

Aufgabe 3 a) $E_{kin} = \sqrt{\vec{p}^2 c^2 + m^2 c^4} - m c^2 = m c^2 \left(1 + \frac{\vec{p}^2}{2 m^2 c^2} - \frac{\vec{p}^4}{8 m^4} + \dots \right)$

$$b) H_{rel} = -\frac{\vec{p}^2}{2m} = -\frac{1}{2mc^2} \left(\frac{\vec{p}^2}{2m} \right)^2 = -\frac{1}{2mc^2} T^2 ; H_0 = T + V(r)$$

$$= -\frac{1}{2mc^2} (H_0 - V(r))^2 = -\frac{1}{2mc^2} (H_0^2 - H_0 V - V H_0 + V^2) \Rightarrow$$

$$[H_{rel}, \vec{L}^2] = [H_{rel}, L_z] = [H_{rel}, \vec{S}^2] = [H_{rel}, S_z] = 0$$

$\Rightarrow \psi_{n, m_l, m_s} = R_{n, l} Y_{l, m_l} \chi_{m_s}$ sind Eigenzustände von H_{rel} .

Verschiebung der Grundzustandsenergie:

$$\langle E_{rel}^{(1)} \rangle = \langle \psi_{n, m_l, m_s} | H_{rel} | \psi_{n, m_l, m_s} \rangle \quad \text{mit } n=1, l=0, \dots$$

$$\begin{cases} H_0 | \psi_{n, m_l, m_s} \rangle = E_n ; & E_n = -\frac{mc^2}{2} \frac{(Z\alpha)^2}{n^2} ; & Z=1. \\ V(r) = -\frac{Z\alpha\hbar c}{r} \end{cases}$$

$$\Rightarrow \langle E_{rel}^{(1)} \rangle = -\frac{1}{2mc^2} \left[E_n^2 - 2E_n \left(-\frac{Z\alpha\hbar c}{r} \right) \left\langle \frac{1}{r} \right\rangle + \left(\frac{Z\alpha\hbar c}{r} \right)^2 \left\langle \frac{1}{r^2} \right\rangle \right]$$

$$= -\frac{1}{2mc^2} \left[E_n^2 - 2E_n \left(-\frac{Z\alpha\hbar c}{m^2} - \frac{mc^2}{r} \right) + \left(\frac{Z\alpha\hbar c}{r} \right)^2 \left(\frac{Z\alpha\hbar c}{r} \right)^2 \frac{1}{n^2(e+1/2)} \right]$$

$$= -\frac{1}{2mc^2} \left[E_n^2 - 2E_n \cdot \left(-\frac{mc^2}{2} \frac{(Z\alpha)^2}{n^2} \right) - 2 \left(-\frac{mc^2}{2} \frac{(Z\alpha)^2}{n^2} \right) \left(\frac{mc^2}{n(e+1/2)} \right) \right]$$

$$= -\frac{1}{2mc^2} E_n \cdot (mc^2) \cdot \frac{(Z\alpha)^2}{n^2} \left[-\frac{1}{2} + 2 - \frac{2n}{e+1/2} \right] =$$

$$= -E_n \frac{(Z\alpha)^2}{n^2} \left(\frac{3}{4} - \frac{n}{e+1/2} \right)$$

$$\Rightarrow \langle E_{rel} \rangle_{GZ} = -E_0 \cdot (Z\alpha)^2 \left(\frac{3}{4} - \frac{1}{1/2} \right) = +\frac{5}{4} (Z\alpha)^2 E_0 = \frac{5}{4} Z^2 E_0$$

$$= \frac{5}{4} Z^2 \left(-\frac{1}{2} \frac{mc^2}{n^2} \right) = -\frac{5}{8} Z^4 (mc^2) < 0.$$

Aufgabe 5

a)

$$H_2 = -(\vec{\mu}_L + \vec{\mu}_S) \cdot \vec{B} = -\left(\frac{e}{2m} \vec{L} + g_e \frac{e}{2m} \vec{S} \right) \cdot \vec{B}$$

$$= -\frac{e}{2m} (\vec{L} + 2\vec{S}) \cdot \vec{B} \quad g_e \approx 2$$

$$= -\frac{eB}{2m} (L_z + 2S_z)$$

$$H = H_0 + H_2 ;$$

$$H_0 = E_{kin} + V_{Coul}(r)$$

$$\Rightarrow [H, \vec{L}^2] = [H, L_z] = [H, \vec{S}^2] = [H, S_z] = 0 \Rightarrow H \text{ diagonal in der Basis } |m, l, s\rangle$$

$$E = E_n + \Delta E ; \quad E_n = \frac{E_0}{n} ; E_0 = -\frac{mc^2}{2} (Z\alpha)^2 ;$$

$$\Delta E = -\frac{eB}{2m} (m_l + 2m_s) \hbar \quad \begin{cases} m_s = \pm 1/2 \\ m_l = -l, -(l-1), \dots, l \end{cases}$$

$$= -\frac{eB}{2m} (m_l + 1) \hbar$$

$\bullet m=1, l=0, m_l=0 ; m_s = \pm 1/2 \Rightarrow M = \begin{cases} +1 \\ -1 \end{cases}$ (magnet. Entartung)

$\bullet m=2, l=0 ; m_l=0 ; m_s = \pm 1/2 \Rightarrow M = \begin{cases} +1 \\ -1 \end{cases}$

$\bullet m=2, l=1 ; m_l=-1 ; m_s = \pm 1/2 \Rightarrow M = \begin{cases} 0 \\ -2 \end{cases}$

$m_l=0 ; m_s = \pm 1/2 \Rightarrow M = \begin{cases} +1 \\ -1 \end{cases}$

$m_l=1 ; m_s = \pm 1/2 \Rightarrow M = \begin{cases} 2 \\ 0 \end{cases}$

b) Auswahlregel f. elektrische Dipol. Übergänge:

$$\begin{cases} \Delta E = \pm 1 \\ \Delta m_l = \pm 1, 0 \end{cases} \quad \text{hier: } m_l \text{ möglich} \quad \begin{cases} \Delta E = \pm 1 ; \Delta m_s = \pm 1 ; 0 \\ \Delta m_s = 0 \end{cases}$$

	M	l	m_l	m_s
ZP	2	1	1	+1/2
	1	1,0	0	+1/2
	0	1	±1	±1/2
	-1	1,0	0	-1/2
	-2	1	-1	-1/2
-15	1	0	0	+1/2
	1	0	0	-1/2

Es gibt 3 verschobene Linien

$$(1) \omega^{(1)} = \frac{E_2 - E_1}{\hbar} = \frac{eB}{2m\hbar} \quad (3) \omega^{(3)} = \frac{E_2 - E_1}{\hbar} + \frac{eB}{2m\hbar} ; E_2 - E_1 = E_0$$

$$(2) \omega^{(2)} = \frac{E_2 - E_1}{\hbar}$$

$$(c) R = \frac{\Gamma_{b \rightarrow a}^{(1)}}{\Gamma_{b \rightarrow a}^{(3)}} = \left(\frac{\omega^{(1)}}{\omega^{(3)}} \right)^3 \frac{|\langle b | \vec{r} | a \rangle^{(1)}|^2}{|\langle b | \vec{r} | a \rangle^{(3)}|^2}$$

$$|\langle b | \vec{r} | a \rangle^{(1)}| = |\langle 1, 0, 0 | \vec{r} | 2, 1, \pm 1 \rangle| \quad \text{Spin variable nicht relevant für } \langle \vec{r} \rangle$$

$$|\langle b | \vec{r} | a \rangle^{(3)}| = |\langle 1, 0, 0 | \vec{r} | 2, 1, \pm 1 \rangle|$$

$$\Rightarrow |\langle b | \vec{r} | a \rangle^{(1)}| = |\langle b | \vec{r} | a \rangle^{(3)}| \quad |\langle b | \vec{r} | a \rangle| \text{ unabh. von } m_e$$

- oder aus azimutaler Sym.

- oder aus Wigner-Eckart-Th.

$$\vec{r} \sim Y_m^{(1)} \Rightarrow \langle 1, 0, 0 | Y_m^{(1)} | 2, 1, \pm 1 \rangle =$$

$$= \underbrace{\langle 1 \pm 1, 1 | 100 \rangle}_{\text{Clebsch-Gordan}} \cdot \underbrace{\langle 211 | Y^{(1)} | 10 \rangle}_{\text{red. Matrix. Element}}$$

$$\Rightarrow \mu = \pm 1$$

$$\Rightarrow R = \left(\frac{\omega^{(1)}}{\omega^{(3)}} \right)^3 = \left(\frac{\frac{3/4|E_0| + |eB\hbar|}{2m\hbar}}{\frac{3/4|E_0| - |eB\hbar|}{2m\hbar}} \right)^3 = \left(\frac{3/8|E_0|/2 + |e|B\hbar/m}{3/8|E_0|/2 - |e|B\hbar/m} \right)^3$$

Aufgabe 4. Sudauer Approximation

• Ursprungsbewegung stationäre Zust. von H_0 :

$$|m^{(0)}\rangle \langle t| = e^{-i\bar{E}_m^{(0)}t/\hbar} |m^{(0)}\rangle$$

• Stationäre Zust. von $H_0 + V$:

$$|\bar{m}, t\rangle = e^{-i\bar{E}_m t/\hbar} |\bar{m}\rangle$$

$$t \leq 0 \quad |\Psi, t\rangle = \phi_0(x) e^{-iE_0^{(0)}t/\hbar} ; E_0^{(0)} = \frac{\hbar\omega}{2}$$

$t \geq 0, |\bar{\Psi}, 0\rangle = |\Psi, 0\rangle$ ungestörtes noch durch Störpotential beeinflusst sich das Syst. in der

$$t > 0: V(x) = \frac{m\omega^2 x^2}{2} - qEx = \frac{m\omega^2}{2} \left(x^2 - \frac{2Eq}{m\omega^2} x + \frac{E^2 q^2}{m^2 \omega^4} \right) - \frac{2Eq}{m\omega^2}$$

$$= \frac{m\omega^2}{2} (x - x_0)^2 + V_0 \quad \text{mit } x_0 = \frac{2(Eq)}{m\omega^2} ; V_0 = -\frac{2Eq^2}{m\omega^2}$$

$$H(x) = \frac{p^2}{2m} + \frac{m\omega^2}{2} (x - x_0)^2 + V_0 =$$

$$= -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + \frac{m\omega^2}{2} (x - x_0)^2 + V_0$$

$$H(y) = -\frac{\hbar^2}{2m} \frac{d^2}{dy^2} + \frac{m\omega^2}{2} y^2 + V_0$$

$$\text{Gesucht } H(y) \bar{\Psi}(y) = \bar{E} \bar{\Psi}(y)$$

$$\Rightarrow \bar{\Psi}(y) = \phi_m(y) ; \bar{E}_m = V_0 + E_m = V_0 + \hbar\omega$$

$$\Rightarrow \bar{\Psi}_m(x) = \phi_m(x - x_0) = \phi_0 + \frac{1}{\sqrt{\sigma_0}} \left(\frac{x - x_0}{\sigma_0} \right) e^{-\frac{(x - x_0)^2}{2\sigma_0^2}} \quad \phi_0 = \left(\frac{m\omega}{\pi\hbar} \right)^{1/4}$$

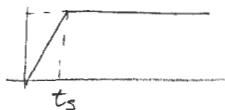
$$\left\{ \bar{\Psi}(x, t) = \sum_n c_n(t) \bar{\Psi}_n(x) \quad \text{mit } \right\} \Rightarrow$$

$$\bar{\Psi}(x, t=0) = \phi_0(x) \quad (t=0)$$

$$c_n(0) = \langle \phi_0(x) | \phi_n(x - x_0) \rangle = \int_{-\infty}^{+\infty} dx \phi_n(x - x_0) \phi_0^*(x) =$$

$$= \sigma_0^{-1} (\pi 2^m m!)^{-1/2} \int_{-\infty}^{+\infty} dx \exp\left(-\frac{1}{2} \left(\frac{x}{\sigma_0}\right)^2 - \frac{1}{2} \left(\frac{x - x_0}{\sigma_0}\right)^2\right) H_m\left(\frac{x - x_0}{\sigma_0}\right) dx$$

$$\xi = (x - x_0)/\sigma_0 \Rightarrow$$



$t_0 < t < t_1$ - dann ist Unstetigkeit

$$\begin{aligned}
 \psi_n(0) &= \frac{1}{\sqrt{2^m m!}} \int_{-\infty}^{+\infty} d\zeta H_m(\zeta) \exp\left[-(\zeta^2 + \frac{1}{2}(\chi_0/p_0)^2 + \zeta(-\chi_0/p_0))\right] \\
 &= \frac{(-1)^m \left(\frac{\chi_0}{p_0}\right)^m \exp\left(-\frac{1}{2} \frac{\chi_0^2}{p_0^2}\right)}{\sqrt{2^m m!}} ; \quad \psi_n(t) = \psi_n(0) e^{-i E_m t / \hbar}
 \end{aligned}$$

$$P_{n_0 \rightarrow \bar{n}} = |\langle \bar{n} | \psi, 0 \rangle|^2 = |\psi|^2 = |\psi_n(0)|^2 = \frac{\left(\frac{\chi_0}{p_0}\right)^{2n} \exp\left(-\frac{\chi_0^2}{2 p_0^2}\right)}{2^m m!}$$

↳ Poisson distribution