^2 + y^2))^3))))^2 + ((1 / (4 * Pi * ε) *
    ((y) / (sqrt((x - 0.5 * 1)^2 + y^2))^3 - (y) / (sqrt((x + 0.5 * 1)^2 + y^2))^3)) -
    (1 / (4 * Pi * ε) * ((3 * y * x * q) / ((sqrt((x - 0.5)^2 + y^2))^5) ))))^2 ^
  0.5, {x, -10, 10}, {y, -10, 10}, PlotLabel ->
  "absoluter Fehler",
FrameLabel ->
  {x, y},
PlotLegends ->
  BarLegend[ Automatic,
    LegendLabel -> "|Eapprox-Eexact| " ],
ColorFunction -> "Rainbow",
PlotRange ->
```

```
{0, 0.01}]
```

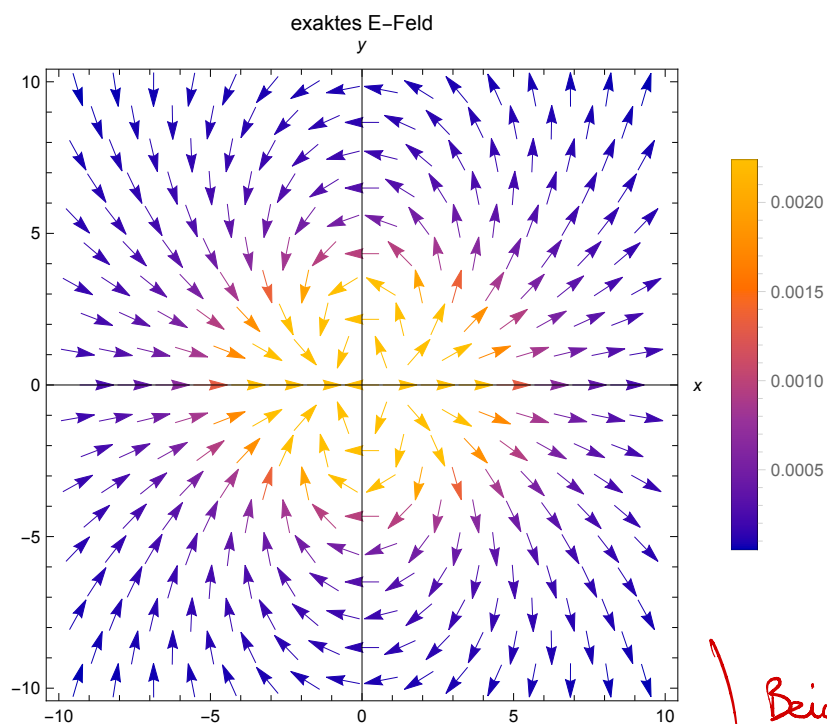
```
DensityPlot[
  (((1 / (4 * Pi * ε) * ((x - 0.5 * 1) / (√(x - 0.5 * 1)^2 + y^2))^3 - (x + 0.5 * 1) /
    (√(x + 0.5 * 1)^2 + y^2))^3)) -
  (1 / (4 * Pi * ε) * ((3 * x * x * q) / ((√(x - 0.5)^2 + y^2))^5) -
    1 / ((√(x - 0.5)^2 + y^2))^3)))^2 + ((1 / (4 * Pi * ε) *
    ((y) / (√(x - 0.5 * 1)^2 + y^2))^3 - (y) / (√(x + 0.5 * 1)^2 + y^2))^3)) -
  (1 / (4 * Pi * ε) * ((3 * y * x * q) / ((√(x - 0.5)^2 + y^2))^5)))^2)^0.5 /
  (((1 / (4 * Pi * ε) * ((x - 0.5 * 1) / (√(x - 0.5 * 1)^2 + y^2))^3 -
    (x + 0.5 * 1) / (√(x + 0.5 * 1)^2 + y^2))^3))^2 +
  (1 / (4 * Pi * ε) * ((y) / (√(x - 0.5 * 1)^2 + y^2))^3 -
    (y) / (√(x + 0.5 * 1)^2 + y^2))^3))^2)^0.5
, {x, -10, 10}, {y, -10, 10}, PlotLabel → "relativer Fehler", FrameLabel → {x, y},
PlotLegends → BarLegend[Automatic, LegendLabel → " $\frac{|E_{\text{approx}} - E_{\text{exact}}|}{|E_{\text{exact}}|}$ "],
ColorFunction → "Rainbow", PlotRange → {0, 1}]
```

```
Plot[(((1 / (4 * Pi * ε) * ((t - 0.5 * 1) / (√(t - 0.5 * 1)^2 + 0^2))^3 -
  (t + 0.5 * 1) / (√(t + 0.5 * 1)^2 + 0^2))^3)) -
  (1 / (4 * Pi * ε) * ((3 * t * t * q) / ((√(t - 0.5)^2 + 0^2))^5) -
    1 / ((√(t - 0.5)^2 + 0^2))^3)))^2)^0.5,
{t, 0.1, 10}, PlotLabel → "Absoluter Fehler für r=(t,0,0)",
PlotRange →
{0, 100},
AxesLabel → {"|r|", "|Eapprox-Eexact|"}]
```

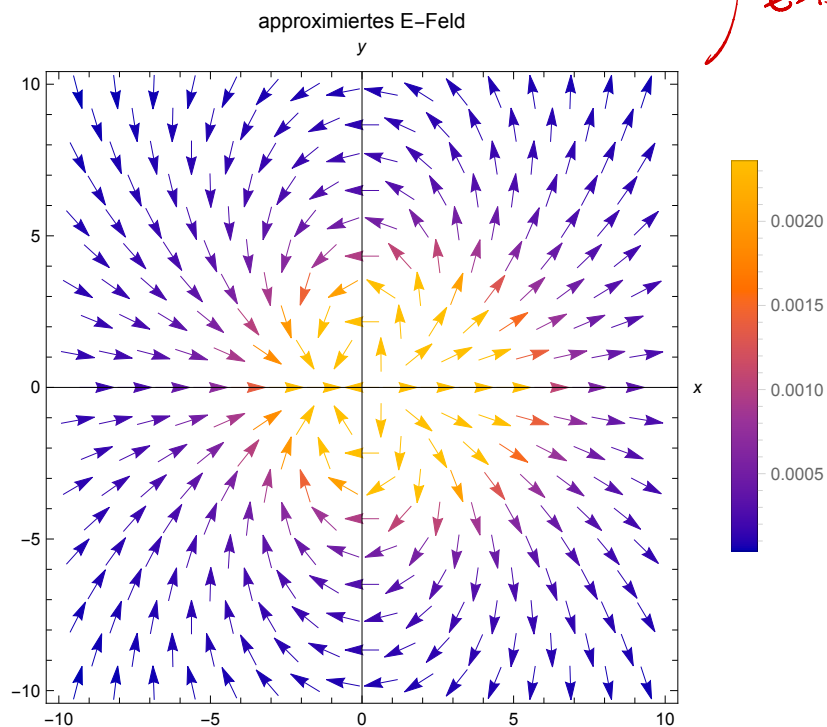
```
Plot[(((1 / (4 * Pi * ε) * ((t - 0.5 * 0) / (√(0 - 0.5 * 1)^2 + t^2))^3 -
  (t + 0.5 * 1) / (√(0 + 0.5 * 1)^2 + t^2))^3)) -
  (1 / (4 * Pi * ε) * ((3 * t * 0 * q) / ((√(0 - 0.5)^2 + t^2))^5) -
    1 / ((√(0 - 0.5)^2 + t^2))^3)))^2)^0.5,
{t, 0.1, 10}, PlotLabel → "Absoluter Fehler für r=(0,t,0)",
PlotRange →
{0, 1},
```

AxisLabel $\rightarrow \{ "|r|", "|E_{\text{approx}} - E_{\text{exact}}|" \}$

Out[310]=

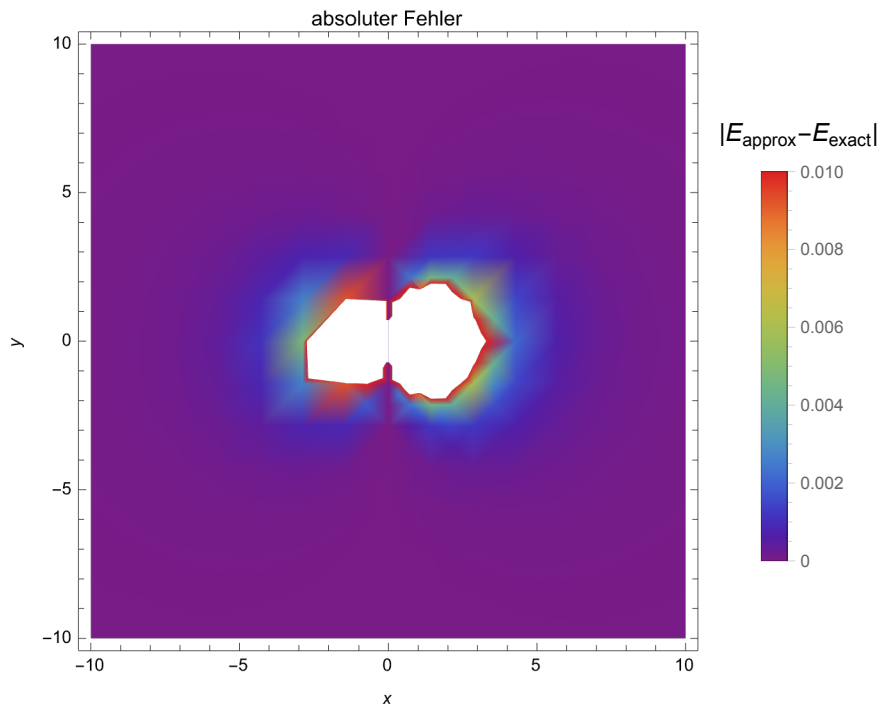


Out[311]=



Beispiel
E-Feld der Näherung

Out[312]=

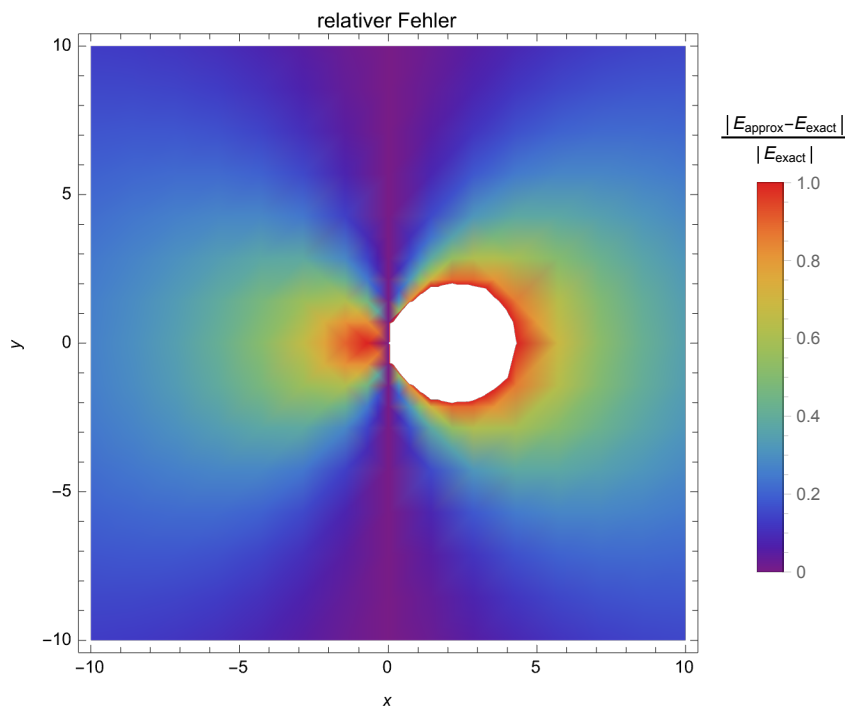


haha keine Ahnung
warum das so cursed
aussieht

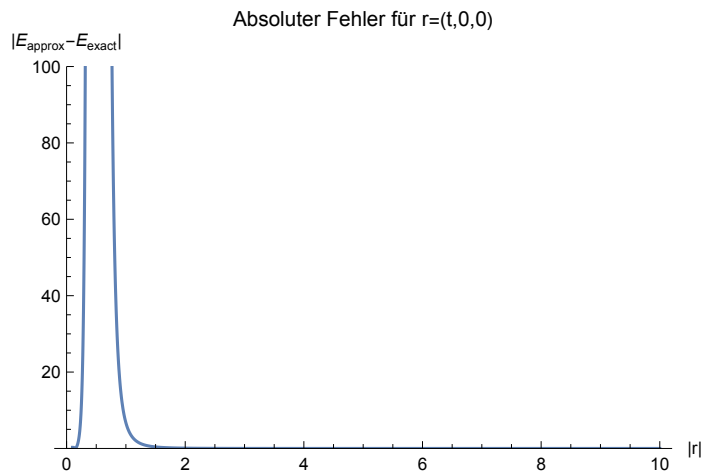
Sollte aber beides
achsensymmetrisch sein

Unten mal die
Musterplots + Coole

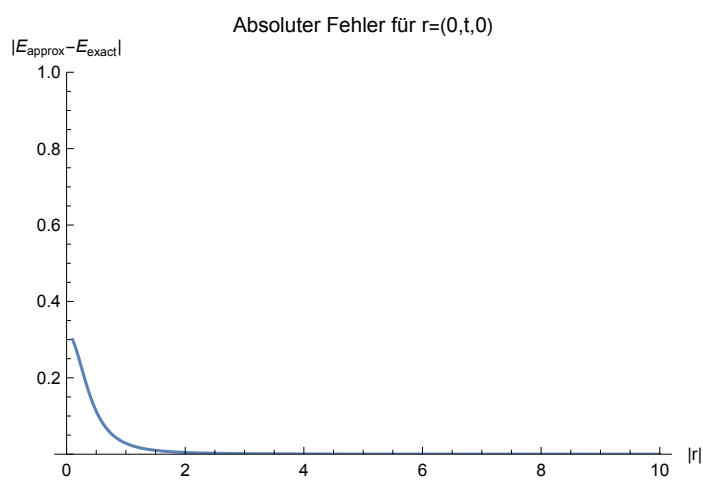
Out[313]=



Out[314]=



Out[315]=



Den Plots ist zu entnehmen, dass der Fehler durch die Näherung des E-Felds für große $|\vec{r}|$ gut vernachlässigbar ist. Außerdem ist der Fehler in der Nähe der y-Achse geringer als der Fehler in Nähe zur x-Achse.

6/10

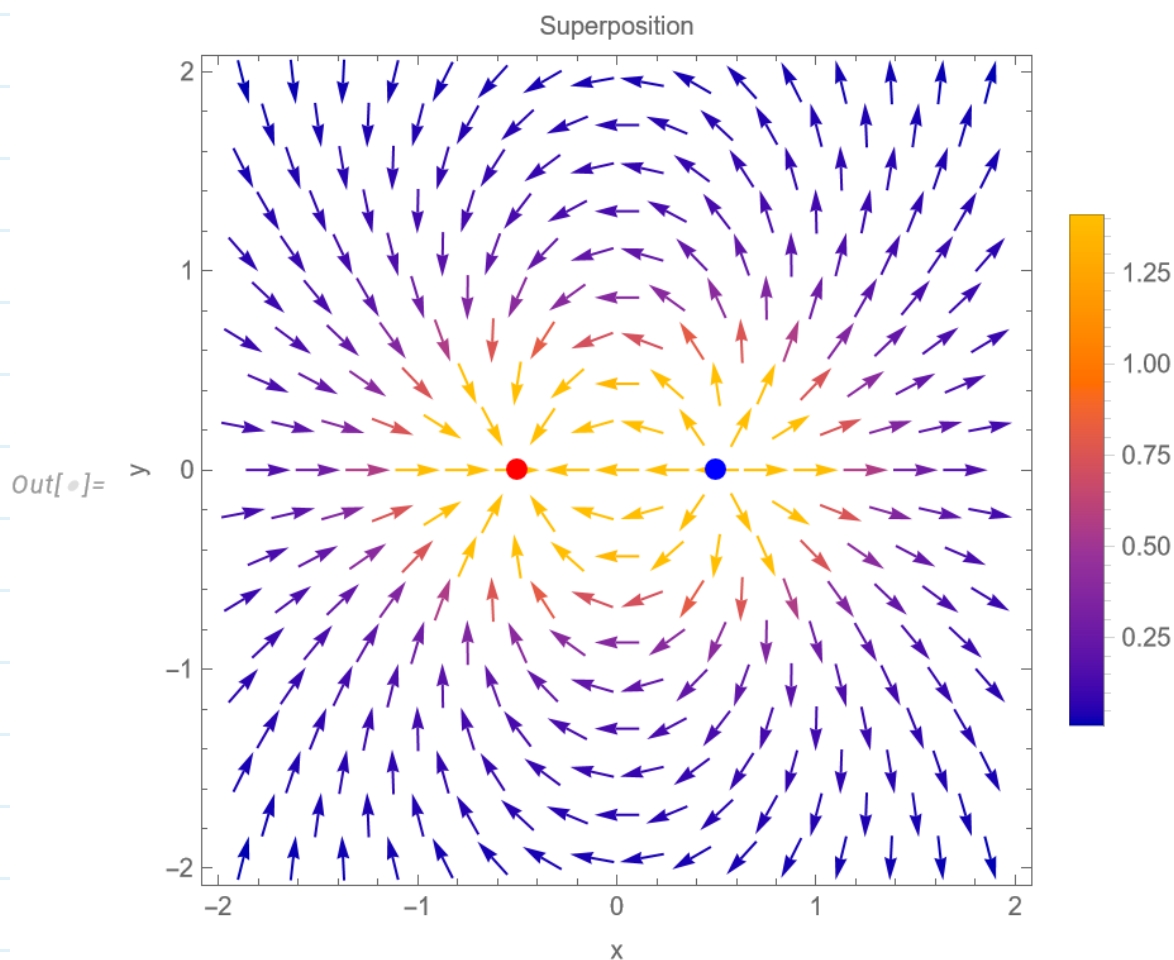
E-Feld aus Superposition

```
In[ ]:= r = {x, y};
```

```
a = {1, 0};
```

```
Show[
```

```
VectorPlot[ $\frac{1}{4\pi} \left( \frac{\mathbf{r} - \mathbf{a}/2}{\text{Norm}[\mathbf{r} - \mathbf{a}/2]^3} - \frac{\mathbf{r} + \mathbf{a}/2}{\text{Norm}[\mathbf{r} + \mathbf{a}/2]^3} \right)$ , {x, -2, 2},  
{y, -2, 2}, FrameLabel -> {{ "y", None}, {"x", "Superposition"}},  
PlotLegends -> Automatic],  
Graphics[{Red, Disk[-a/2, 0.05], Blue, Disk[a/2, 0.05]}]  
]
```



(2)

E-Feld aus Näherung

```
In[•]:= r = {x, y};
```

```
a = {1, 0};
```

```
Show[
```

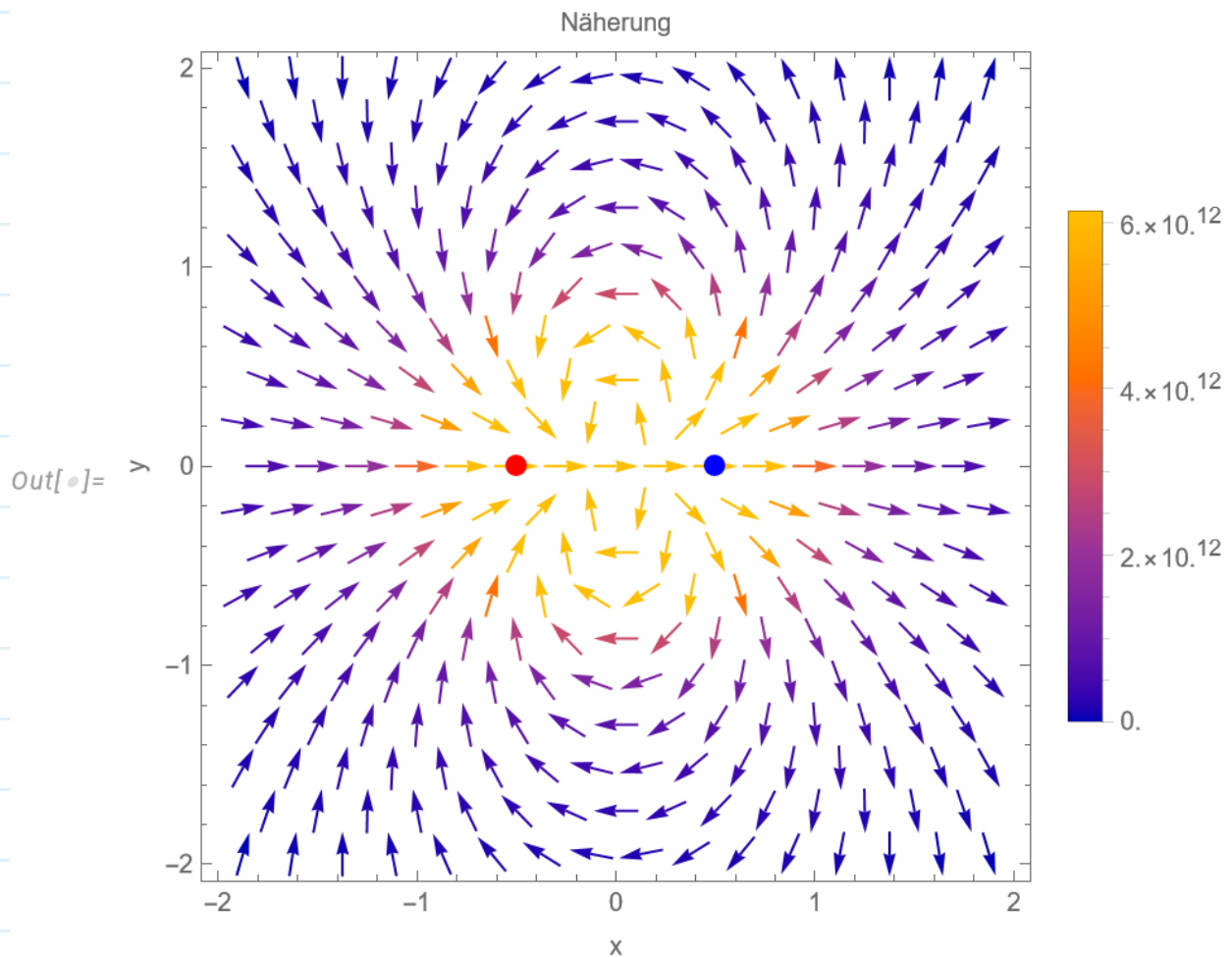
```
VectorPlot[ $\frac{1}{4\pi} \left( 3r \frac{r \cdot a}{\text{Norm}[r]^5} - \frac{a}{\text{Norm}[r]^3} \right)$ , {x, -2, 2},
```

```
{y, -2, 2}, FrameLabel -> {{ "y", None}, {"x", "Näherung"}},
```

```
PlotLegends -> Automatic],
```

```
Graphics[{Red, Disk[-a/2, 0.05], Blue, Disk[a/2, 0.05]}]
```

```
]
```



2

Absoluter Fehler

```

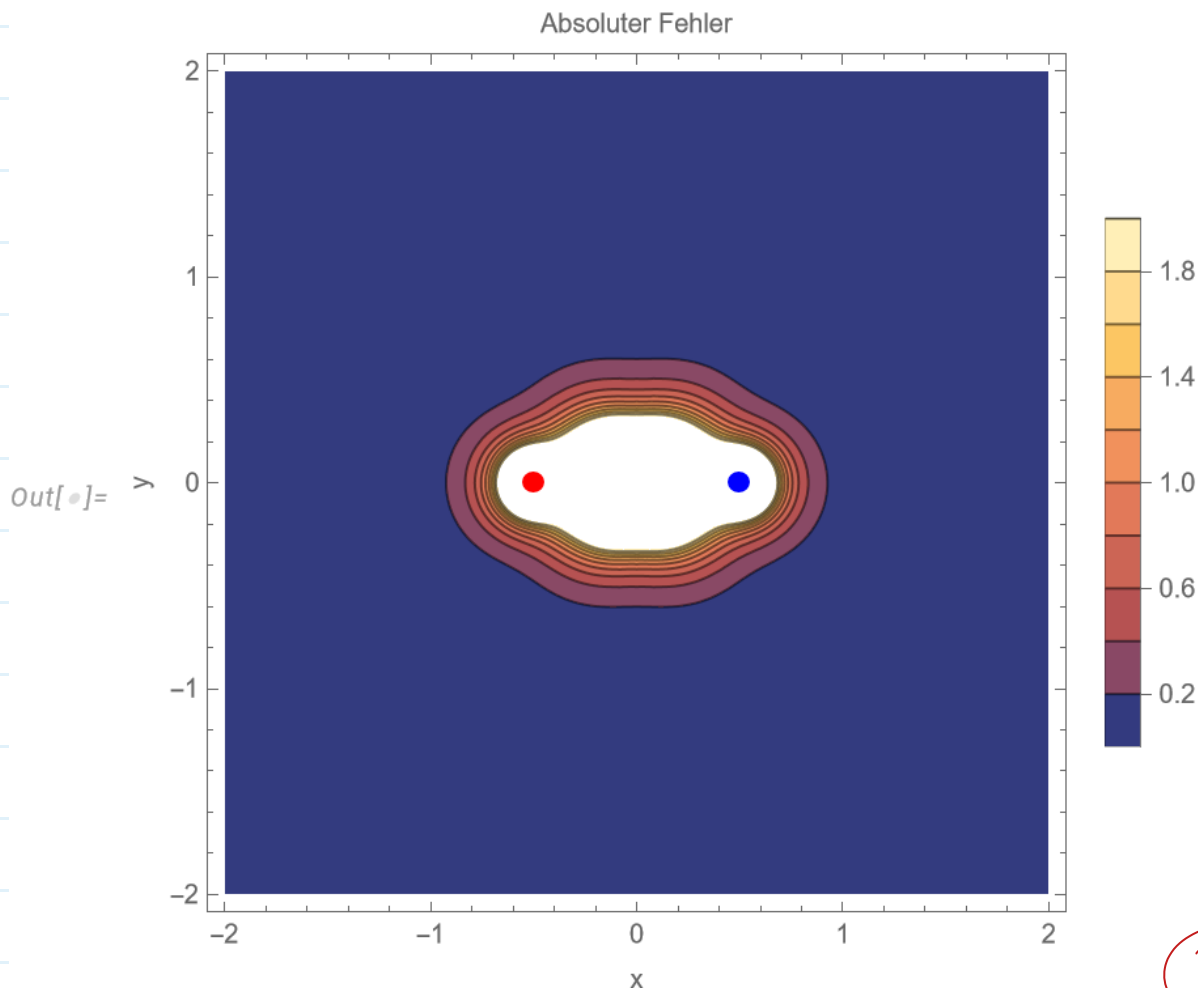
In[ ]:= r = {x, y};
a = {1, 0};

dipolExact =  $\frac{1}{4 \pi} \left( \frac{r - a/2}{\text{Norm}[r - a/2]^3} - \frac{r + a/2}{\text{Norm}[r + a/2]^3} \right)$ ;

dipolApprox =  $\frac{1}{4 \pi} \left( 3 r \frac{r \cdot a}{\text{Norm}[r]^5} - \frac{a}{\text{Norm}[r]^3} \right)$ ;

Show[
  ContourPlot[Norm[dipolApprox - dipolExact], {x, -2, 2},
    {y, -2, 2},
    FrameLabel -> {{ "y", None}, {"x", "Absoluter Fehler"}},
    PlotLegends -> Automatic, PlotRange -> {All, All, {0, 2}},
    PlotPoints -> 50],
  Graphics[{Red, Disk[-a/2, 0.05], Blue, Disk[a/2, 0.05]}]
]

```



2

Relativer Fehler

```

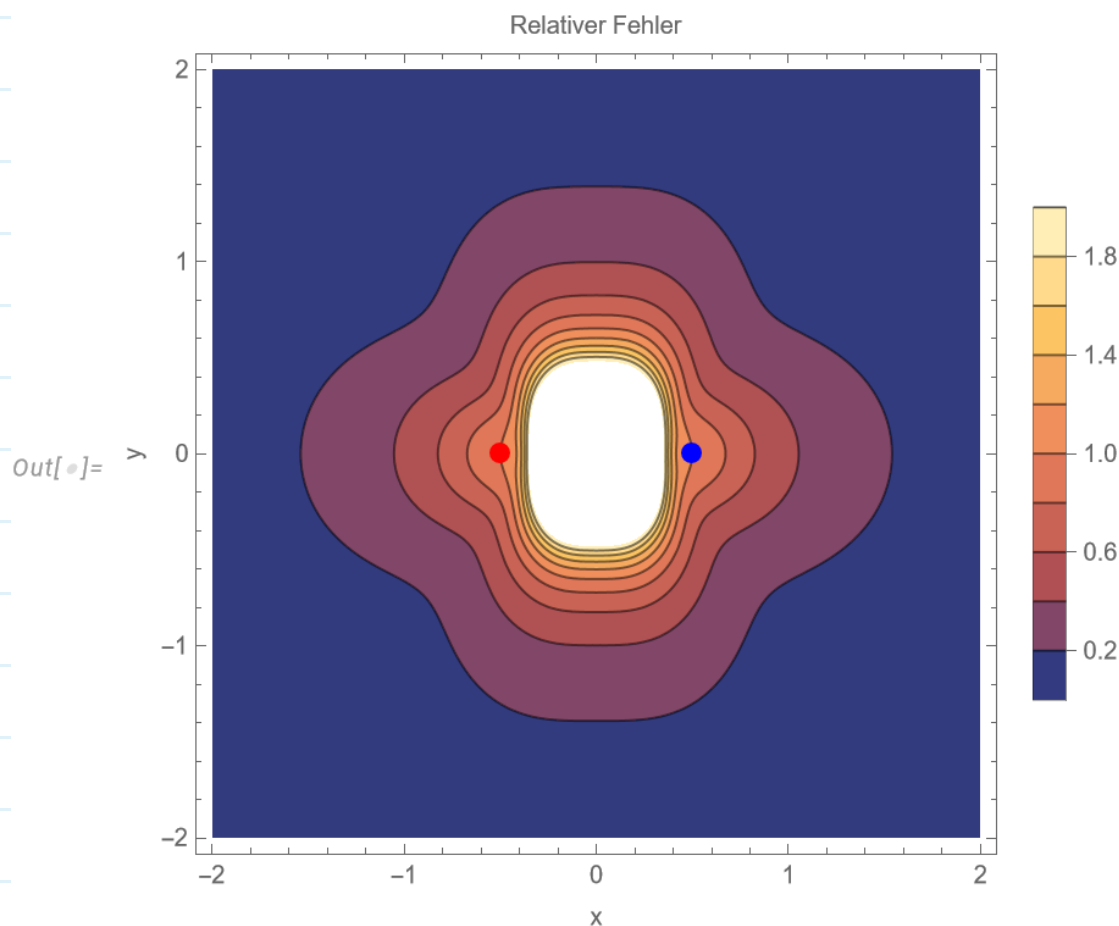
In[ ]:= r = {x, y};
a = {1, 0};

dipolExact =  $\frac{1}{4 \pi} \left( \frac{r - a/2}{\text{Norm}[r - a/2]^3} - \frac{r + a/2}{\text{Norm}[r + a/2]^3} \right);$ 

dipolApprox =  $\frac{1}{4 \pi} \left( 3 r \frac{r \cdot a}{\text{Norm}[r]^5} - \frac{a}{\text{Norm}[r]^3} \right);$ 

Show[
  ContourPlot[ $\frac{\text{Norm}[\text{dipolApprox} - \text{dipolExact}]}{\text{Norm}[\text{dipolExact}]}$ , {x, -2, 2},
    {y, -2, 2},
    FrameLabel -> {{ "y", None}, {"x", "Relativer Fehler"}},
    PlotLegends -> Automatic, PlotRange -> {All, All, {0, 2}},
    PlotPoints -> 50],
  Graphics[{Red, Disk[-a/2, 0.05], Blue, Disk[a/2, 0.05]}]
]

```



Konvergenz

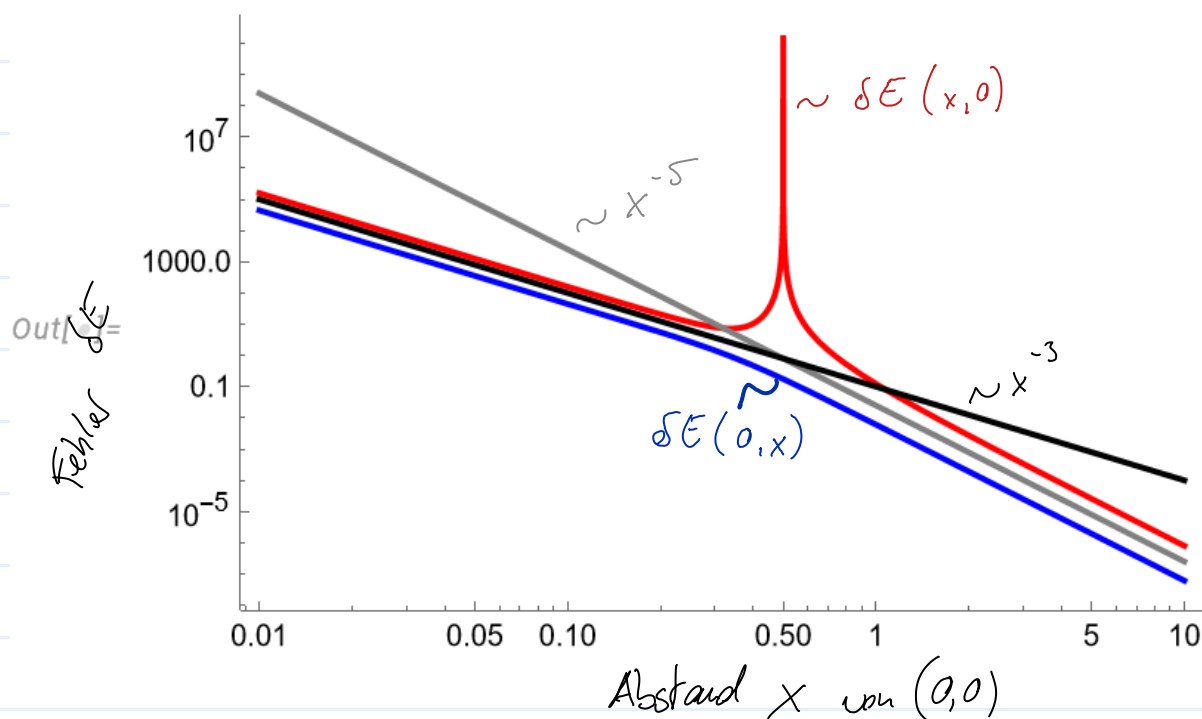
```
In[•]:= r = {x, y};
```

```
a = {1, 0};
```

```
dipolExact = 1/(4 π) ( (r - a/2)/Norm[r - a/2]^3 - (r + a/2)/Norm[r + a/2]^3 );
```

```
dipolApprox = 1/(4 π) ( 3 r (r.a)/Norm[r]^5 - a/Norm[r]^3 );
```

```
LogLogPlot[{
  Norm[dipolApprox - dipolExact] /. y -> 0,
  Norm[dipolApprox - dipolExact] /. x -> 0 /. y -> x,
  0.025 x^-5,
  0.1 x^-3
}, {x, 0.01, 10}, PlotStyle -> {Red, Blue, Gray, Black}]
```



$\Rightarrow$ Für x bzw $y \rightarrow 0$ Konvergenz mit r^{-3} .
 Für x bzw $y \rightarrow \infty$ Konvergenz mit r^{-5} .

(2)